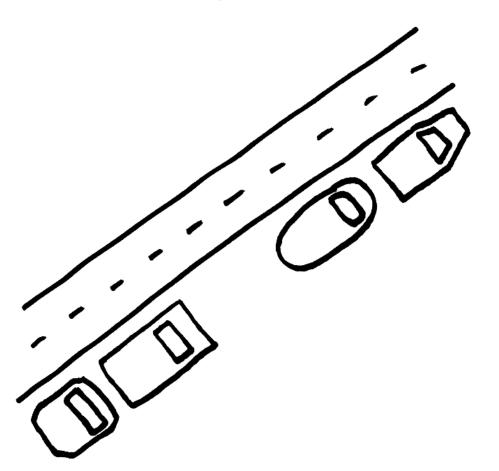
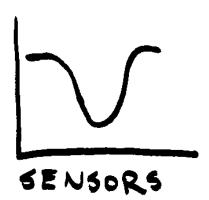
Self Parallel-Parking Car

Illustrated and Presented by Kevin Hsiue and Frank Ni

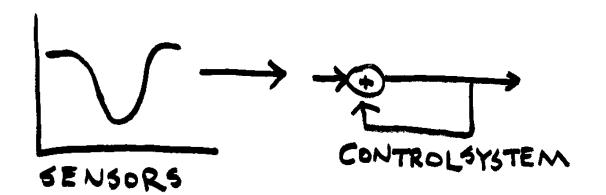
The big idea: Parallel parking is usually a pain.



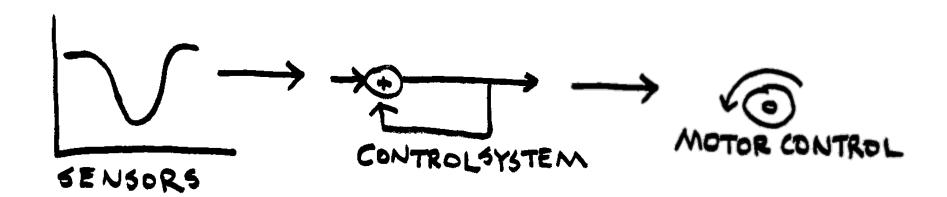
Relevant ideas: Why this is educationally interesting.



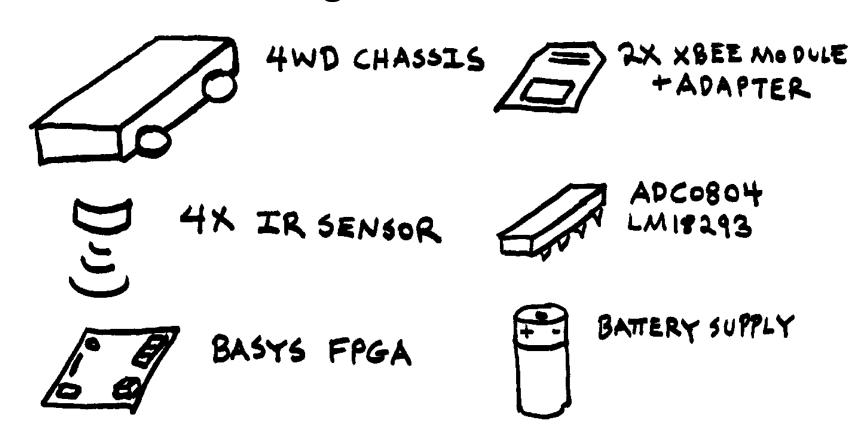
Relevant ideas: Why this is educationally interesting.



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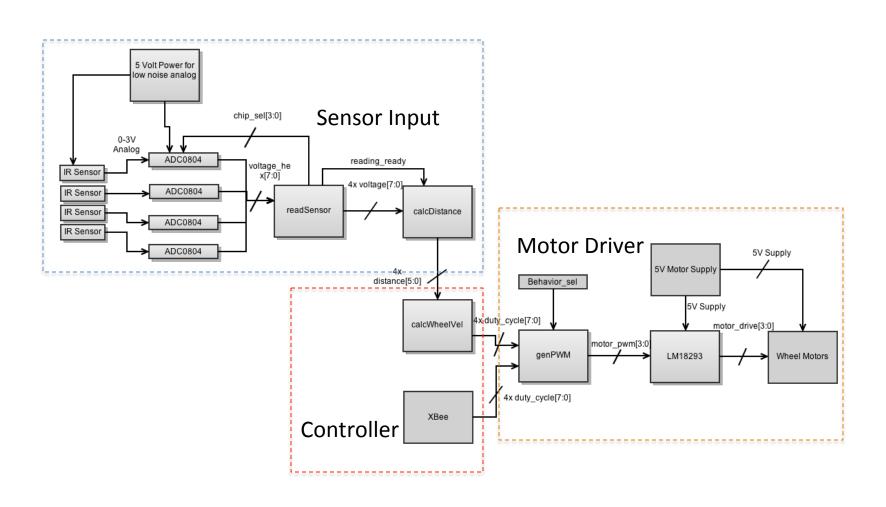


Required materials: Building a suitable model.



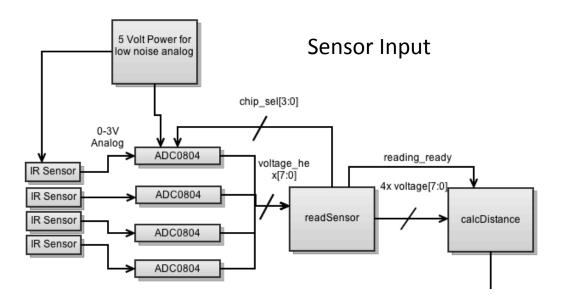
Block diagram:

Abstracting the challenge into smaller pieces.



