

FPGA videogame

6.111 final project report

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Introduction

The aim of this project was to develop a gaming system on the FPGA easily reconfigurable; by switching small component parts on the system, it could be used to play another game. Two apparently opposing goals were set: to avoid hardwiring game logic into the hardware, and to use the massive parallel processing power available on the labkit to speed up the game, making this project have an interesting digital design aspect. The compromise was achieved by designing the game logic itself to be controlled by a microprocessor, but letting the graphics processing being controlled by hardware, in the form of a somewhat primitive graphics processing unit.

Diverse factors, such as availability, familiarity and available technical support, the microprocessor architecture chosen was the Beta, a processor used for an introductory computational structures class at MIT, 6.004. The GPU design is very ad hoc; nevertheless, it is inspired by and shares various similarities with early-eras of videogame systems, such as the use of sprites, of hardware modules dedicated to individual images, the hierarchical collision detection on a pixel-by-pixel level, image layering, mirroring, and color filters. A more unusual characteristic of this GPU is to assume the responsibility for image loading; the design guideline was that the processor should not waste cycles doing a graphics-related task, but instead give a (somewhat) higher level instruction to the GPU.

Project Design

Design tools

All hardware used for this project was supplied by the course staff: the labkit FPGA, logic analyzers, and LCD monitors for output. Various softwares were employed: the Xilinx development suit for the Verilog code, some Java for converting images into text format parsable by memory creators, the BSim beta simulator provided by 6.004, and a Python script to speed up the creation of small memory modules, provided by the professor.

The verilog code for the processor module was provided by the course staff. The 2-stage pipelined Beta was used almost on unaltered form, except for the duplication and exposure of 5 registers, addition and externalization of a new control signal, and a corresponding opcode for hardware calls. This difference was enough, however, to make the BSim simulations slightly less useful, since a macro would have to be redefined either for producing a new RAM with the game logic either for software simulation, and forgetting this detail would cause a whole synthesis process to be wasted (around 30 minutes on late design stage). The hardware call macro, HW(), would have its definition altered for producing the .coe files for the labkit and for the software simulation.

Software simulations for verilog and tests of individual modules would probably have been very useful; as of two days before the demo date, some of the GPU modules still had hard-to-track bugs, and the hardware synthesis of those particular modules is the largest time sink of the development, and their absence might be one of the factors of the project not being as polished as originally envisioned (together with an inappropriate schedule).

Design overview

All game logic is controlled by the processor, who receives information through interrupts, related to in-screen sprite collision, user input and built-in clock interrupt. Graphics commands are sent to the graphics processing unit, who produces a pixel per cycle, which is combined with the VGA signal and sent to the labkit video components, and forwarded to the monitor.

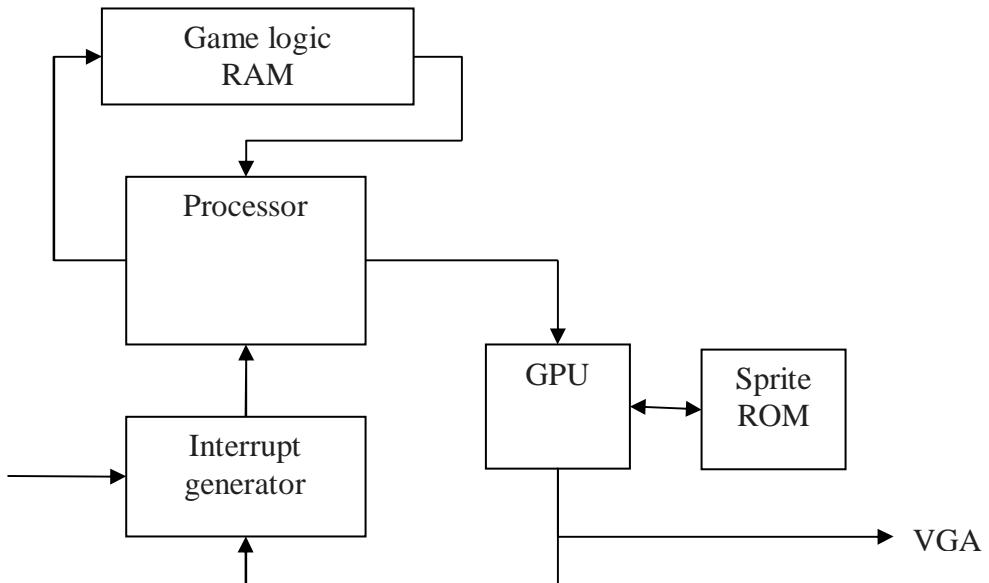


Fig. 1: System block diagram

Output

Most videogame systems have the video display as its primary output. This system uses a VGA signal to communicate with the display. VGA was chosen as opposed to a higher-resolution due to its clocking speed; even after extensive pipelining, the circuit logic maximum speed, as estimated by Xilinx, tends to be around 50 MHz. The IBM standard for a 640x480 VGA display, also available on the course website, ask for a convenient clock speed of 31.5MHz, which is fast enough to drive a 75Hz screen frequency and slow enough for the combinatorial logic without a more detailed (and complex, and time-consuming to implement) pipeline.

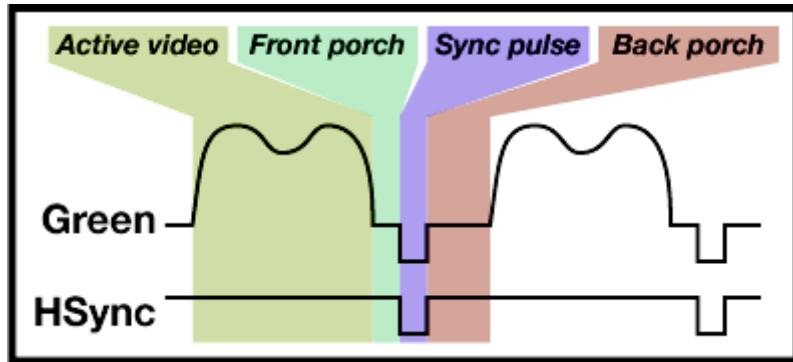


Fig. 2: VGA horizontal sync (source: 6.111 website, labkit documentation)

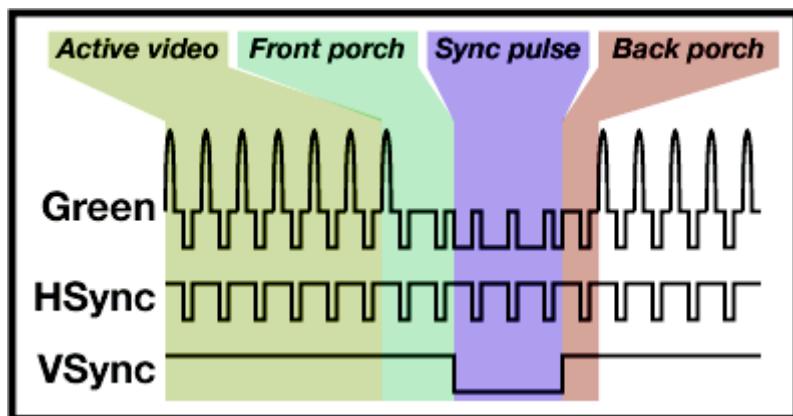


Fig. 3: VGA vertical sync (source: 6.111 website, labkit documentation)

Format	Frame frequency (Hz)	Pixel Clock (MHz)	Horizontal (in pixels)				Vertical(in lines)			
			Active video	Front porch	Sync pulse	Back porch	Active video	Front porch	Sync pulse	Back porch
640x480	60	25.175	640	16	96	48	480	11	2	31
640x480	72	31.500	640	24	40	128	480	9	3	28
640x480	75	31.500	640	16	96	48	480	11	2	32
640x480	85	36.000	640	32	48	112	480	1	3	25
800x600	56	38.100	800	32	128	128	600	1	4	14
800x600	60	40.000	800	40	128	88	600	1	4	23
800x600	72	50.000	800	56	120	64	600	37	6	23
800x600	75	49.500	800	16	80	160	600	1	2	21
800x600	85	56.200	800	32	64	152	600	1	3	27
1024x768	60	65.000	1024	24	136	160	768	3	6	29
1024x768	70	75.000	1024	24	136	144	768	3	6	29
1024x768	75	78.500	1024	16	96	176	768	1	3	28
1024x768	85	94.500	1024	48	96	208	768	1	3	36

Table 1: VGA timings (source: 6.111 website, labkit documentation)

After the project was completed, it is visible that some resolutions at 800x600 could also be supported; however, to err on the side of caution, the system, as well as the memory sizes for the sprites, were projected with a 600x480 resolution in sight.

Pixel colors are represented within the digital logic as a 8-bit value, with 3 bits of red, 2 bits of green and 3 bits of blue. Some small ROMs then convert these bits back into 8-bits for each color, to send to the video output on the labkit.

The module for generating the VGA sync signals and combining it with pixels was taken from this class, from laboratory number 5.

GPU communication

The GPU needs two-way communication, since it both receives graphics-related instructions and returns sprite-collision information. Processors in general send messages to hardware as if communicating with a memory, and receive "hardware events" through interrupt requests. A simpler approach was used on the CPU-to-hardware communication: a new opcode (0b00001) was reserved to, effectively, cause the processor to stall for a cycle, as a NOP, and to set a control signal as 1 during that cycle. At the same time, three registers (R1, R2 and R3) were duplicated and had their values exposed. Whenever the control signal is asserted, the GPU can respond properly to the values contained in those registers. In this aspect, the communication with the hardware is more similar to the method-call paradigm for the Beta architecture, though distinct macros are used for methods and hardware calls for clarity (and sanity) reasons.

User input and other hardware can affect a processor operation by establishing interrupt signals; on the Beta architecture, it causes the supervisor bit to be set, and the instruction to jump to an externally provided value. This is a good communication protocol if the number of possible values the hardware needs to provide to the Beta is fairly limited: a jump instruction is put at the appropriate location on the kernel, and from there software only is responsible for responding as necessary. This method is much less effective, however, if there is a reasonably large input to be provided for the processor: for example, the GPU can provide a 32-bit word as flags for sprite collision, and it is unreasonable (and out of available physical resources) to dedicate 2^{32} kernel addresses to jump instructions, much less to handle each one of these.

As a work around this problem, this project lets the GPU (and, in theory, any other optional hardware devices that were not developed) write to specific locations of the main memory. Since the hardware will always be writing to the same addresses, and not reading the memory, a fairly easy implementation that does not require adding ports to the memory consists of a memory wrapper module that "shadows" those specific memory addresses with external registers. Whenever an address is read or written to, the correct info is muxed from (or to) either the main memory or those registers, depending on the address. Some

additional logic gives writing access to the registers to hardware simultaneous to the Beta writing to the main memory, letting the hardware have priority in case of conflict.

GPU submodules

The GPU is composed by various submodules, as indicated on the block diagram:

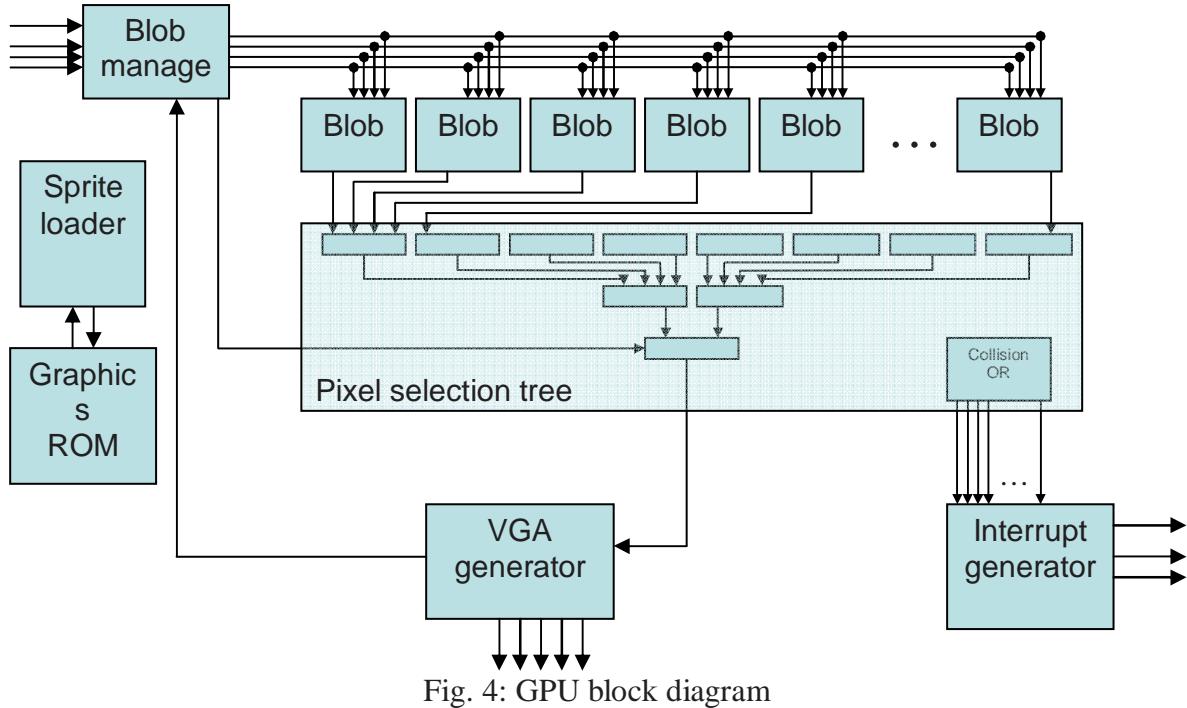


Fig. 4: GPU block diagram

- Blob manager, responsible for receiving information from the CPU;
- 32 blobs, hardware modules dedicated to producing the output from one sprite instantiated by code;
- Sprite manager, a module responsible for reading the graphics ROM and loading its contents into the blobs;
- Pixel selection tree, a fanning tree to select which blob output, if any, is responsible for driving the current pixel being displayed, and generating collision information based on the specific pixel;
- Interrupt generator, responsible for creating (and queueing) interrupt requests for the CPU, and writing to two specific main memory addresses;
- Coordinate generator, responsible for generating pixel address requests to the rest of the GPU.

The blob manager controls the behavior of most of the GPU components, being the responsible for interpreting the CPU commands. Whenever the control signal is asserted, it behaves on that specific clock cycle as appropriate, changing its internal registers, sending

commands to a bus connected to all blobs, and background pixel color information for the pixel selection tree.

Each blob has an assigned OWNER parameter that distinguishes it from the others; it compares one of the blob manager bus wires, id_bus, to determine if it should react to the blob manager. All instructions that determine a blob behavior are given to it by the blob manager. Each blob has a small local memory with the sprite it is currently responsible for, if any; whenever commands are issued that would require loading a new sprite, the blob sends a request for the sprite manager, with the code of the sprite type it requires.

Whenever the sprite manager responds, the request bit is turned off. A new request may be issued while the sprite manager is busy loading a sprite on this very same blob. For implementation convenience, and due to the small number of operations required to store a sprite (exactly as many as to display one frame of the sprite), the sprite manager will ignore the new request while busy. Each blob outputs the pixel it would produce, along with extra pixel information (owner, whether the sprite is collidable, whether the sprite represents an enemy, whether the pixel is should be considered transparent, sprite layer).

Each blob also has built-in capacity for some minor image effects, such as mirroring the sprite it contains, by reading its memory in another order, or applying a color filter to each pixel, by applying an operation to the pixel bits before outputting them. A blob is a small 4-state machine, with respect to how it responds to a pixel request. In order to support the tiling effect, instead of evaluating a remainder operation on every cycle, it uses the fact that most often the pixels are requested in sequential order, by keeping an internal counter and resetting it at the appropriate times, similarly to an odometer technique (refer to the module for more details).