Block diagram:

Abstracting the challenge into smaller pieces.



- Mount four sensors in optimal positions
- Use ADC to convert voltage to eight byte hex value
- readSensor module cycles through the 4 ADC
- lets calcDistance know when it is ready
- calcDistance converts the voltages into a distance value



Block diagram: Abstracting the challenge into smaller pieces.

- genPWM module uses duty cycle input to create PWM
- PWM is fed to LM18293 to control vehicle
- Separate supply to isolate noise

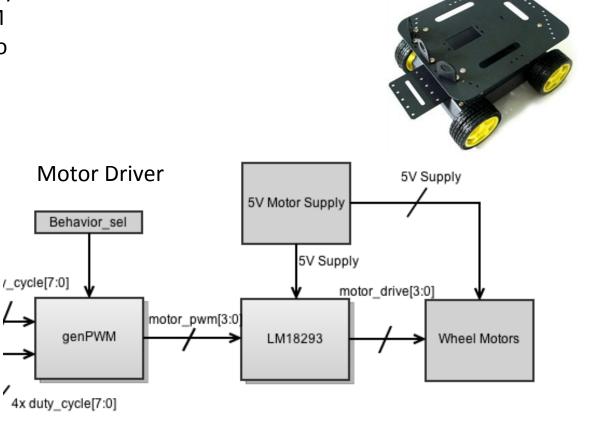
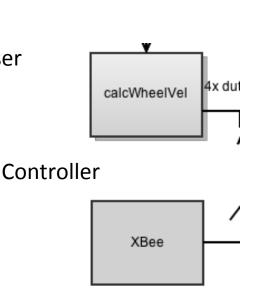
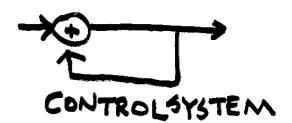


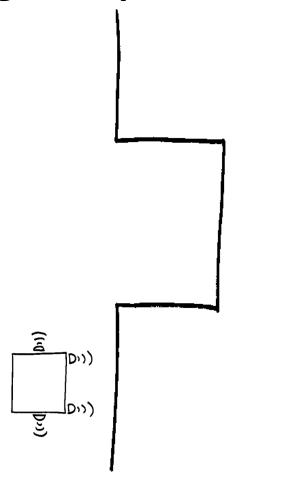
Image courtesy of SparkFun.com

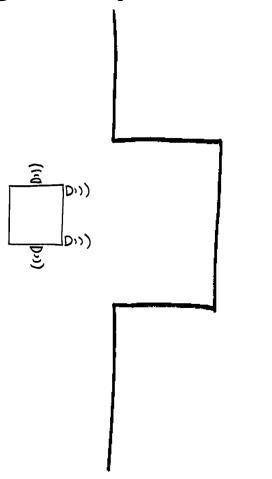
Block diagram: Abstracting the challenge into smaller pieces.

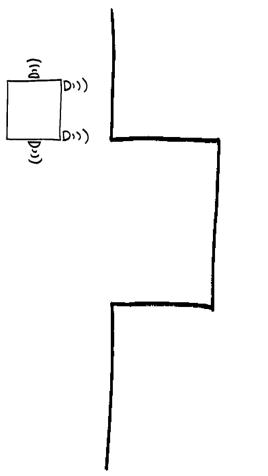
- calcWheelVel is a feedback controller implemented via FSM
- Use XBee to control the vehicle wirelessly
- Behavior is selected by user

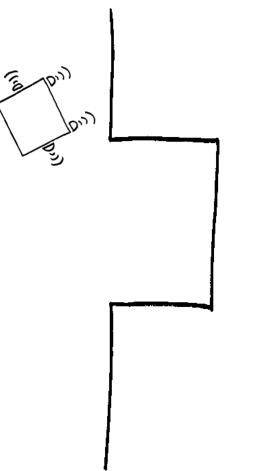


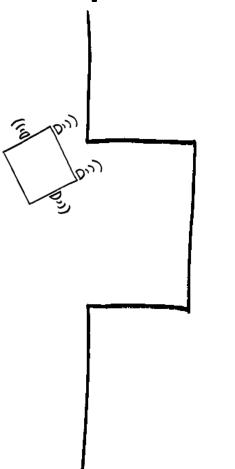


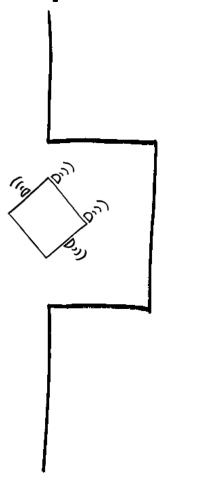


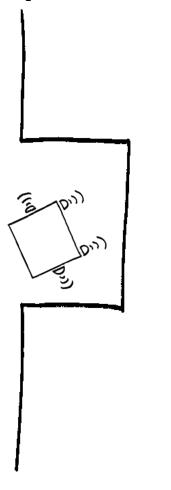


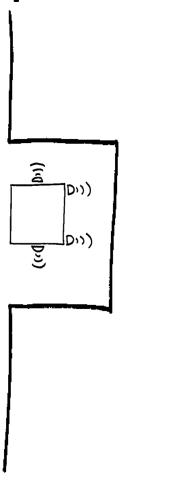












Timeline

Week Of	Frank Ni	Kevin Hsiue
Nov. 12	Interfacing Sensors	Interfacing motors
Nov. 19	Sensor Modules	Motor Modules
Nov. 26	Feedback controller	Xbee Controller
Dec. 3	System Integration and Testing	
Dec. 10	Check off	