S_NONE	Always outputs transparent pixels
S_SPRITE	Outputs transparent pixels if coordinates are outside sprite, or sprite pixel otherwise, with corresponding sprite information (layer and collision/enemy bits)
S_PLATFORM	Outputs always transparent pixels, but outputs collision bits as set (and, if set, also enemy bits) inside a defined rectangular region.
S_TILED_SPRITE	Tiles a rectangular region with copies of the selected sprite.

Table 2: Blob states

The sprite manager is responsible for serving sprites for the blobs. It always gives priority for the blobs with lowest ID, when not busy; while busy, it ignores the requests. It sends the loaded sprite pixel information down a bus, and a write signal only to the blob that is being currently served, if any. The sprite device is the only hardware component with access to the graphics ROM, making it a one-port rom and greatly saving on labkit resources, as opposed to 32 parallel accesses.

The pixel selection tree is made mostly of smaller submodules, named pixel combinator. The pixel combinator takes four inputs of the form produced by a blob, and output a series of signal of the same form (pixel color, pixel owner, layer, etc.), along with collision information for each one of its inputs (whether it is collidable and is colliding with something collidable on the current pixel, whether it is collidable and is colliding with something collidable and enemy on the current pixel). A tree of 7 pixel combinator, in 3 layers, along with extra logic to collect collision information, form the pixel selection tree. At the last layer, some additional logic determines whether to display the background pixel instead of the selected pixel. The pixel selection tree has the most logic on the GPU; as such, it is pipelined after each pixel combinator layer.

The interrupt generator, while might or might not be considered as a proper part of the GPU, receives the collision information from the pixel selection tree, monitors it for changes over one screen sweep, and when it happens it sends an interrupt to the CPU, writing the new collision information on the proper place in the wrapper main memory. For implementation convenience, it also generates the interrupt requests for the other interrupt events (labkit button presses and releases, and a low-frequency clock).

The coordinate generator sends x, y coordinates in advance to the blob manager, to be processed by the GPU logic described above (the blob manager adds the screen coordinates, sends it to the blobs, the blobs produce the pixel, which is filtered down the pixel selection tree, muxed with the background color, and sent to the display). It sends coordinates in advance to the current hcount, vcount vga information to count for the pipeline delay.

Hardware protocols

CPU to GPU

The following commands may be issued to the blob manager, by interpreting the contents of the registers R1, R2, R3, R4 and R5 when the ctl signal is issued:

M_NEW_SPRITE

OPCODE: 0b00000

R1	0b00000	?<6>	E	C	L<2>	?	ID<5>	TYPE<10>
R2	X1 <32>							
R3	Y1 <32>							
R4	?<32>							
R5	?<32>							

Instanciates a new sprite of type TYPE on blob ID, with layer L, enemy bit E, collision bit C, with top left corner at X1, Y1.

M_NEW_BLOB

OPCODE: 0b00001

R1	0b00001	? <6>	E	?	L <2>	?	ID <5>	? <10>
R2	X1 <32>							
R3	Y1 <32>							
R4	X2 <32>							
R5	Y2 <32>							

Instanciates a new invisible, collidable platform on blob ID, with layer L, enemy bit E, collidable, at position X1, Y1 as the top left corner and X2, Y2 as the down right corner.

M_NEW_TILED_SPRITE

OPCODE: 0b00010

R1	0b00010	? <6>	E	C	L <2>	?	ID <5>	TYPE <10>
R2	X1 <32>							
R3	Y1 <32>							
R4	X2 <32>							
R5	Y2 <32>							

Instanciates a new tiled sprite of type TYPE on blob ID, with layer L, collidable bit C, enemy bit E, at position X1, Y1. The sprite will repeat itself side by side, down to position X2, Y2.

M_DESTROY_SPRITE

OPCODE: 0b00011

R1	0b00011	? <11>			ID <5>	? <10>
R2	? <32>					
R3	? <32>					
R4	? <32>					
R5	? <32>					

Frees the blob ID of its sprite.

M_MOVE_SPRITE

OPCODE 0b00100

R1	0b00010	? <11>		ID <5>	? <10>
R2	X1 <32>				
R3	Y1 <32>				
R4	X2 <32>				
R5	Y2 <32>				

Sets the coordinates X1, Y1 of the blob ID. Also sets coordinates X2, Y2 if applicable.

M_SET_LAYER_CLIP_ENEMY

OPCODE: 0b00101

R1	0b00101	? <6>	E	C	L <2>	?	ID <5>	? <10>
R2	? <32>							
R3	? <32>							
R4	? <32>							
R5	? <32>							

Sets the layer, collidable bit and enemy bit attributes of the blob ID.

M_SET_FILTER

OPCODE: 0b00110

R1	0b00110	? <11>	ID<5>	? <5>	FILTER <5>
R2	? <32>				
R3	? <32>				
R4	? <32>				
R5	? <32>				

Sets the filter as FILTER for the blob ID:

Code	Parameter name	Description
0b00000	F_NONE	Regular output
0b00001	F_RED	Only red component
0b00010	F_GREEN	Only green component
0b00011	F_BLUE	Only blue component
0b00100	F_YELLOW	Only red and green components
0b00101	F_PURPLE	Only red and blue components
0b00110	F_CYAN	Only green and blue components
0b00111	F_INVERT	The complement of each color
0b01000	F_BLACK	All opaque pixels become black
0b01001	F_WHITE	All opaque pixels become white

Table 3: Blob pixel filters

M_SET_MIRROR

OPCODE: 0b00111

R1	0b00111	? <11>	ID<5>	? <8>	M<2>
R2	? <32>				
R3	? <32>				
R4	? <32>				
R5	? <32>				

Sets the mirror attribute for blob ID as M (the last bit specifies whether to invert x, the larger bit specifies whether to invert y).

M_SET_CAMERA

OPCODE: 0b01000

R1	0b01000	? <26>	
R2	X <32>		
R3	Y <32>		
R4	? <32>		
R5	? <32>		

Set coordinates X, Y for the camera.

M_SET_BACKGROUND_PIXEL

OPCODE: 0b01001

R1	0b01001	? <18>	PIXEL<8>
R2	? <32>		
R3	? <32>		
R4	? <32>		
R5	? <32>		

Sets the background color pixel. A pixel is represented in the rgb format, with 3 bits of red, 2 of green, and 3 of blue (RRRGGBBB)

M_SET_TYPE

OPCODE: 0b01010

R1	0b01010	? <11>	ID<5>	TYPE<10>
R2	? <32>			
R3	? <32>			
R4	? <32>			
R5	? <32>			

Changes the type of the sprite at blob ID to TYPE.

Blob manager to blob

The following commands can be issued by the blob manager to individual blobs, through the command_bus wire, accompanied of the appropriate blob ID on id_bus, as well as relevant information for each command on the other buses:

Code	Parameter name	Other buses considered
0x0	C_NOP	<i>no other parameters</i>
0x1	C_SET_POSITION	x1_bus, y1_bus, x2_bus, y2_bus
0x2	C_SET_TYPE	type_bus
0x3	C_SET_LAYER_CLIP_AND_ENEMY	layer_bus, collidable_bus, enemy_bus
0x4	C_SET_MIRROR	mirror_bus
0x5	C_CLEAN	<i>no other parameters</i>
0x6	C_CREATE_BLOB	x1_bus, y1_bus, x2_bus, y2_bus, enemy_bus
0x7	C_CREATE_SPRITE	x1_bus, y1_bus, type_bus, collidable_bus, enemy_bus
0x8	C_CREATE_TILED_SPRITE	x1_bus, y1_bus, x2_bus, y2_bus, type_bus, layer_bus, collidable_bus, enemy_bus,
0x9	C_SET_FILTER	filter_bus

Table 4: command_bus protocol

Feedback

Developing an entire programmable game system is a huge project, even more so for a one person group. Doing the bulk of the work during the last week and not being able to sleep at all on the last days approaching the deadline is definitively something to be avoided, even though in the future I will look back to this project with fondness. This project touched on computer-related engineering practices on diverse levels; producing a sprite controlled via assembly code and general-purpose hardware was very satisfying.

TAs told me that not many projects use the Beta, due to its complexity. While it has a reasonably large set of instructions, it is most likely one a prospective student would already be familiar with, from 6.004, and a deep understanding of its control signals, as well as the 6.004 kernel, is required for an adequate debug of the project (for instance, to recognize that, on a previous attempt, the hardware control signal and the SVC calls had namespace conflicts.) A simulator for the Beta itself is very convenient, to reduce the amount of synthesis and save much time during debugging. A better though approach for interfacing with the beta would also have made things easier – some too-late research revealed me that the standard approach for interfacing a processor with hardware is to mux out the memory ports, so that the interfacing may be done entirely with load and store commands (besides interruptions). I strongly recommend doing that in any project using a Beta.

Insufficient documentation of the sample kernel code in the 6.004 course locker proved to be a minor annoyance at a late development stage. Different versions of the kernel, with or without accompanying code, can be found distributed in course-related materials. An older version uses big-endian opcodes to make system calls to the kernel, while a more recent one would use little-endian opcodes. Originally incompatible namespaces for the software system calls and the hardware call would lead the system to unexpected behavior, hard to track without comparing a line-by-line simulation and the logic analyzer output.

Early testing of components and/or simulations would have been greatly helpful. Few things are more frustrating than spending 30 minutes synthesizing all the hardware to determine that a wrong signal is being produced because of a missing case on a case statement, or a typo. Due to its own nature as a processor, it is hard to understand what is happening at any given moment without outputting various control signals to the logic analyzer.

While this project did not get implemented as far as originally planned, nevertheless it worked at a very basic level – a proof of concept level, if you will – and with additional time, it wouldn't be hard to actually create a game based on this, or add additional output hardware, such as audio, interfacing with the CPU on the same way that the GPU does.

References

6.111 website, Fall '07. Lecture slides, labkit documentation, and VGA specification.
<http://web.mit.edu/6.111/www/f2007/index.html> Retrieved in 12.12.2007

6.004 website, Fall '07. BSim program and documentation, 2-stage pipelined Beta documentation. <http://6004.lcs.mit.edu/currentsemester/courseware/> Retrieved in 12.12.2007

Appendix A: Verilog files

final-project.v

Contains the top-level module file for the project, a wrapper for the main RAM that allows it to behave as if hardware could write to specific addresses, and tables to convert from 2-bit and 3-bit to 8-bit color information.

```
//////////  
//  
// 6.111 FPGA Labkit -- Template Toplevel Module  
//  
// For Labkit Revision 004  
//  
//  
// Created: October 31, 2004, from revision 003 file  
// Author: Nathan Ickes  
//  
//////////  
//  
// CHANGES FOR BOARD REVISION 004  
//  
// 1) Added signals for logic analyzer pods 2-4.  
// 2) Expanded "tv_in_ycrcb" to 20 bits.  
// 3) Renamed "tv_out_data" to "tv_out_i2c_data" and "tv_out_sclk" to  
//    "tv_out_i2c_clock".  
// 4) Reversed disp_data_in and disp_data_out signals, so that "out" is an  
//    output of the FPGA, and "in" is an input.  
//  
// CHANGES FOR BOARD REVISION 003  
//  
// 1) Combined flash chip enables into a single signal, flash_ce_b.  
//  
// CHANGES FOR BOARD REVISION 002  
//  
// 1) Added SRAM clock feedback path input and output  
// 2) Renamed "mousedata" to "mouse_data"  
// 3) Renamed some ZBT memory signals. Parity bits are now incorporated into  
//    the data bus, and the byte write enables have been combined into the  
//    4-bit ram#_bwe_b bus.  
// 4) Removed the "systemace_clock" net, since the SystemACE clock is now  
//    hardwired on the PCB to the oscillator.  
//  
//////////  
//  
// Complete change history (including bug fixes)  
//  
// 2005-Sep-09: Added missing default assignments to "ac97_sdata_out",  
//              "disp_data_out", "analyzer[2-3]_clock" and  
//              "analyzer[2-3]_data".  
//  
// 2005-Jan-23: Reduced flash address bus to 24 bits, to match 128Mb devices  
//              actually populated on the boards. (The boards support up to  
//              256Mb devices, with 25 address lines.)  
//  
// 2004-Oct-31: Adapted to new revision 004 board.  
//  
// 2004-May-01: Changed "disp_data_in" to be an output, and gave it a default  
//              value. (Previous versions of this file declared this port to  
//              be an input.)
```

```

//  

// 2004-Apr-29: Reduced SRAM address busses to 19 bits, to match 18Mb devices  

//               actually populated on the boards. (The boards support up to  

//               72Mb devices, with 21 address lines.)  

//  

// 2004-Apr-29: Change history started  

//  

///////////////////////////////  

module final_project (beep, audio_reset_b, ac97_sdata_out, ac97_sdata_in,  

ac97_synch,  

    ac97_bit_clock,  

    vga_out_red, vga_out_green, vga_out_blue, vga_out_sync_b,  

    vga_out_blank_b, vga_out_pixel_clock, vga_out_hsync,  

    vga_out_vsync,  

    tv_out_ycrcb, tv_out_reset_b, tv_out_clock, tv_out_i2c_clock,  

    tv_out_i2c_data, tv_out_pal_ntsc, tv_out_hsync_b,  

    tv_out_vsync_b, tv_out_blank_b, tv_out_subcar_reset,  

    tv_in_ycrcb, tv_in_data_valid, tv_in_line_clock1,  

    tv_in_line_clock2, tv_in_aef, tv_in_hff, tv_in_aff,  

    tv_in_i2c_clock, tv_in_i2c_data, tv_in_fifo_read,  

    tv_in_fifo_clock, tv_in_iso, tv_in_reset_b, tv_in_clock,  

    ram0_data, ram0_address, ram0_adv_ld, ram0_clk, ram0_cen_b,  

    ram0_ce_b, ram0_oe_b, ram0_we_b, ram0_bwe_b,  

    ram1_data, ram1_address, ram1_adv_ld, ram1_clk, ram1_cen_b,  

    ram1_ce_b, ram1_oe_b, ram1_we_b, ram1_bwe_b,  

    clock_feedback_out, clock_feedback_in,  

    flash_data, flash_address, flash_ce_b, flash_oe_b, flash_we_b,  

    flash_reset_b, flash_sts, flash_byte_b,  

    rs232_txd, rs232_rxd, rs232_rts, rs232_cts,  

    mouse_clock, mouse_data, keyboard_clock, keyboard_data,  

    clock_27mhz, clock1, clock2,  

    disp_blank, disp_data_out, disp_clock, disp_rs, disp_ce_b,  

    disp_reset_b, disp_data_in,  

    button0, button1, button2, button3, button_enter, button_right,  

    button_left, button_down, button_up,  

    switch,  

    led,  

    user1, user2, user3, user4,  

    daughtercard,  

    systemace_data, systemace_address, systemace_ce_b,  

    systemace_we_b, systemace_oe_b, systemace_irq, systemace_mpbrdy,  

    analyzer1_data, analyzer1_clock,  

    analyzer2_data, analyzer2_clock,  

    analyzer3_data, analyzer3_clock,

```

```

        analyzer4_data, analyzer4_clock);

output beep, audio_reset_b, ac97_synch, ac97_sdata_out;
input ac97_bit_clock, ac97_sdata_in;

output [7:0] vga_out_red, vga_out_green, vga_out_blue;
output vga_out_sync_b, vga_out_blank_b, vga_out_pixel_clock,
      vga_out_hsync, vga_out_vsync;

output [9:0] tv_out_ycrcb;
output tv_out_reset_b, tv_out_clock, tv_out_i2c_clock, tv_out_i2c_data,
      tv_out_pal_ntsc, tv_out_hsync_b, tv_out_vsync_b, tv_out_blank_b,
      tv_out_subcar_reset;

input [19:0] tv_in_ycrcb;
input tv_in_data_valid, tv_in_line_clock1, tv_in_line_clock2, tv_in_aef,
      tv_in_hff, tv_in_aff;
output tv_in_i2c_clock, tv_in_fifo_read, tv_in_fifo_clock, tv_in_iso,
      tv_in_reset_b, tv_in_clock;
inout tv_in_i2c_data;

inout [35:0] ram0_data;
output [18:0] ram0_address;
output ram0_adv_ld, ram0_clk, ram0_cen_b, ram0_ce_b, ram0_oe_b, ram0_we_b;
output [3:0] ram0_bwe_b;

inout [35:0] ram1_data;
output [18:0] ram1_address;
output ram1_adv_ld, ram1_clk, ram1_cen_b, ram1_ce_b, ram1_oe_b, ram1_we_b;
output [3:0] ram1_bwe_b;

input clock_feedback_in;
output clock_feedback_out;

inout [15:0] flash_data;
output [23:0] flash_address;
output flash_ce_b, flash_oe_b, flash_we_b, flash_reset_b, flash_byte_b;
input flash_sts;

output rs232_txd, rs232_rts;
input rs232_rxd, rs232_cts;

input mouse_clock, mouse_data, keyboard_clock, keyboard_data;

input clock_27mhz, clock1, clock2;

output disp_blank, disp_clock, disp_rs, disp_ce_b, disp_reset_b;
input disp_data_in;
output disp_data_out;

input button0, button1, button2, button3, button_enter, button_right,
      button_left, button_down, button_up;
input [7:0] switch;
output [7:0] led;

inout [31:0] user1, user2, user3, user4;

inout [43:0] daughtercard;

inout [15:0] systemace_data;
output [6:0] systemace_address;
output systemace_ce_b, systemace_we_b, systemace_oe_b;
input systemace_irq, systemace_mpbrdy;

```

```

output [15:0] analyzer1_data, analyzer2_data, analyzer3_data,
        analyzer4_data;
output analyzer1_clock, analyzer2_clock, analyzer3_clock, analyzer4_clock;

///////////////////////////////
// I/O Assignments
// ///////////////////////
// Audio Input and Output
assign beep= 1'b0;
assign audio_reset_b = 1'b0;
assign ac97_synch = 1'b0;
assign ac97_sdata_out = 1'b0;
// ac97_sdata_in is an input

// Video Output
assign tv_out_ycrcb = 10'h0;
assign tv_out_reset_b = 1'b0;
assign tv_out_clock = 1'b0;
assign tv_out_i2c_clock = 1'b0;
assign tv_out_i2c_data = 1'b0;
assign tv_out_pal_ntsc = 1'b0;
assign tv_out_hsync_b = 1'b1;
assign tv_out_vsync_b = 1'b1;
assign tv_out_blank_b = 1'b1;
assign tv_out_subcar_reset = 1'b0;

// Video Input
assign tv_in_i2c_clock = 1'b0;
assign tv_in_fifo_read = 1'b0;
assign tv_in_fifo_clock = 1'b0;
assign tv_in_iso = 1'b0;
assign tv_in_reset_b = 1'b0;
assign tv_in_clock = 1'b0;
assign tv_in_i2c_data = 1'bZ;
// tv_in_ycrcb, tv_in_data_valid, tv_in_line_clock1, tv_in_line_clock2,
// tv_in_aef, tv_in_hff, and tv_in_aff are inputs

// SRAMs
assign ram0_data = 36'hZ;
assign ram0_address = 19'h0;
assign ram0_adv_ld = 1'b0;
assign ram0_clk = 1'b0;
assign ram0_cen_b = 1'b1;
assign ram0_ce_b = 1'b1;
assign ram0_oe_b = 1'b1;
assign ram0_we_b = 1'b1;
assign ram0_bwe_b = 4'hF;
assign ram1_data = 36'hZ;
assign ram1_address = 19'h0;
assign ram1_adv_ld = 1'b0;
assign ram1_clk = 1'b0;
assign ram1_cen_b = 1'b1;
assign ram1_ce_b = 1'b1;
assign ram1_oe_b = 1'b1;
assign ram1_we_b = 1'b1;
assign ram1_bwe_b = 4'hF;
assign clock_feedback_out = 1'b0;
// clock_feedback_in is an input

```

```

// Flash ROM
assign flash_data = 16'hZ;
assign flash_address = 24'h0;
assign flash_ce_b = 1'b1;
assign flash_oe_b = 1'b1;
assign flash_we_b = 1'b1;
assign flash_reset_b = 1'b0;
assign flash_byte_b = 1'b1;
// flash_sts is an input

// RS-232 Interface
assign rs232_txd = 1'b1;
assign rs232_rts = 1'b1;
// rs232_rxd and rs232_cts are inputs

// PS/2 Ports
// mouse_clock, mouse_data, keyboard_clock, and keyboard_data are inputs

// LED Displays
assign disp_blank = 1'b1;
assign disp_clock = 1'b0;
assign disp_rs = 1'b0;
assign disp_ce_b = 1'b1;
assign disp_reset_b = 1'b0;
assign disp_data_out = 1'b0;
// disp_data_in is an input

// Buttons, Switches, and Individual LEDs
// assign led = 8'hFF;
// button0, button1, button2, button3, button_enter, button_right,
// button_left, button_down, button_up, and switches are inputs

// User I/Os
assign user1 = 32'hZ;
assign user2 = 32'hZ;
assign user3 = 32'hZ;
assign user4 = 32'hZ;

// Daughtercard Connectors
assign daughtercard = 44'hZ;

// SystemACE Microprocessor Port
assign systemace_data = 16'hZ;
assign systemace_address = 7'h0;
assign systemace_ce_b = 1'b1;
assign systemace_we_b = 1'b1;
assign systemace_oe_b = 1'b1;
// systemace_irq and systemace_mpbrdy are inputs

///////////////////////////////
//
// videogame code
//
///////////////////////////////

// use FPGA's digital clock manager to produce a
// 31.5MHz clock
    // Those things, after the following two lines? THEY ARE NOT COMMENTS.
    // They are parameters for the digital clock manager.
    // I wish that had been documented somewhere.
wire clk_unbuf, clk;
DCM vclk1(.CLKIN(clock_27mhz),.CLKFX(clk_unbuf));

```

```

// synthesis attribute CLKFX_DIVIDE of vclk1 is 6
// synthesis attribute CLKFX_MULTIPLY of vclk1 is 7
// synthesis attribute CLK_FEEDBACK of vclk1 is NONE
// synthesis attribute CLKIN_PERIOD of vclk1 is 37
BUFG vclk2(.O(clk),.I(clk_unbuf));

// power-on reset generation
wire power_on_reset;      // remain high for first 16 clocks
SRL16 reset_sr (.D(1'b0), .CLK(clk), .Q(power_on_reset),
                 .A0(1'b1), .A1(1'b1), .A2(1'b1), .A3(1'b1));
defparam reset_sr.INIT = 16'hFFFF;

// Button 0 button is user reset
wire reset_user_reset;
debounce db1(power_on_reset, clk, ~button0, user_reset);
assign reset = user_reset | power_on_reset;

// UP, DOWN, LEFT, RIGHT, ENTER, 1, 2, 3 buttons for game control
wire up,down,left,right,enter,one,two,three;
debounce db2(reset, clk, ~button_up, up);
debounce db3(reset, clk, ~button_down, down);
debounce db4(reset, clk, ~button_left, left);
debounce db5(reset, clk, ~button_right, right);
debounce db6(reset, clk, ~button_enter, enter);
debounce db7(reset, clk, ~button1, one);
debounce db8(reset, clk, ~button2, two);
debounce db9(reset, clk, ~button3, three);

// generate basic VGA video signals
wire [10:0] hcount;
wire [9:0] vcount;
wire hsync,vsync,blank;
vga vgal(clk,hcount,vcount,hsync,vsync,blank);

// pixel tree output, fed to vga signal
wire [7:0] pixel;

/*
All parameters are listed here for programming convenience.

// GPU opcodes
parameter M_NEW_SPRITE          = 0;
parameter M_NEW_BLOB              = 1;
parameter M_NEW_TILED_SPRITE     = 2;
parameter M_DESTROY_SPRITE       = 3;
parameter M_MOVE_SPRITE          = 4;
parameter M_SET_LAYER_CLIP_ENEMY = 5;
parameter M_SET_FILTER           = 6;
parameter M_SET_MIRROR           = 7;
parameter M_SET_CAMERA            = 8;
parameter M_SET_BACKGROUND        = 9;
parameter M_SET_TYPE              = 10;

parameter C_NOP                  = 0;
parameter C_SET_POSITION         = 1;
parameter C_SET_TYPE              = 2;
parameter C_SET_LAYER_AND_CLIP   = 3;
parameter C_SET_MIRROR           = 4;
parameter C_CLEAN                = 5;
parameter C_CREATE_BLOB           = 6;
parameter C_CREATE_SPRITE         = 7;
parameter C_CREATE_TILED_SPRITE  = 8;
parameter C_SET_FILTER            = 9;

```

```

// IRQ xaddr
parameter I_ECOLLISION      = 3;
parameter I_COLLISION        = 4;
parameter I_UP_PRESS          = 5;
parameter I_DOWN_PRESS        = 6;
parameter I_LEFT_PRESS        = 7;
parameter I_RIGHT_PRESS       = 8;
parameter I_B1_PRESS          = 9;
parameter I_B2_PRESS          = 10;
parameter I_B3_PRESS          = 11;
parameter I_UP_RELEASE        = 12;
parameter I_DOWN_RELEASE      = 13;
parameter I_LEFT_RELEASE      = 14;
parameter I_RIGHT_RELEASE     = 15;
parameter I_B1_RELEASE        = 16;
parameter I_B2_RELEASE        = 17;
parameter I_B3_RELEASE        = 18;

// blob filters
parameter F_NONE    = 0;
parameter F_RED     = 1;
parameter F_GREEN   = 2;
parameter F_BLUE    = 3;
parameter F_YELLOW  = 4;
parameter F_PURPLE  = 5;
parameter F_CYAN    = 6;
parameter F_INVERT  = 7;
parameter F_BLACK   = 8;
parameter F_WHITE   = 9;
*/

```

```

// blob manager related wires
wire ctl;
wire[3:0] command_bus;
wire[5:0] id_bus;
wire[1:0] layer_bus;
wire collidable_bus, enemy_bus;
wire[5:0] filter_bus;
wire[1:0] mirror_bus;
wire[6:0] type_bus;
wire[31:0] xl_bus, x2_bus, y1_bus, y2_bus;
wire[31:0] pixel_x, pixel_y;
wire[9:0] x_request, y_request;

// sprite manager related wires
wire[11:0] adr_in;
wire[7:0] din;
wire[31:0] request, we;
wire[223:0] sprite_type;
wire[7:0] alpha_bus, h_bus, w_bus;

// pixel-tree related wires
wire[31:0] collision, ecollision;
wire[7:0] bkg_pixel;
wire[255:0] pixels;
wire[223:0] owners;
wire[31:0] zs;
wire[63:0] layers;
wire[63:0] ce;

// CPU related wires
wire irq, full, pc31, hwwe, mwe;

```

```

wire[4:0] xadr;
wire[31:0] ma;
wire[31:0] mdin, mdout;
wire[31:0] reg1, reg2, reg3, reg4, reg5;

// beta, memory and interrupts

beta2 beta (.clk(clk),.reset(reset),.irq(irq),.xadr({24'b0,xadr,2'b0}),
            .ma(ma),.mdin(mdin),.mdout(mdout),.mwe(mwe), .reg1(reg1),
            .reg2(reg2), .reg3(reg3), .reg4(reg4), .reg5(reg5),
            .ctrl(ctl), .pc31(pc31));

ram_beta beta_ram(.clock(clk), .we(mwe), .addr(ma[15:2]), .rdata(mdin),
                  .wdata(mdout), .hwwe(hwwe), .xadr(xadr),
                  .collision(collision), .ecollision(ecollision));

interrupt_generator ig(clk, reset, collision, ecollision, up, down,
                      left, right, enter, one, two, three, irq, xadr,
                      hwwe, pc31);

assign led = ~{up, down, left, right, enter, reset, switch[1], switch[0]};

// GPU

coordinate_generator cg (clk, reset, hcount, vcount, x_request, y_request);

// debug wires
wire[31:0] screen_x, screen_y, x1, y1;

blob_manager bm (.clk(clk), .reset(reset), .ctl(ctl), .reg1(reg1),
                 .reg2(reg2), .reg3(reg3), .reg4(reg4), .reg5(reg5),
                 .x_request(x_request), .y_request(y_request),
                 .pixel_x(pixel_x), .pixel_y(pixel_y), .x1_bus(x1_bus),
                 .y1_bus(y1_bus), .x2_bus(x2_bus), .y2_bus(y2_bus),
                 .type_bus(type_bus), .mirror_bus(mirror_bus),
                 .filter_bus(filter_bus), .collidable_bus(collidable_bus),
                 .enemy_bus(enemy_bus), .layer_bus(layer_bus), .id_bus(id_bus),
                 .command_bus(command_bus), .bkg_pixel(bkg_pixel),
                 .screen_x(screen_x), .screen_y(screen_y));

pixel_tree pt (clk, pixels, owners, zs, layers, ce, pixel, collision,
               ecollision, bkg_pixel);

sprite_manager sm (.clk(clk), .reset(reset), .request(request),
                  .sprite_type(sprite_type), .we(we), .addr(adr_in),
                  .din(din), .alpha_bus(alpha_bus), .h_bus(h_bus),
                  .w_bus(w_bus));

// I didn't find verilog supportive enough for looping through distinct
// instances, specifying indexes. The list of blob instances was generated
// using an external script, then pasted here.

wire[7:0] x_rem1, y_rem1, x_rem2, y_rem2; // debug wires

// Debug signals to logic analyzer.
// Possibly the most-often edited piece of code of this project.
assign analyzer1_data = ma[15:0];
assign analyzer1_clock = clk;
assign analyzer2_data = {xadr[2:0], irq, we[3:0], xadr[4:3],

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```

        command_bus,ctl,reset};
assign analyzer2_clock = clk;
assign analyzer3_data = switch[5] ? (switch[3] ? x_reml : y_reml) :
                           switch[3] ? din : adr_in;
assign analyzer3_clock = clk;
assign analyzer4_data = switch[7] ? (switch[6] ? x_rem2 : y_rem2) :
                           switch[6] ? {h_bus,w_bus} : {pixel_x, pixel_y};
assign analyzer4_clock = clk;

blob blob0(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[7:0], layers[1:0], owners[6:0], we[0], din, adr_in,
           sprite_type[6:0], request[0], zs[0], ce[1:0], x_reml, y_reml);

blob blob1(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[15:8], layers[3:2], owners[13:7], we[1], din, adr_in,
           sprite_type[13:7], request[1], zs[1], ce[3:2], x_rem2, y_rem2);

blob blob2(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[23:16], layers[5:4], owners[20:14], we[2], din, adr_in,
           sprite_type[20:14], request[2], zs[2], ce[5:4]);

blob blob3(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[31:24], layers[7:6], owners[27:21], we[3], din, adr_in,
           sprite_type[27:21], request[3], zs[3], ce[7:6]);

blob blob4(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[39:32], layers[9:8], owners[34:28], we[4], din, adr_in,
           sprite_type[34:28], request[4], zs[4], ce[9:8]);

blob blob5(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[47:40], layers[11:10], owners[41:35], we[5], din, adr_in,
           sprite_type[41:35], request[5], zs[5], ce[11:10]);

blob blob6(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[55:48], layers[13:12], owners[48:42], we[6], din, adr_in,
           sprite_type[48:42], request[6], zs[6], ce[13:12]);

blob blob7(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[63:56], layers[15:14], owners[55:49], we[7], din, adr_in,
           sprite_type[55:49], request[7], zs[7], ce[15:14]);

blob blob8(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[71:64], layers[17:16], owners[62:56], we[8], din, adr_in,
           sprite_type[62:56], request[8], zs[8], ce[17:16]);

```

```

blob blob9(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[79:72], layers[19:18], owners[69:63], we[9], din, adr_in,
           sprite_type[69:63], request[9], zs[9], ce[19:18]);

blob blob10(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[87:80], layers[21:20], owners[76:70], we[10], din, adr_in,
           sprite_type[76:70], request[10], zs[10], ce[21:20]);

blob blob11(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[95:88], layers[23:22], owners[83:77], we[11], din, adr_in,
           sprite_type[83:77], request[11], zs[11], ce[23:22]);

blob blob12(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus, ty
pe_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
pixels[103:96], layers[25:24], owners[90:84], we[12], din,
adr_in, sprite_type[90:84], request[12], zs[12], ce[25:24]);

blob blob13(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[111:104], layers[27:26], owners[97:91], we[13], din,
           adr_in, sprite_type[97:91], request[13], zs[13], ce[27:26]);

blob blob14(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[119:112], layers[29:28], owners[104:98], we[14], din,
           adr_in, sprite_type[104:98], request[14], zs[14], ce[29:28]);

blob blob15(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[127:120], layers[31:30], owners[111:105], we[15], din,
           adr_in, sprite_type[111:105], request[15], zs[15], ce[31:30]);

blob blob16(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[135:128], layers[33:32], owners[118:112], we[16], din,
           adr_in, sprite_type[118:112], request[16], zs[16], ce[33:32]);

blob blob17(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[143:136], layers[35:34], owners[125:119], we[17], din,
           adr_in, sprite_type[125:119], request[17], zs[17], ce[35:34]);

blob blob18(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
           pixels[151:144], layers[37:36], owners[132:126], we[18], din,
           adr_in, sprite_type[132:126], request[18], zs[18], ce[37:36]);

blob blob19(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
           type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
           layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,

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pixels[159:152], layers[39:38], owners[139:133], we[19], din,
adr_in, sprite_type[139:133], request[19], zs[19], ce[39:38]);

blob blob20(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
    type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
    layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
    pixels[167:160], layers[41:40], owners[146:140], we[20], din,
    adr_in, sprite_type[146:140], request[20], zs[20], ce[41:40]);

blob blob21(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
    type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
    layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
    pixels[175:168], layers[43:42], owners[153:147], we[21], din,
    adr_in, sprite_type[153:147], request[21], zs[21], ce[43:42]);

blob blob22(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
    type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
    layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
    pixels[183:176], layers[45:44], owners[160:154], we[22], din,
    adr_in, sprite_type[160:154], request[22], zs[22], ce[45:44]);

blob blob23(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
    type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
    layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
    pixels[191:184], layers[47:46], owners[167:161], we[23], din,
    adr_in, sprite_type[167:161], request[23], zs[23], ce[47:46]);

blob blob24(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
    type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
    layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
    pixels[199:192], layers[49:48], owners[174:168], we[24], din,
    adr_in, sprite_type[174:168], request[24], zs[24], ce[49:48]);

blob blob25(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
    type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
    layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
    pixels[207:200], layers[51:50], owners[181:175], we[25], din,
    adr_in, sprite_type[181:175], request[25], zs[25], ce[51:50]);

blob blob26(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
    type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
    layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
    pixels[215:208], layers[53:52], owners[188:182], we[26], din,
    adr_in, sprite_type[188:182], request[26], zs[26], ce[53:52]);

blob blob27(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
    type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
    layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
    pixels[223:216], layers[55:54], owners[195:189], we[27], din,
    adr_in, sprite_type[195:189], request[27], zs[27], ce[55:54]);

blob blob28(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
    type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
    layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
    pixels[231:224], layers[57:56], owners[202:196], we[28], din,
    adr_in, sprite_type[202:196], request[28], zs[28], ce[57:56]);

blob blob29(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
    type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
    layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
    pixels[239:232], layers[59:58], owners[209:203], we[29], din,
    adr_in, sprite_type[209:203], request[29], zs[29], ce[59:58]);

```

```

blob blob30(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
            type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
            layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
            pixels[247:240], layers[61:60], owners[216:210], we[30], din,
            adr_in, sprite_type[216:210], request[30], zs[30], ce[61:60]);

blob blob31(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
            type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,
            layer_bus, alpha_bus, h_bus, w_bus, id_bus, command_bus,
            pixels[255:248], layers[63:62], owners[223:217], we[31], din,
            adr_in, sprite_type[223:217], request[31], zs[31], ce[63:62]);

// blob parameters: needed for collecting collision info
defparam blob0.OWNER = 0;
defparam blob1.OWNER = 1;
defparam blob2.OWNER = 2;
defparam blob3.OWNER = 3;
defparam blob4.OWNER = 4;
defparam blob5.OWNER = 5;
defparam blob6.OWNER = 6;
defparam blob7.OWNER = 7;

defparam blob8.OWNER = 8;
defparam blob9.OWNER = 9;
defparam blob10.OWNER = 10;
defparam blob11.OWNER = 11;
defparam blob12.OWNER = 12;
defparam blob13.OWNER = 13;
defparam blob14.OWNER = 14;
defparam blob15.OWNER = 15;

defparam blob16.OWNER = 16;
defparam blob17.OWNER = 17;
defparam blob18.OWNER = 18;
defparam blob19.OWNER = 19;
defparam blob20.OWNER = 20;
defparam blob21.OWNER = 21;
defparam blob22.OWNER = 22;
defparam blob23.OWNER = 23;

defparam blob24.OWNER = 24;
defparam blob25.OWNER = 25;
defparam blob26.OWNER = 26;
defparam blob27.OWNER = 27;
defparam blob28.OWNER = 28;
defparam blob29.OWNER = 29;
defparam blob30.OWNER = 30;
defparam blob31.OWNER = 31;

parameter PIXELS_PER_LINE = 640;
parameter LINES           = 480;

// switch[1:0] selects which video generator to use:
// 00 (or 11): final project game
// 01: 1 pixel outline of active video area (adjust screen controls)
// 10: color bars
reg [7:0] rgb;
reg b,hs,vs;

always @(posedge clk) begin
    hs <= hsync;
    vs <= vsync;

```

```

b <= blank;

// zero rgb if outside screen; somehow needed for preventing badness
if (hcount > PIXELS_PER_LINE || vcount > LINES)
    rgb <= 0;

else if (switch[1:0] == 2'b01) begin
    // 1 pixel outline of visible area (white)
    rgb <= (hcount==0 | hcount==PIXELS_PER_LINE-1 | vcount==0
        | vcount==LINES-1 ) ? 8'hFF : 0;

end
else if (switch[1:0] == 2'b10) begin
    // color bars; map a bit from vertical coordinates to every
    // bit of a color
    rgb <= {hcount[8], hcount[8], hcount[8], hcount[7], hcount[7], hcount[6],
        hcount[6], hcount[6]};

end
else if (switch[2])
    rgb <= pixel;

else
    rgb <= zs[0] ? bkg_pixel : pixels[7:0];

end

// VGA Output. In order to meet the setup and hold times of the
// ADV7125, we send it ~clk, just like the code that was here when
// I copied this piece of code over from lab5 of 6.111 Fall '07.
// No matter that the resolution and the clock are completely different.
// We use small tables (converted to ROMs by synthesis) to convert
// colors from 2 or 3 bits back to 8 bits.
three_vga red_converter(rgb[7:5], vga_out_red);
two_vga green_converter(rgb[4:3], vga_out_green);
three_vga blue_converter(rgb[2:0], vga_out_blue);
assign vga_out_sync_b = 1'bl;      // not used
assign vga_out_blank_b = ~b;
assign vga_out_pixel_clock = clk;
assign vga_out_hsync = hs;
assign vga_out_vsync = vs;

endmodule

// converts 2-bit color information to 8-bit
module two_vga(two, eight);
    input[1:0] two;
    output[7:0] eight;

    reg[7:0] eight;

    always @(two) begin
        case (two)
            2'b00: eight = 8'h00;
            2'b01: eight = 8'h55;
            2'b10: eight = 8'hAA;
            2'b11: eight = 8'hFF;
            default: eight = 8'hXX;
        endcase
    end
endmodule

```

```

// converts 3-bit color information to 8-bit
module three_vga(three, eight);
    input[2:0] three;
    output[7:0] eight;

    reg[7:0] eight;

    always @(three) begin
        case (three)
            3'b000: eight = 8'h00;
            3'b001: eight = 8'h24;
            3'b010: eight = 8'h49;
            3'b011: eight = 8'h6D;
            3'b100: eight = 8'h92;
            3'b101: eight = 8'hB6;
            3'b110: eight = 8'hDB;
            3'b111: eight = 8'hFF;
            default: eight = 8'hXX;
        endcase
    end

endmodule

///////////////////////////////
//  

//      A wrapper for the RAM, giving write access to a couple registers to  

//      hardware.  

//  

///////////////////////////////

module ram_beta (clock, we, addr, rdata, wdata, hwwe, xadr, collision,  

                ecollision);
    input clock;
    input we;                      // write enable: 1=write, 0=read (from addr 1)
    input[13:0] addr;              // address
    input[31:0] wdata;              // write data port
    input hwwe;                   // hardware interrupt write enable
    input[4:0] xadr;               // instruction type (I_ECOLLISION or
                                // I_COLLISION)
    input[31:0] collision, ecollision;

    output[31:0] rdata;           // read data port

    // RAM hardware interrupt reserved addresses
    parameter M_COLLISION_ADDR = 21;
    parameter M_ECOLLISION_ADDR = 22;

    parameter I_ECOLLISION     = 3;
    parameter I_COLLISION      = 4;

    wire[31:0] ram_rdata;
    wire[31:0] rdata;

    reg[31:0] extra_memory[1:0];

    // the real RAM, with game code logic, goes here
    ram real_ram(.addr(addr), .clk(clock), .din(wdata), .dout(ram_rdata),
                .we(we));

    // mux where to read from, RAM or shadowing registers
    assign rdata = (addr == M_COLLISION_ADDR) ? extra_memory[0]
                                              : (addr == M_ECOLLISION_ADDR) ? extra_memory[1]
                                              : ram_rdata;

```

```

always @(posedge clock) begin
    // write enable
    if (we) begin
        if (addr == M_COLLISION_ADDR)
            extra_memory[0] <= wdata;
        else if (addr == M_ECOLLISION_ADDR)
            extra_memory[1] <= wdata;
    end

    // hardware write enable
    if (hwwe) begin
        if (xadr == I_COLLISION)
            extra_memory[0] <= collision;
        if (xadr == I_ECOLLISION)
            extra_memory[1] <= ecollision;
    end
end

endmodule

```

vga.v

Contains the VGA module, based on the XVGA module from lab 5, but with pixels per line, number of lines, porches and sync pulse parameters explicated, for easier understanding of the code and future generalizations.

```

///////////////////////////////
// vga: Generate VGA display signals (640 x 480 @ 75Hz)
///////////////////////////////

module vga(vclock, hcount, vcount, hsync, vsync, blank);
    input vclock;

    output[10:0] hcount;
    output[9:0] vcount;
    output vsync, hsync, blank;

    reg hsync, vsync, hblank, vblank, blank;
    reg [10:0] hcount;      // pixel number on current line
    reg [9:0] vcount;      // line number

    parameter PIXELS_PER_LINE = 640;
    parameter H_FRONT_PORCH   = 16;
    parameter H_SYNC_PULSE    = 96;
    parameter H_BACK_PORCH    = 48;

    parameter LINES          = 480;
    parameter V_FRONT_PORCH  = 11;
    parameter V_SYNC_PULSE   = 2;
    parameter V_BACK_PORCH   = 32;

    // horizontal
    wire hsyncon, hsyncoff, hreset, hblankon;
    assign hblankon  = (hcount == PIXELS_PER_LINE - 1);
    assign hsyncon   = (hcount == PIXELS_PER_LINE + H_FRONT_PORCH - 1);
    assign hsyncoff  = (hcount == PIXELS_PER_LINE + H_FRONT_PORCH
                       + H_SYNC_PULSE - 1);
    assign hreset    = (hcount == PIXELS_PER_LINE + H_FRONT_PORCH

```

```

+ H_SYNC_PULSE + H_BACK_PORCH - 1);

// vertical
wire vsynccon, vsyncoff, vreset, vblankon;
assign vblankon = hreset & (vcount == LINES - 1);
assign vsynccon = hreset & (vcount == LINES + V_FRONT_PORCH - 1);
assign vsyncoff = hreset & (vcount == LINES + V_FRONT_PORCH
                           + V_SYNC_PULSE - 1);
assign vreset = hreset & (vcount == LINES + V_FRONT_PORCH
                           + V_SYNC_PULSE + V_BACK_PORCH - 1);

// sync and blanking
wire next_hblank, next_vblank;
assign next_hblank = hreset ? 0 : hblankon ? 1 : hblank;
assign next_vblank = vreset ? 0 : vblankon ? 1 : vblank;

always @(posedge vclock) begin
    hcount <= hreset ? 0 : hcount + 1;
    hblank <= next_hblank;
    hsync <= hsynccon ? 0 : hsyncoff ? 1 : hsync;

    vcount <= hreset ? (vreset? 0 : vcount + 1) : vcount;
    vblank <= next_vblank;
    vsync <= vsynccon ? 0 : vsyncoff ? 1 : vsync;

    blank <= next_vblank | (next_vblank & ~hreset);
end

endmodule

```

beta2.v

Contains the 2-stage pipelined beta processor and its submodules. Based largely on the beta2.v file provided on the 6.111 course website, but modified to expose pc31 and the first 5 registers, as well as adding the new hardware call opcode.

```

///////////////////////////////
//
//      2-stage pipelined Beta (one bidirectional memory port) [cjt]
// modified to expose registers and control signal, and for interrupts
//
///////////////////////////////

module beta2(clk, reset, irq, xadr, ma, mdin, mdout, mwe, reg1, reg2, reg3,
            reg4, reg5, ctrl, pc31);
    input clk, reset, irq;
    input[30:0] xadr;                      // irq address
    input[31:0] mdin;                      // data in

    output[31:0] ma;                      // memory address
    output[31:0] mdout;                     // data out
    output[31:0] reg1, reg2, reg3, reg4, reg5;
                                         // exposed register values
    output mwe;                          // memory write enable
    output ctrl;                         // control signal for hardware
    output pc31;                         // exposed supervisor bit

    // beta2 registers
    reg [31:0] npc, pc_inc;
    reg [31:0] inst;

```

```

reg [4:0] rc_save; // needed for second cycle on LD,LDR

// debug
assign opcode = inst[31:26];

// internal buses
wire [31:0] rd1,rd2,wd;
wire [31:0] a,b,xb,c,addsub,cmp,shift,boole,mult;

// control signals
wire wasel,werf,z,asel,bsel,csel;
wire addsub_op,cmp_lt,cmp_eq,shift_op,shift_sxt,boole_and,boole_or;
wire wd_addsub,wd_cmp,wd_shift,wd_boole,wd_mult;
wire msel,msel_next,branch,trap,interrupt;

assign pc31 = npc[31];

// pc
wire [31:0] npc_inc,npc_next;
assign npc_inc = npc + 4;
assign npc_next = reset ? 32'h80000000 :
    msel ? npc :
    branch ? {npc[31] & addsub[31],addsub[30:2],2'b00} :
    trap ? 32'h80000004 :
    interrupt ? {1'b1,xadr} :
    {npc[31],npc_inc[30:0]};
always @ (posedge clk) begin
    npc <= npc_next; // logic for msel handled above
    if (!msel) pc_inc <= {npc[31],npc_inc[30:0]};
end

// instruction reg
always @ (posedge clk) if (!msel) inst <= mdin;

// control logic
decode ctl(.clk(clk),.reset(reset),.irq(irq & !npc[31]),.z(z),
    .opcode(inst[31:26]),
    .asel(asel),.bsel(bsel),.csel(csel),.wasel(wasel),
    .werf(werf),.msel(msel),.msel_next(msel_next),.mwe(mwe),
    .addsub_op(addsub_op),.cmp_lt(cmp_lt),.cmp_eq(cmp_eq),
    .shift_op(shift_op),.shift_sxt(shift_sxt),
    .boole_and(boole_and),.boole_or(boole_or),
    .wd_addsub(wd_addsub),.wd_cmp(wd_cmp),
    .wd_shift(wd_shift),.wd_boole(wd_boole),.wd_mult(wd_mult),
    .branch(branch),.trap(trap),.interrupt(interrupt),.ctrl(ctrl));

// register file
wire [4:0] wa;
always @ (posedge clk) if (!msel) rc_save <= inst[25:21];
assign wa = msel ? rc_save : wasel ? 5'd30 : inst[25:21];

regfile rf(inst[20:16],rd1,inst[15:11],rd2,inst[25:21],mdout,
    wa,wd,clk,werf,reg1,reg2,reg3,reg4,reg5);

assign z = ~| rd1; // used in BEQ/BNE instructions

// alu
assign a = asel ? pc_inc : rd1;
assign b = bsel ? c : rd2;
assign c = csel ? {{14{inst[15]}},inst[15:0],2'b00} :
    {{16{inst[15]}},inst[15:0]};

wire addsub_n,addsub_v,addsub_z;

```

```

assign xb = {32{addsub_op}} ^ b;
assign addsub = a + xb + addsub_op;
assign addsub_n = addsub[31];
assign addsub_v = (addsub[31] & ~a[31] & ~xb[31]) |
                  (~addsub[31] & a[31] & xb[31]);
assign addsub_z = ~| addsub;

assign cmp[31:1] = 0;
assign cmp[0] = (cmp_lt & (addsub_n ^ addsub_v)) | (cmp_eq & addsub_z);

//mul32 mpy(a,b,mult);

wire [31:0] shift_right;
// Verilog >>> operator not synthesized correctly, so do it by hand
shift_right sr(shift_sxt,a,b[4:0],shift_right);
assign shift = shift_op ? shift_right : a << b[4:0];

assign boole = boole_and ? (a & b) : boole_or ? (a | b) : a ^ b;

// result mux, listed in order of speed (slowest first)
assign wd = msel ? mdin :
            wd_cmp ? cmp :
            wd_addsub ? addsub :
            //wd_mult ? mult :
            wd_shift ? shift :
            wd_boole ? boole :
            pc_inc;

// assume synchronous external memory
assign ma = msel_next ? {npc[31],addsub[30:0]} : npc_next;
endmodule

///////////////////////////////
//
//      3-port register file
//
///////////////////////////////

// Beta register file: 32 registers of 32 bits
// R31 always reads as 0
// 3 read ports, 1 write port
module regfile(ral,rd1,ra2,rd2,ra3,rd3,wa,wd,clk,werf,reg1,reg2,reg3,reg4,reg5);
    input [4:0] ral,ra2,ra3,wa;
    output [31:0] rd1,rd2,rd3;
    output [31:0] reg1, reg2, reg3,reg4,reg5;
    input [31:0] wd;
    input clk,werf;

    (* ram_style = "distributed" *)
    reg [31:0] regfile[31:0];
    reg [31:0] reg1,reg2,reg3,reg4,reg5;

    assign rd1 = regfile[ral];
    assign rd2 = regfile[ra2];
    assign rd3 = regfile[ra3];

    always @ (posedge clk)
        if (werf && wa != 31) begin
            regfile[wa] <= wd;
            if (wa == 5'd1) reg1 <= wd;
            if (wa == 5'd2) reg2 <= wd;
            if (wa == 5'd3) reg3 <= wd;
            if (wa == 5'd4) reg4 <= wd;

```

```

        if (wa == 5'd5) reg5 <= wd;
    end

endmodule

///////////////////////////////
// Instruction decode (inst => datapath control signals)
// //////////////////////

module decode(clk,reset,irq,z,opcode,
              asel,bsel,csel,wasel,werf,msel,msel_next,mwe,
              addsub_op,cmp_lt,cmp_eq,
              shift_op,shift_sxt,boole_and,boole_or,
              wd_addsub,wd_cmp,wd_shift,wd_boole,wd_mult,
              branch,trap,interrupt,ctrl);
input clk,reset,irq,z;
input [5:0] opcode;
output asel,bsel,csel,wasel,werf,msel,msel_next,mwe;
output addsub_op,shift_op,shift_sxt,cmp_lt,cmp_eq,boole_and,boole_or;
output wd_addsub,wd_cmp,wd_shift,wd_boole,wd_mult;
output branch,trap,interrupt,ctrl;

reg asel,bsel,csel,wasel,mem_next;
reg addsub_op,shift_op,shift_sxt,cmp_lt,cmp_eq,boole_and,boole_or;
reg wd_addsub,wd_cmp,wd_shift,wd_boole,wd_mult;
reg branch,trap,interrupt,ctrl;

// a little bit of state...
reg annul,msel,mwrite;

always @ (opcode or z or annul or msel or irq or reset)
begin
    // initial assignments for all control signals
    asel = 1'hx;
    bsel = 1'hx;
    csel = 1'hx;
    addsub_op = 1'hx;
    shift_op = 1'hx;
    shift_sxt = 1'hx;
    cmp_lt = 1'hx;
    cmp_eq = 1'hx;
    boole_and = 1'hx;
    boole_or = 1'hx;

    wasel = 0;
    mem_next = 0;

    wd_addsub = 0;
    wd_cmp = 0;
    wd_shift = 0;
    wd_boole = 0;
    wd_mult = 0;

    branch = 0;
    trap = 0;
    interrupt = 0;
    ctrl = 0;

    if (irq && !reset && !annul && !msel) begin
        interrupt = 1;
        wasel = 1;

```

```

end else casez (opcode)
 6'b000001: begin // HW call
    ctrl = 1;
  end
 6'b011000: begin // LD
    asel = 0; bsel = 1; csel = 0;
    addsub_op = 0;
    mem_next = 1;
  end
 6'b011001: begin // ST
    asel = 0; bsel = 1; csel = 0;
    addsub_op = 0;
    mem_next = 1;
  end
 6'b011011: begin // JMP
    asel = 0; bsel = 1; csel = 0;
    addsub_op = 0;
    branch = !annul && !msel;
  end
 6'b011101: begin // BEQ
    asel = 1; bsel = 1; csel = 1;
    addsub_op = 0;
    branch = !annul && !msel && z;
  end
 6'b011110: begin // BNE
    asel = 1; bsel = 1; csel = 1;
    addsub_op = 0;
    branch = !annul && !msel && ~z;
  end
 6'b011111: begin // LDR
    asel = 1; bsel = 1; csel = 1;
    addsub_op = 0;
    mem_next = 1;
  end
 6'b1?0000: begin // ADD, ADDC
    asel = 0; bsel = opcode[4]; csel = 0;
    addsub_op = 0;
    wd_addsub = 1;
  end
 6'b1?0001: begin // SUB, SUBC
    asel = 0; bsel = opcode[4]; csel = 0;
    addsub_op = 1;
    wd_addsub = 1;
  end
//6'b1?0010: begin // MUL, MULC
//    asel = 0; bsel = opcode[4]; csel = 0;
//    wd_mult = 1;
//  end
 6'b1?0100: begin // CMPEQ, CMPEQC
    asel = 0; bsel = opcode[4]; csel = 0;
    addsub_op = 1;
    cmp_eq = 1; cmp_lt = 0;
    wd_cmp = 1;
  end
 6'b1?0101: begin // CMPLT, CMPLTC
    asel = 0; bsel = opcode[4]; csel = 0;
    addsub_op = 1;
    cmp_eq = 0; cmp_lt = 1;
    wd_cmp = 1;
  end
 6'b1?0110: begin // CMPLE, CMPLEC
    asel = 0; bsel = opcode[4]; csel = 0;
    addsub_op = 1;

```

```

        cmp_eq = 1; cmp_lt = 1;
        wd_cmp = 1;
    end
6'b1?1000: begin // AND, ANDC
    asel = 0; bsel = opcode[4]; csel = 0;
    boole_and = 1; boole_or = 0;
    wd_boole = 1;
end
6'b1?1001: begin // OR, ORC
    asel = 0; bsel = opcode[4]; csel = 0;
    boole_and = 0; boole_or = 1;
    wd_boole = 1;
end
6'b1?1010: begin // XOR, Xorc
    asel = 0; bsel = opcode[4]; csel = 0;
    boole_and = 0; boole_or = 0;
    wd_boole = 1;
end
6'b1?1100: begin // SHL, SHLC
    asel = 0; bsel = opcode[4]; csel = 0;
    shift_op = 0;
    wd_shift = 1;
end
6'b1?1101: begin // SHR, SHRC
    asel = 0; bsel = opcode[4]; csel = 0;
    shift_op = 1; shift_sxt = 0;
    wd_shift = 1;
end
6'b1?1110: begin // SRA, SRAC
    asel = 0; bsel = opcode[4]; csel = 0;
    shift_op = 1; shift_sxt = 1;
    wd_shift = 1;
end
default: begin // illegal opcode
    trap = !annul && !msel; wasel = 1;
end
endcase
end

// state
wire msel_next = !reset && !annul && mem_next && !msel;
wire mwrite_next = msel_next && opcode==6'b011001;

always @ (posedge clk)
begin
    annul <= !reset && (trap || branch || interrupt);
    msel <= msel_next;
    mwrite <= mwrite_next;
end

assign mwe = mwrite_next; // assume synchronous memory
assign werf = msel ? !mwrite : (!annul & !mem_next);
endmodule

///////////////////////////////
// 32-bit signed/unsigned right shift
///////////////////////////////

module shift_right(sxt,a,b,shift_right);
    input sxt;
    input [31:0] a;

```

```

input [4:0] b;
output [31:0] shift_right;

wire [31:0] w,x,y,z;
wire sin;

assign sin = sxt & a[31];
assign w = b[0] ? {sin,a[31:1]} : a;
assign x = b[1] ? {{2{sin}},w[31:2]} : w;
assign y = b[2] ? {{4{sin}},x[31:4]} : x;
assign z = b[3] ? {{8{sin}},y[31:8]} : y;
assign shift_right = b[4] ? {{16{sin}},z[31:16]} : z;
endmodule

```

coordinate_generator.v

Contains the coordinate generator module; parametrized to configure for how many positions in advance to ask for.

```

///////////////////////////////
// 
// coordinate_generator: Sends screen coordinates to solicite for GPU in
// advance
// 
///////////////////////////////

module coordinate_generator(vclock, reset, hcount, vcount, x, y);

    input vclock, reset;
    input[10:0] hcount;
    input[9:0] vcount;

    output[9:0] x, y;

    reg[9:0] x, y;

    parameter LINE_SIZE    = 800;
    parameter TOTAL_LINES = 525;

    parameter STAGES = 5;

    always @(posedge vclock) begin
        if (reset) begin
            x <= 0;
            y <= 0;
        end
        if (hcount < LINE_SIZE - 1 - STAGES) begin
            x <= hcount + STAGES;
            y <= vcount;
        end
        else if (vcount == TOTAL_LINES - 1) begin
            x <= hcount + STAGES - 800;
            y <= 0;
        end
        else begin
            x <= hcount + STAGES - 800;
            y <= vcount + 1;
        end
    end
end

endmodule

```

debounce.v

Contains the debouncer module provided by most 6.111 laboratories.

```
//////////  
//  
// Pushbutton Debounce Module (video version)  
//  
//////////  
  
module debounce (reset, clock, noisy, clean);  
    input reset, clock, noisy;  
    output clean;  
  
    reg [19:0] count;  
    reg new, clean;  
  
    always @(posedge clock)  
        if (reset) begin new <= noisy; clean <= noisy; count <= 0; end  
        else if (noisy != new) begin new <= noisy; count <= 0; end  
        else if (count == 650000) clean <= new;  
        else count <= count+1;  
  
endmodule
```

blob.v

Contains the blob module.

```
//////////  
//  
// blob: Hardware blob responsible for displaying and managing one sprite.  
//  
// Receives instructions from blob manager, solicites and receives sprites  
// from sprite manager, and sends pixel information to pixel tree.  
//  
// Includes support for tiling, mirroring and some hardwired color filters.  
// Contains a small BRAM for storing a sprite.  
//  
// Could be extended to support right-angle rotation, or less easily for  
// other operations as zoom and rotation, using pixel color interpolation,  
// without modifying other modules except the blob manager.  
//  
// The maximum blob size is determined both by BRAM size and the remainder  
// counter registers (see below for more information).  
//  
//////////  
  
module blob(clk, reset, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,  
            type_bus, mirror_bus, filter_bus, collidable_bus, enemy_bus,  
            layer_bus, alpha_bus, h_bus, w_bus, id_bus, command, pixel_out,  
            layer_out, owner_out, we, din, addr_in, sprite_type, request, z,  
            ce, x_rem, y_rem);  
  
    input clk, reset;                                // clock and reset  
    input[31:0] pixel_x, pixel_y;                    // solicited pixel positions  
    input[31:0] x1_bus,y1_bus,x2_bus,y2_bus;        // buses for setting x1, x2,  
                                                    // y1, y2
```

```

input[6:0] type_bus;                                // bus for setting type
input[1:0] mirror_bus;                             // bus for setting mirror
input[5:0] filter_bus;                            // bus for setting filter
input collidable_bus, enemy_bus;                  // bus for setting collidable
                                                // and enemy bits
input[1:0] layer_bus;                            // bus for setting layers
input[5:0] id_bus;                               // blob ID bus
input[3:0] command;                             // bus with the command
input[7:0] din;                                 // pixel data received from
                                                // sprite manager
input[11:0] addr_in;                           // address to write the
                                                // received data to, from
                                                // sprite manager
input we;                                     // write enable to blob BRAM
input[7:0] alpha_bus, h_bus, w_bus;             // buses for setting the
                                                // transparent pixel color,
                                                // height and width, from
                                                // sprite manager
output[7:0] pixel_out;                         // produced pixel
output[1:0] layer_out;                          // produced layer
output[6:0] owner_out;                          // produced owner (constant and
                                                // equal to OWNER parameter)
output[6:0] sprite_type;                       // solicited sprite type for
                                                // sprite manager
output[1:0] ce;                                // output of collision/enemy
                                                // bits
output request, z;                            // request: request bit for
                                                // sprite manager;
                                                // z: whether the produced
                                                // pixel is transparent

parameter OWNER = 0;                           // OWNER parameter; identifies
                                                // a blob uniquely

// debug signals
output[7:0] x_rem, y_rem; // exposing for debug

// local memory
wire[7:0] dout;
reg[7:0] w, h;
reg[10:0] read_addr;
blob_memory memory(.addra(addr_in), .addrb(read_addr), .clka(clk),
                   .clkb(clk), .dina(din), .doutb(dout), .wea(we));

reg[1:0] state;
reg[31:0] x1, y1, x2, y2;
reg[6:0] type;
reg[3:0] step;
reg collidable, enemy;
reg[1:0] layer;
reg[7:0] pixel_out;
reg[1:0] layer_out;
reg z;
reg request;
reg platform;
reg[7:0] alpha;
reg prev_we, prev_we2;

reg[5:0] filter;
reg[1:0] mirror;

// blob states
parameter S_NONE = 0;

```

```

parameter S_SPRITE = 1;
parameter S_PLATFORM = 2;
parameter S_TILED_SPRITE = 3;

// blob commands
parameter C_NOP = 0;
parameter C_SET_POSITION = 1;
parameter C_SET_TYPE = 2;
parameter C_SET_LAYER_AND_CLIP = 3;
parameter C_SET_MIRROR = 4;
parameter C_CLEAN = 5;
parameter C_CREATE_BLOB = 6;
parameter C_CREATE_SPRITE = 7;
parameter C_CREATE_TILED_SPRITE = 8;
parameter C_SET_FILTER = 9;

// filter parameters
parameter F_NONE = 0;
parameter F_RED = 1;
parameter F_GREEN = 2;
parameter F_BLUE = 3;
parameter F_YELLOW = 4;
parameter F_PURPLE = 5;
parameter F_CYAN = 6;
parameter F_INVERT = 7;
parameter F_BLACK = 8;
parameter F_WHITE = 9;

assign owner_out = OWNER;
assign sprite_type = type;

reg[7:0] x_rem, y_rem;
reg prev_y_unit;
reg[7:0] prev_dout;
reg[1:0] ce;

always @ (posedge clk) begin

    if (reset) begin
        state <= S_NONE;
        layer_out <= 0;
        layer <= 0;
        request <= 0;
        read_addr <= 0;
        platform <= 0;
        filter <= F_NONE;
        mirror <= 0;
        x_rem <= 0;
        y_rem <= 0;
        prev_y_unit <= pixel_y[0];
        alpha <= 0;
        w <= 0;
        h <= 0;
        ce <= 0;
        prev_we <= 0;
        prev_we2 <= 0;
    end
    else begin

        // signals controlled by sprite manager
        // do not capture info if it is still writing old information;
        // only get signals on change of we from 0 to 1 (2 cycles ago)
        if (we & !prev_we2) begin

```

```

    request <= 0;
    alpha <= alpha_bus;
    w <= w_bus;
    h <= h_bus;
end

prev_we <= we;
prev_we2 <= prev_we;
layer_out <= layer;
prev_dout <= dout;

// x_rem and y_rem are bounded by w and y, respectively, so this
// statement makes sense;
// mirror bits are used to determine how to read the image
read_addr <= mirror[1] ? mirror[0] ? (h - y_rem) * w + (w - x_rem) :
                           (h - y_rem) * w + x_rem
                           : mirror[0] ? y_rem * w + (w - x_rem)
                           : y_rem * w + x_rem;

// Now, the remainder operation is way too expansive to do in one
// cycle at 31.5MHz, and looking up tables is too messy / roomy.

// The hack around it is to use the fact that, most of the time, the
// pixels will be scanned from right to left, then from top to down, and
// keep bounded counters that are set back to 0 whenever appropriate.

// Yes, it might cause at most one frame of weirdness when the sprite or
// the camera move, but one frame at 75Hz is not that bad.

// 0 <= x_rem < w, except when aligning just before sprite start
if ((pixel_x + 1) == x1)
    x_rem <= -1;
else if (pixel_x == 0)
    x_rem <= 0;
else if ((x_rem + 1) < w)
    x_rem <= x_rem + 1;
else
    x_rem <= 0;

// 0 <= y_rem < h, except when aligning just before sprite start
if (prev_y_unit != pixel_y[0]) begin
    prev_y_unit <= pixel_y[0];
    if ((pixel_y + 1) == y1)
        y_rem <= -1;
    else if (pixel_y == 0)
        y_rem <= 0;
    else if ((y_rem + 1) < h)
        y_rem <= y_rem + 1;
    else
        y_rem <= 0;
end

// interpret command if there is command available
if (id_bus == owner_out[5:0]) begin
    case (command)

        C_SET_POSITION:
        begin
            if (state == S_SPRITE) begin
                x1 <= x1_bus;
                y1 <= y1_bus;

```

```

    end
  else if (state == S_PLATFORM || state == S_TILED_SPRITE) begin
    x1 <= x1_bus;
    y1 <= y1_bus;
    x2 <= x2_bus;
    y2 <= y2_bus;
  end
end

C_SET_TYPE:
begin
  type <= type_bus;
  request <= 1;
end

C_SET_LAYER_AND_CLIP:
begin
  layer <= layer_bus;
  collidable <= collidable_bus;
  enemy <= enemy_bus;
end

C_SET_MIRROR:
begin
  mirror <= mirror_bus;
end

C_CLEAN:
begin
  state <= S_NONE;
  request <= 0;
  platform <= 0;
end

C_CREATE_BLOB:
begin
  state <= S_PLATFORM;
  x1 <= x1_bus;
  y1 <= y1_bus;
  x2 <= x2_bus;
  y2 <= y2_bus;
  collidable <= 1;
  platform <= 1;
  request <= 0;
  layer <= 3;
  enemy <= enemy_bus;
end

C_CREATE_SPRITE:
begin
  state <= S_SPRITE;
  x1 <= x1_bus;
  y1 <= y1_bus;
  type <= type_bus;
  layer <= layer_bus;
  collidable <= collidable_bus;
  enemy <= enemy_bus;
  platform <= 0;
  request <= 1;
  mirror <= 0;
  filter <= F_NONE;
end

```

```

C_CREATE_TILED_SPRITE:
begin
    state <= S_TILED_SPRITE;
    x1 <= x1_bus;
    y1 <= y1_bus;
    x2 <= x2_bus;
    y2 <= y2_bus;
    type <= type_bus;
    layer <= layer_bus;
    platform <= 0;
    collidable <= collidable_bus;
    enemy <= enemy_bus;
    request <= 1;
    mirror <= 0;
    filter <= F_NONE;
end

C_SET_FILTER:
begin
    filter <= filter_bus;
    mirror <= mirror_bus;
end

// on default, do nothing

endcase
end

// produce pixel_out:
case (state)

S_NONE:
begin
    pixel_out <= 0;
    alpha <= 0;
    z <= 1;
end

S_SPRITE:
begin
    if (pixel_x < x1 +4 || pixel_x >= x1 + w +4 || pixel_y < y1 +4
        || pixel_y >= y1 + h+4) begin
        pixel_out <= 0;
        ce <= 0;
        z <= 1;
    end
    else begin
        case (filter)
            F_NONE:    pixel_out <= dout;
            F_RED:     pixel_out <= {dout[7:5],5'b0};
            F_GREEN:   pixel_out <= {3'b0,dout[4:3],3'b0};
            F_BLUE:    pixel_out <= {5'b0,dout[2:0]};
            F_YELLOW:  pixel_out <= {dout[7:3],3'b0};
            F_PURPLE:  pixel_out <= {dout[7:5],2'b0,dout[2:0]};
            F_CYAN:    pixel_out <= {3'b0,dout[4:0]};
            F_INVERT:  pixel_out <= ~dout;
            F_BLACK:   pixel_out <= 8'h00;
            F_WHITE:   pixel_out <= 8'hFF;
            default:   pixel_out <= dout;
        endcase
        ce[0] <= (dout != alpha);
        ce[1] <= (dout != alpha) && enemy;
        z <= (dout == alpha);
    end
end

```

```

        end
    end

    S_PLATFORM:
    begin
        z <= 1;
        pixel_out <= 0;
        if (pixel_x < x1 || pixel_x >= x2 || pixel_y <= y1 || pixel_y >= y2)
        begin
            ce <= 0;
        end
        else begin
            ce[0] <= 1;
            ce[1] <= enemy;
        end
    end

    S_TILED_SPRITE:
    begin
        if (pixel_x < x1 +4|| pixel_x >= x2 +4|| pixel_y < y1 +4
            || pixel_y >= y2+4) begin
            pixel_out <= 0;
            z <= 1;
            ce <= 0;
        end
        else begin
            case (filter)
                F_NONE:      pixel_out <= dout;
                F_RED:       pixel_out <= {dout[7:5],5'b0};
                F_GREEN:     pixel_out <= {3'b0,dout[4:3],3'b0};
                F_BLUE:      pixel_out <= {5'b0,dout[2:0]};
                F_YELLOW:    pixel_out <= {dout[7:3],3'b0};
                F_PURPLE:   pixel_out <= {dout[7:5],2'b0,dout[2:0]};
                F_CYAN:      pixel_out <= {3'b0,dout[4:0]};
                F_INVERT:    pixel_out <= ~dout;
                F_BLACK:     pixel_out <= 8'h00;
                F_WHITE:     pixel_out <= 8'hFF;
                default:     pixel_out <= dout;
            endcase
            ce[0] <= (dout != alpha);
            ce[1] <= (dout != alpha) && enemy;
            z <= (dout == alpha);
        end
    end
endcase
end
end

endmodule

```

blob_manager.v

Contains the blob manager module.

```

///////////
// blob_manager: Coordinates the GPU: listens to the GPU, issues commands
// to the blobs, stores screen coordinates and pass absolute (camera + screen)
// pixel values to the blobs.
//
///////////

```

```

module blob_manager(clk, reset, ctl, reg1, reg2, reg3, reg4, reg5, x_request,
                    y_request, pixel_x, pixel_y, x1_bus, y1_bus, x2_bus, y2_bus,
                    type_bus, mirror_bus, filter_bus, collidable_bus,
                    enemy_bus, layer_bus, id_bus, command_bus, bkg_pixel,
                    screen_x, screen_y);
    input clk, reset, ctl;
    input[31:0] reg1, reg2, reg3, reg4, reg5;
                input[9:0] x_request, y_request;

    output[31:0] pixel_x, pixel_y;
    output[31:0] x1_bus, y1_bus, x2_bus, y2_bus;
    output[6:0] type_bus;
    output collidable_bus, enemy_bus;
        output[1:0] mirror_bus;
        output[5:0] filter_bus;
    output[1:0] layer_bus;
    output[5:0] id_bus;
    output[3:0] command_bus;
    output[7:0] bkg_pixel;

    // debug
    output[31:0] screen_x, screen_y;

    reg[31:0] pixel_x, pixel_y;
    reg[31:0] x1_bus, y1_bus, x2_bus, y2_bus;
    reg[6:0] type_bus;
    reg collidable_bus, enemy_bus;
    reg[1:0] layer_bus;
    reg[5:0] id_bus;
    reg[3:0] command_bus;
    reg[7:0] bkg_pixel;
    reg[5:0] filter_bus;
    reg[1:0] mirror_bus;

    reg[31:0] screen_x, screen_y;

    parameter M_NEW_SPRITE          = 0;
    parameter M_NEW_BLOB            = 1;
    parameter M_NEW_TILED_SPRITE    = 2;
    parameter M_DESTROY_SPRITE     = 3;
    parameter M_MOVE_SPRITE        = 4;
    parameter M_SET_LAYER_CLIP_ENEMY = 5;
    parameter M_SET_FILTER          = 6;
    parameter M_SET_MIRROR          = 7;
    parameter M_SET_CAMERA          = 8;
    parameter M_SET_BACKGROUND      = 9;
    parameter M_SET_TYPE            = 10;

    parameter C_NOP                 = 0;
    parameter C_SET_POSITION        = 1;
    parameter C_SET_TYPE            = 2;
    parameter C_SET_LAYER_AND_CLIP  = 3;
    parameter C_SET_MIRROR          = 4;
    parameter C_CLEAN               = 5;
    parameter C_CREATE_BLOB         = 6;
    parameter C_CREATE_SPRITE       = 7;
    parameter C_CREATE_TILED_SPRITE = 8;
    parameter C_SET_FILTER          = 9;

    always @ (posedge clk) begin
        if (reset) begin
            bkg_pixel <= 0;

```

```

screen_x <= 0;
screen_y <= 0;
filter_bus <= 0;
command_bus <= C_NOP;
end

pixel_x <= screen_x + x_request;
pixel_y <= screen_y + y_request;

if (ctl) begin
    x1_bus <= 0;
    x2_bus <= 0;
    y1_bus <= 0;
    y2_bus <= 0;
    type_bus <= 0;
    collidable_bus <= 0;
    enemy_bus <= 0;
    layer_bus <= 0;
    id_bus <= 0;
    case (reg1[31:27])

        M_NEW_SPRITE:
        begin
            type_bus <= reg1[9:0];
            id_bus <= reg1[15:10];
            layer_bus <= reg1[17:16];
            collidable_bus <= reg1[18];
            enemy_bus <= reg1[19];
            x1_bus <= reg2;
            y1_bus <= reg3;
            command_bus <= C_CREATE_SPRITE;
        end

        M_NEW_BLOB:
        begin
            id_bus <= reg1[15:10];
            layer_bus <= reg1[17:16];
            collidable_bus <= 1;
            enemy_bus <= reg1[19];
            x1_bus <= reg2;
            y1_bus <= reg3;
            x2_bus <= reg4;
            y2_bus <= reg5;
            command_bus <= C_CREATE_BLOB;
        end

        M_NEW_TILED_SPRITE:
        begin
            type_bus <= reg1[9:0];
            id_bus <= reg1[15:10];
            layer_bus <= reg1[17:16];
            collidable_bus <= reg1[18];
            enemy_bus <= reg1[19];
            x1_bus <= reg2;
            y1_bus <= reg3;
            x2_bus <= reg4;
            y2_bus <= reg5;
            command_bus <= C_CREATE_TILED_SPRITE;
        end

        M_DESTROY_SPRITE:
        begin
            id_bus <= reg1[15:10];

```

```

        command_bus <= C_CLEAN;
    end

M_MOVE_SPRITE:
begin
    id_bus <= reg1[15:10];
    x1_bus <= reg2;
    y1_bus <= reg3;
    x2_bus <= reg4;
    y2_bus <= reg5;
    command_bus <= C_SET_POSITION;
end

M_SET_LAYER_CLIP_ENEMY:
begin
    layer_bus <= reg1[17:16];
    collidable_bus <= reg1[18];
    enemy_bus <= reg1[19];
    id_bus <= reg1[15:10];
    command_bus <= C_SET_LAYER_AND_CLIP;
end

M_SET_FILTER:
begin
    filter_bus <= reg1[5:0];
    id_bus <= reg1[15:10];
    command_bus <= C_SET_FILTER;
end

M_SET_MIRROR:
begin
    mirror_bus <= reg1[1:0];
    id_bus <= reg1[15:10];
    command_bus <= C_SET_MIRROR;
end

M_SET_CAMERA:
begin
    screen_x <= reg2;
    screen_y <= reg3;
    command_bus <= C_NOP;
end

M_SET_BACKGROUND:
begin
    bkg_pixel <= reg1[7:0];
    command_bus <= C_NOP;
end

M_SET_TYPE:
begin
    type_bus <= reg1[9:0];
    id_bus <= reg1[15:10];
    command_bus <= C_SET_TYPE;
end

default:
begin
    command_bus <= C_NOP;
end

endcase
end else begin           // If ctl is not asserted, send NOPs

```

```

        command_bus <= C_NOP;
    end
end

endmodule

```

sprite_manager.v

Contains the sprite manager module, a table for width, height, transparency color and initial address for every sprite on the ROM, and an auxiliary module to determine request priority.

```

///////////////////////////////
//
//      Sprite manager: accesses sprite ROM, writes information sequentially
// to blobs as request, using the blob's ID as priority.
//
///////////////////////////////

module sprite_manager(clk, reset, request, sprite_type, we, addr, din, alpha_bus,
h_bus, w_bus, target, index);
    input clk, reset;                                // clock and reset signals
    input[31:0] request;                            // request bits from all blobs
    input[223:0] sprite_type;                      // sprite types from all blobs

    output[31:0] we;                                // write enable bits for every blob
    output[7:0] din;                               // pixel data bus
    output[11:0] addr;                            // data address bus
    output[7:0] alpha_bus, h_bus, w_bus;           // transparency pixel, height and
                                                // width bus

    // debug signals
    output[5:0] index;
    output[5:0] target;

    reg[1:0] status;
    reg[5:0] target;
    reg[7:0] w, h;
    reg[15:0] position;
    reg[11:0] size, size_counter, addr;

    reg first_addr;

    reg[6:0] sprite_type_selected;
    reg[31:0] we;
    reg[7:0] alpha_bus, h_bus, w_bus;

    wire[7:0] w_wire, h_wire, alpha;
    wire[15:0] position_start;
    wire[5:0] index;

    parameter S_FREE          = 0;
    parameter S_GETTING_SIZE = 1;
    parameter S_LOADING       = 2;
    parameter S_RECHECK       = 3;

    sizes_rom srom(sprite_type_selected, w_wire, h_wire, alpha, position_start);
    sprites_rom sprom(position+size_counter, clk, din);
    smallest_index index_selector(request, index);

    always @ (posedge clk) begin

```

```

if (reset) begin
    status <= S_FREE;
    alpha_bus <= 0;
    w_bus <= 0;
    h_bus <= 0;
    position <= 0;
    size <= 0;
    size_counter <= 0;
    addr <= 0;
    w <= 0;
    h <= 0;
    we <= 0;
    target <= 0;
end

case (status)
S_FREE:
begin
    if (request != 0) begin
        status <= S_GETTING_SIZE;
        target <= index;
        we <= 1 << index;
        sprite_type_selected[0] <= sprite_type[7*target];
        sprite_type_selected[1] <= sprite_type[7*target+1];
        sprite_type_selected[2] <= sprite_type[7*target+2];
        sprite_type_selected[3] <= sprite_type[7*target+3];
        sprite_type_selected[4] <= sprite_type[7*target+4];
        sprite_type_selected[5] <= sprite_type[7*target+5];
        sprite_type_selected[6] <= sprite_type[7*target+6];
    end
end

S_GETTING_SIZE:
begin
    w_bus <= w_wire;
    h_bus <= h_wire;
    alpha_bus <= alpha;
    size <= w_wire*h_wire;
    size_counter <= 0;
    position <= position_start;
    first_addr <= 1;
    status <= S_LOADING;
end

S_LOADING:
begin
    if (size_counter == size) begin
        we <= 0;
        status <= S_RECHECK;
    end
    else if (first_addr) begin
        first_addr <= 0;
        addr <= 0;
    end
    else begin
        addr <= size_counter;
        size_counter <= size_counter+1;
    end
end

S_RECHECK:
begin
    if (request != 0) begin

```

```

        status <= S_GETTING_SIZE;
        target <= index;
        we <= 1 << index;
        sprite_type_selected[0] <= sprite_type[7*target];
        sprite_type_selected[1] <= sprite_type[7*target+1];
        sprite_type_selected[2] <= sprite_type[7*target+2];
        sprite_type_selected[3] <= sprite_type[7*target+3];
        sprite_type_selected[4] <= sprite_type[7*target+4];
        sprite_type_selected[5] <= sprite_type[7*target+5];
        sprite_type_selected[6] <= sprite_type[7*target+6];
    end
    else begin
        status <= S_FREE;
        position <= 0;
        target <= 0;
        we <= 0;
    end
end

default:
begin
    status <= S_FREE;
    position <= 0;
    target <= 0;
    we <= 0;
end
endcase
end

endmodule

///////////////////////////////
// Selects the smallest index that is 1 on a binary number
// ///////////////////////
module smallest_index(number, index);
    input[31:0] number;
    output[5:0] index;

    assign index = number[0] ? 0
        : number[1] ? 1
        : number[2] ? 2
        : number[3] ? 3
        : number[4] ? 4
        : number[5] ? 5
        : number[6] ? 6
        : number[7] ? 7
        : number[8] ? 8
        : number[9] ? 9
        : number[10] ? 10
        : number[11] ? 11
        : number[12] ? 12
        : number[13] ? 13
        : number[14] ? 14
        : number[15] ? 15
        : number[16] ? 16
        : number[17] ? 17
        : number[18] ? 18
        : number[19] ? 19
        : number[20] ? 20
        : number[21] ? 21

```

```

        : number[22] ? 22
        : number[23] ? 23
        : number[24] ? 24
        : number[25] ? 25
        : number[26] ? 26
        : number[27] ? 27
        : number[28] ? 28
        : number[29] ? 29
        : number[30] ? 30
        : 31;

endmodule

///////////////////////////////
// Small ROM with size and alpha information
// //////////////////////

module sizes_rom(sprite_type, w, h, alpha, position);
    input[6:0] sprite_type;
    output[7:0] w, h, alpha;
    output[15:0] position;

    reg[7:0] w, h, alpha;
    reg[15:0] position;

    always @(sprite_type) begin
        case (sprite_type)
            0:
            begin
                w      <= 19;
                h      <= 13;
                alpha  <= 8'h00;
                position <= 0;
            end

            1:
            begin
                w      <= 19;
                h      <= 13;
                alpha  <= 8'h00;
                position <= 247;
            end

            2:
            begin
                w      <= 19;
                h      <= 13;
                alpha  <= 8'h00;
                position <= 494;
            end

            3:
            begin
                w      <= 19;
                h      <= 13;
                alpha  <= 8'h00;
                position <= 741;
            end

            4:
            begin

```

```

        w      <= 19;
        h      <= 13;
        alpha <= 8'h00;
        position <= 988;
end

5:
begin
        w      <= 19;
        h      <= 13;
        alpha <= 8'h00;
        position <= 1235;
end

6:
begin
        w      <= 19;
        h      <= 13;
        alpha <= 8'h00;
        position <= 1482;
end

7:
begin
        w      <= 19;
        h      <= 13;
        alpha <= 8'h00;
        position <= 1729;
end

8:
begin
        w      <= 19;
        h      <= 13;
        alpha <= 8'h00;
        position <= 1796;
end

9:
begin
        w      <= 19;
        h      <= 13;
        alpha <= 8'h00;
        position <= 2223;
end

10: // :
begin
        w      <= 19;
        h      <= 13;
        alpha <= 8'h00;
        position <= 2470;
end

11: // heart 0
begin
        w      <= 13;
        h      <= 11;
        alpha <= 8'h00;
        position <= 2717;
end

12: // heart 1

```

```

begin
    w      <= 13;
    h      <= 11;
    alpha <= 8'h00;
    position <= 2860;
end

13: // heart 2
begin
    w      <= 13;
    h      <= 11;
    alpha <= 8'h00;
    position <= 3003;
end

14: // heart 3
begin
    w      <= 13;
    h      <= 11;
    alpha <= 8'h00;
    position <= 3146;
end

15: // heart 4
begin
    w      <= 13;
    h      <= 11;
    alpha <= 8'h00;
    position <= 3289;
end

16: // bml
begin
    w      <= 19;
    h      <= 26;
    alpha <= 8'h07;
    position <= 3432;
end

17: // bm2
begin
    w      <= 19;
    h      <= 26;
    alpha <= 8'h07;
    position <= 3926;
end

18: // bm_casting
begin
    w      <= 18;
    h      <= 26;
    alpha <= 8'h07;
    position <= 4420;
end

19: // bm_hurt
begin
    w      <= 19;
    h      <= 26;
    alpha <= 8'h07;
    position <= 4888;
end

```

```

20: // bm_dead
begin
    w      <= 26;
    h      <= 26;
    alpha <= 8'h07;
    position <= 5382;
end

21: // box
begin
    w      <= 16;
    h      <= 16;
    alpha <= 8'hFF;
    position <= 6058;
end

22: // brick
begin
    w      <= 16;
    h      <= 16;
    alpha <= 8'hE0;
    position <= 6314;
end

23: // red_rock
begin
    w      <= 16;
    h      <= 15;
    alpha <= 8'h07;
    position <= 6570;
end

24: // fire_1
begin
    w      <= 13;
    h      <= 15;
    alpha <= 8'h07;
    position <= 6810;
end

25: // fire_2
begin
    w      <= 13;
    h      <= 15;
    alpha <= 8'h07;
    position <= 7005;
end

26: // hadouken_start
begin
    w      <= 6;
    h      <= 46;
    alpha <= 8'h07;
    position <= 7200;
end

27: // hadouken_loop
begin
    w      <= 1;
    h      <= 46;
    alpha <= 8'h07;
    position <= 7476;
end

```

```

28: // arrow
begin
    w      <= 16;
    h      <= 26;
    alpha <= 8'h07;
    position <= 7522;
end

29: // archer
begin
    w      <= 25;
    h      <= 26;
    alpha <= 8'h07;
    position <= 7938;
end

30: // archer_firing
begin
    w      <= 25;
    h      <= 26;
    alpha <= 8'h07;
    position <= 8588;
end

31: // paladin
begin
    w      <= 20;
    h      <= 26;
    alpha <= 8'h07;
    position <= 9238;
end

32: // paladin_2
begin
    w      <= 20;
    h      <= 26;
    alpha <= 8'h07;
    position <= 9758;
end

// check: 10278 lines

default:
begin
    w      <= 0;
    h      <= 0;
    alpha <= 8'h00;
end
endcase
end

endmodule

```

pixel_tree.v

Contains the pixel tree module, with the collision OR logic.

```

///////////////////////////////
// pixel_tree: Produces the appropriate collision info and sprite color

```

```

//           from the 32 blob outputs.
//
// 4-stage pipelined.
//
// Uses a tree of pixel-combinators to select the appropriate pixel to display,
// if any, and send the inferences it can make about collisions on the current
// pixel position to the interrupt generator.
//
///////////////////////////////
module pixel_tree(clk, pixels, owners, z, layers, ce, pixel_out, collision,
ecollision, bkg_pixel);

    input clk;

    input[255:0] pixels;
    input[223:0] owners;
    input[63:0] layers;
    input[63:0] ce;
    input[31:0] z;
    input[7:0] bkg_pixel;

    output[7:0] pixel_out;
    output[31:0] collision, ecollision;

    wire[63:0] pixel_a;
    wire[55:0] owner_a;
    wire[15:0] layer_a;
    wire[15:0] cea;
    wire[31:0] ca, eca;
    wire[7:0] za;

    wire[15:0] pixel_b;
    wire[13:0] owner_b;
    wire[3:0] layer_b;
    wire[3:0] ceb;
    wire[7:0] cb, ecb;
    wire[1:0] zb;

    wire[7:0] pixel_c;
    wire[6:0] owner_c;
    wire[1:0] layer_c;
    wire[1:0] cec;
    wire[3:0] cc, ecc;
    wire zc;

    wire[31:0] c, e;

    reg[63:0] pixel_areg;
    reg[55:0] owner_areg;
    reg[15:0] layer_areg;
    reg[15:0] ceareg;
    reg[31:0] careg, ecareg;
    reg[7:0] za_reg;

    reg[55:0] owner_a2reg;
    reg[31:0] ca2reg, eca2reg;

    reg[55:0] owner_a3reg;
    reg[31:0] ca3reg, eca3reg;

    reg[15:0] pixel_breg;
    reg[13:0] owner_breg;

```

```

reg[3:0] layer_breg;
reg[3:0] cebreg;
reg[7:0] cbreg, ecbreg;
reg[1:0] zb_reg;

reg[13:0] owner_b2reg;
reg[7:0] cb2reg, ecb2reg;

reg[6:0] owner_creg;
reg[1:0] cecreg;
reg[1:0] ccreg, eccreg;

reg[31:0] collision_reg, ecollision_reg;
reg[7:0] pixel_out_reg, pixel_out;

assign collision = collision_reg;
assign ecollision = ecollision_reg;

// pixel combinator tree

// layer 1
pixel_combinator a1(clk, pixels[7:0], pixels[15:8], pixels[23:16],
                     pixels[31:24], z[0], z[1], z[2], z[3],
                     owners[6:0], owners[13:7], owners[20:14], owners[27:21],
                     layers[1:0], layers[3:2], layers[5:4], layers[7:6],
                     ce[1:0], ce[3:2], ce[5:4], ce[7:6],
                     pixel_a[7:0], layer_a[1:0], owner_a[6:0], cea[1:0], za[0],
                     ca[0], ca[1], ca[2], ca[3],
                     eca[0], eca[1], eca[2], eca[3]);

pixel_combinator a2(clk, pixels[39:32], pixels[47:40], pixels[55:48],
                     pixels[63:56], z[4], z[5], z[6], z[7],
                     owners[34:28], owners[41:35], owners[48:42], owners[55:49],
                     layers[9:8], layers[11:10], layers[13:12], layers[15:14],
                     ce[9:8], ce[11:10], ce[13:12], ce[15:14],
                     pixel_a[15:8], layer_a[3:2], owner_a[13:7], cea[3:2],
                     za[1], ca[4], ca[5], ca[6], ca[7],
                     eca[4], eca[5], eca[6], eca[7]);

pixel_combinator a3(clk, pixels[71:64], pixels[79:72], pixels[87:80],
                     pixels[95:88], z[8], z[9], z[10], z[11],
                     owners[62:56], owners[69:63], owners[76:70], owners[83:77],
                     layers[17:16], layers[19:18], layers[21:20], layers[23:22],
                     ce[17:16], ce[19:18], ce[21:20], ce[23:22],
                     pixel_a[23:16], layer_a[5:4], owner_a[20:14], cea[5:4],
                     za[2], ca[8], ca[9], ca[10], ca[11],
                     eca[8], eca[9], eca[10], eca[11]);

pixel_combinator a4(clk, pixels[103:96], pixels[111:104], pixels[119:112],
                     pixels[127:120], z[12], z[13], z[14], z[15],
                     owners[90:84], owners[97:91], owners[104:98],
                     owners[111:105],
                     layers[25:24], layers[27:26], layers[29:28], layers[31:30],
                     ce[25:24], ce[27:26], ce[29:28], ce[31:30],
                     pixel_a[31:24], layer_a[7:6], owner_a[27:21], cea[7:6],
                     za[3], ca[12], ca[13], ca[14], ca[15],
                     eca[12], eca[13], eca[14], eca[15]);

pixel_combinator a5(clk, pixels[135:128], pixels[143:136], pixels[151:144],
                     pixels[159:152], z[16], z[17], z[18], z[19],
                     owners[118:112], owners[125:119], owners[132:126],
                     owners[139:133],
                     layers[33:32], layers[35:34], layers[37:36], layers[39:38],

```

```

        ce[33:32], ce[35:34], ce[37:36], ce[39:38],
        pixel_a[39:32], layer_a[9:8], owner_a[34:28], cea[9:8],
        za[4], ca[16], ca[17], ca[18], ca[19],
        eca[16], eca[17], eca[18], eca[19]);
```

```

pixel_combinator a6(clk, pixels[167:160], pixels[175:168], pixels[183:176],
                     pixels[191:184], z[20], z[21], z[22], z[23],
                     owners[146:140], owners[153:147], owners[160:154],
                     owners[167:161], layers[41:40], layers[43:42],
                     layers[45:44], layers[47:46],
                     ce[41:40], ce[43:42], ce[45:44], ce[47:46],
                     pixel_a[47:40], layer_a[11:10], owner_a[41:35], cea[11:10],
                     za[5], ca[20], ca[21], ca[22], ca[23],
                     eca[20], eca[21], eca[22], eca[23]);
```

```

pixel_combinator a7(clk, pixels[199:192], pixels[207:200], pixels[215:208],
                     pixels[223:216], z[24], z[25], z[26], z[27],
                     owners[174:168], owners[181:175], owners[188:182],
                     owners[195:189],
                     layers[49:48], layers[51:50], layers[53:52], layers[55:54],
                     ce[49:48], ce[51:50], ce[53:52], ce[55:54],
                     pixel_a[55:48], layer_a[13:12], owner_a[48:42], cea[13:12],
                     za[6], ca[24], ca[25], ca[26], ca[27],
                     eca[24], eca[25], eca[26], eca[27]);
```

```

pixel_combinator a8(clk, pixels[231:224], pixels[239:232], pixels[247:240],
                     pixels[255:248],
                     z[28], z[29], z[30], z[31],
                     owners[202:196], owners[209:203], owners[216:210],
                     owners[223:217],
                     layers[57:56], layers[59:58], layers[61:60], layers[63:62],
                     ce[57:56], ce[59:58], ce[61:60], ce[63:62],
                     pixel_a[63:56], layer_a[15:14], owner_a[55:49], cea[15:14],
                     za[7], ca[28], ca[29], ca[30], ca[31],
                     eca[28], eca[29], eca[30], eca[31]);
```

```
// layer 2
```

```

pixel_combinator b1(clk, pixel_a[7:0], pixel_a[15:8], pixel_a[23:16],
                     pixel_a[31:24],
                     za[0], za[1], za[2], za[3],
                     owner_a[6:0], owner_a[13:7], owner_a[20:14],
                     owner_a[27:21],
                     layer_a[1:0], layer_a[3:2], layer_a[5:4], layer_a[7:6],
                     cea[1:0], cea[3:2], cea[5:4], cea[7:6],
                     pixel_b[7:0], layer_b[1:0], owner_b[6:0], ceb[1:0], zb[0],
                     cb[0], cb[1], cb[2], cb[3],
                     ecb[0], ecb[1], ecb[2], ecb[3]);
```

```

pixel_combinator b2(clk, pixel_a[39:32], pixel_a[47:40], pixel_a[55:48],
                     pixel_a[63:56], za[4], za[5], za[6], za[7],
                     owner_a[34:28], owner_a[41:35], owner_a[48:42],
                     owner_a[55:49],
                     layer_a[9:8], layer_a[11:10], layer_a[13:12],
                     layer_a[15:14],
                     cea[9:8], cea[11:10], cea[13:12], cea[15:14],
                     pixel_b[15:8], layer_b[3:2], owner_b[13:7], ceb[3:2],
                     zb[1], cb[4], cb[5], cb[6], cb[7],
                     ecb[4], ecb[5], ecb[6], ecb[7]);
```

```
// layer 3
```

```

pixel_combinator c1(clk, pixel_b[7:0], pixel_b[15:8], 8'b0, 8'b0,
                     zb[0], zb[1], 1'b1, 1'b1,
                     owner_b[6:0], owner_b[13:7], 7'b0, 7'b0,
```

```

        layer_b[1:0], layer_b[3:2], 2'b0, 2'b0,
        ceb[1:0], ceb[3:2], 2'b0, 2'b0,
        pixel_c[7:0], layer_c[1:0], owner_c[6:0], cec[1:0], zc,
        cc[0], cc[1], cc[2], cc[3],
        ecc[0], ecc[1], ecc[2], ecc[3]);;

// collision OR

// collision:
assign c[0] = ca3reg[0] | ((owner_a3reg[6:0] == 0) & cb2reg[0]) |
((owner_b2reg[6:0] == 0) & ccreg[0]);
assign c[1] = ca3reg[1] | ((owner_a3reg[6:0] == 1) & cb2reg[0]) |
((owner_b2reg[6:0] == 1) & ccreg[0]);
assign c[2] = ca3reg[2] | ((owner_a3reg[6:0] == 2) & cb2reg[0]) |
((owner_b2reg[6:0] == 2) & ccreg[0]);
assign c[3] = ca3reg[3] | ((owner_a3reg[6:0] == 3) & cb2reg[0]) |
((owner_b2reg[6:0] == 3) & ccreg[0]);

assign c[4] = ca3reg[4] | ((owner_a3reg[13:7] == 4) & cb2reg[1]) |
((owner_b2reg[6:0] == 4) & ccreg[0]);
assign c[5] = ca3reg[5] | ((owner_a3reg[13:7] == 5) & cb2reg[1]) |
((owner_b2reg[6:0] == 5) & ccreg[0]);
assign c[6] = ca3reg[6] | ((owner_a3reg[13:7] == 6) & cb2reg[1]) |
((owner_b2reg[6:0] == 6) & ccreg[0]);
assign c[7] = ca3reg[7] | ((owner_a3reg[13:7] == 7) & cb2reg[1]) |
((owner_b2reg[6:0] == 7) & ccreg[0]);

assign c[8] = ca3reg[8] | ((owner_a3reg[20:14] == 8) & cb2reg[2]) |
((owner_b2reg[6:0] == 0) & ccreg[0]);
assign c[9] = ca3reg[9] | ((owner_a3reg[20:14] == 9) & cb2reg[2]) |
((owner_b2reg[6:0] == 1) & ccreg[0]);
assign c[10] = ca3reg[10] | ((owner_a3reg[20:14] == 10) & cb2reg[2]) |
((owner_b2reg[6:0] == 2) & ccreg[0]);
assign c[11] = ca3reg[11] | ((owner_a3reg[20:14] == 11) & cb2reg[2]) |
((owner_b2reg[6:0] == 3) & ccreg[0]);

assign c[12] = ca3reg[12] | ((owner_a3reg[27:21] == 12) & cb2reg[3]) |
((owner_b2reg[6:0] == 4) & ccreg[0]);
assign c[13] = ca3reg[13] | ((owner_a3reg[27:21] == 13) & cb2reg[3]) |
((owner_b2reg[6:0] == 5) & ccreg[0]);
assign c[14] = ca3reg[14] | ((owner_a3reg[27:21] == 14) & cb2reg[3]) |
((owner_b2reg[6:0] == 6) & ccreg[0]);
assign c[15] = ca3reg[15] | ((owner_a3reg[27:21] == 15) & cb2reg[3]) |
((owner_b2reg[6:0] == 7) & ccreg[0]);

assign c[16] = ca3reg[16] | ((owner_a3reg[34:28] == 16) & cb2reg[4]) |
((owner_b2reg[13:7] == 16) & ccreg[1]);
assign c[17] = ca3reg[17] | ((owner_a3reg[34:28] == 17) & cb2reg[4]) |
((owner_b2reg[13:7] == 17) & ccreg[1]);
assign c[18] = ca3reg[18] | ((owner_a3reg[34:28] == 18) & cb2reg[4]) |
((owner_b2reg[13:7] == 18) & ccreg[1]);
assign c[19] = ca3reg[19] | ((owner_a3reg[34:28] == 19) & cb2reg[4]) |
((owner_b2reg[13:7] == 19) & ccreg[1]);

assign c[20] = ca3reg[20] | ((owner_a3reg[41:35] == 20) & cb2reg[5]) |
((owner_b2reg[13:7] == 20) & ccreg[1]);
assign c[21] = ca3reg[21] | ((owner_a3reg[41:35] == 21) & cb2reg[5]) |
((owner_b2reg[13:7] == 21) & ccreg[1]);
assign c[22] = ca3reg[22] | ((owner_a3reg[41:35] == 22) & cb2reg[5]) |
((owner_b2reg[13:7] == 22) & ccreg[1]);
assign c[23] = ca3reg[23] | ((owner_a3reg[41:35] == 23) & cb2reg[5]) |
((owner_b2reg[13:7] == 23) & ccreg[1]);

```

```

    assign c[24] = ca3reg[24] | ((owner_a3reg[48:42] == 24) & cb2reg[6]) |
((owner_b2reg[13:7] == 24) & ccreg[1]);
    assign c[25] = ca3reg[25] | ((owner_a3reg[48:42] == 25) & cb2reg[6]) |
((owner_b2reg[13:7] == 25) & ccreg[1]);
    assign c[26] = ca3reg[26] | ((owner_a3reg[48:42] == 26) & cb2reg[6]) |
((owner_b2reg[13:7] == 26) & ccreg[1]);
    assign c[27] = ca3reg[27] | ((owner_a3reg[48:42] == 27) & cb2reg[6]) |
((owner_b2reg[13:7] == 27) & ccreg[1]);

    assign c[28] = ca3reg[28] | ((owner_a3reg[55:49] == 28) & cb2reg[7]) |
((owner_b2reg[13:7] == 28) & ccreg[1]);
    assign c[29] = ca3reg[29] | ((owner_a3reg[55:49] == 29) & cb2reg[7]) |
((owner_b2reg[13:7] == 29) & ccreg[1]);
    assign c[30] = ca3reg[30] | ((owner_a3reg[55:49] == 30) & cb2reg[7]) |
((owner_b2reg[13:7] == 30) & ccreg[1]);
    assign c[31] = ca3reg[31] | ((owner_a3reg[55:49] == 31) & cb2reg[7]) |
((owner_b2reg[13:7] == 31) & ccreg[1]);

// enemy:
    assign e[0] = eca3reg[0] | ((owner_a3reg[6:0] == 0) & ecb2reg[0]) |
((owner_b2reg[6:0] == 0) & eccreg[0]);
    assign e[1] = eca3reg[1] | ((owner_a3reg[6:0] == 1) & ecb2reg[0]) |
((owner_b2reg[6:0] == 1) & eccreg[0]);
    assign e[2] = eca3reg[2] | ((owner_a3reg[6:0] == 2) & ecb2reg[0]) |
((owner_b2reg[6:0] == 2) & eccreg[0]);
    assign e[3] = eca3reg[3] | ((owner_a3reg[6:0] == 3) & ecb2reg[0]) |
((owner_b2reg[6:0] == 3) & eccreg[0]);

    assign e[4] = eca3reg[4] | ((owner_a3reg[13:7] == 4) & ecb2reg[1]) |
((owner_b2reg[6:0] == 4) & eccreg[0]);
    assign e[5] = eca3reg[5] | ((owner_a3reg[13:7] == 5) & ecb2reg[1]) |
((owner_b2reg[6:0] == 5) & eccreg[0]);
    assign e[6] = eca3reg[6] | ((owner_a3reg[13:7] == 6) & ecb2reg[1]) |
((owner_b2reg[6:0] == 6) & eccreg[0]);
    assign e[7] = eca3reg[7] | ((owner_a3reg[13:7] == 7) & ecb2reg[1]) |
((owner_b2reg[6:0] == 7) & eccreg[0]);

    assign e[8] = eca3reg[8] | ((owner_a3reg[20:14] == 8) & ecb2reg[2]) |
((owner_b2reg[6:0] == 0) & eccreg[0]);
    assign e[9] = eca3reg[9] | ((owner_a3reg[20:14] == 9) & ecb2reg[2]) |
((owner_b2reg[6:0] == 1) & eccreg[0]);
    assign e[10] = eca3reg[10] | ((owner_a3reg[20:14] == 10) & ecb2reg[2]) |
((owner_b2reg[6:0] == 2) & eccreg[0]);
    assign e[11] = eca3reg[11] | ((owner_a3reg[20:14] == 11) & ecb2reg[2]) |
((owner_b2reg[6:0] == 3) & eccreg[0]);

    assign e[12] = eca3reg[12] | ((owner_a3reg[27:21] == 12) & ecb2reg[3]) |
((owner_b2reg[6:0] == 4) & eccreg[0]);
    assign e[13] = eca3reg[13] | ((owner_a3reg[27:21] == 13) & ecb2reg[3]) |
((owner_b2reg[6:0] == 5) & eccreg[0]);
    assign e[14] = eca3reg[14] | ((owner_a3reg[27:21] == 14) & ecb2reg[3]) |
((owner_b2reg[6:0] == 6) & eccreg[0]);
    assign e[15] = eca3reg[15] | ((owner_a3reg[27:21] == 15) & ecb2reg[3]) |
((owner_b2reg[6:0] == 7) & eccreg[0]);

    assign e[16] = eca3reg[16] | ((owner_a3reg[34:28] == 16) & ecb2reg[4]) |
((owner_b2reg[13:7] == 16) & eccreg[1]);
    assign e[17] = eca3reg[17] | ((owner_a3reg[34:28] == 17) & ecb2reg[4]) |
((owner_b2reg[13:7] == 17) & eccreg[1]);
    assign e[18] = eca3reg[18] | ((owner_a3reg[34:28] == 18) & ecb2reg[4]) |
((owner_b2reg[13:7] == 18) & eccreg[1]);
    assign e[19] = eca3reg[19] | ((owner_a3reg[34:28] == 19) & ecb2reg[4]) |
((owner_b2reg[13:7] == 19) & eccreg[1]);

```

```

    assign e[20] = eca3reg[20] | ((owner_a3reg[41:35] == 20) & ecb2reg[5]) |
((owner_b2reg[13:7] == 20) & eccreg[1]);
    assign e[21] = eca3reg[21] | ((owner_a3reg[41:35] == 21) & ecb2reg[5]) |
((owner_b2reg[13:7] == 21) & eccreg[1]);
    assign e[22] = eca3reg[22] | ((owner_a3reg[41:35] == 22) & ecb2reg[5]) |
((owner_b2reg[13:7] == 22) & eccreg[1]);
    assign e[23] = eca3reg[23] | ((owner_a3reg[41:35] == 23) & ecb2reg[5]) |
((owner_b2reg[13:7] == 23) & eccreg[1]);

    assign e[24] = eca3reg[24] | ((owner_a3reg[48:42] == 24) & ecb2reg[6]) |
((owner_b2reg[13:7] == 24) & eccreg[1]);
    assign e[25] = eca3reg[25] | ((owner_a3reg[48:42] == 25) & ecb2reg[6]) |
((owner_b2reg[13:7] == 25) & eccreg[1]);
    assign e[26] = eca3reg[26] | ((owner_a3reg[48:42] == 26) & ecb2reg[6]) |
((owner_b2reg[13:7] == 26) & eccreg[1]);
    assign e[27] = eca3reg[27] | ((owner_a3reg[48:42] == 27) & ecb2reg[6]) |
((owner_b2reg[13:7] == 27) & eccreg[1]);

    assign e[28] = eca3reg[28] | ((owner_a3reg[55:49] == 28) & ecb2reg[7]) |
((owner_b2reg[13:7] == 28) & eccreg[1]);
    assign e[29] = eca3reg[29] | ((owner_a3reg[55:49] == 29) & ecb2reg[7]) |
((owner_b2reg[13:7] == 29) & eccreg[1]);
    assign e[30] = eca3reg[30] | ((owner_a3reg[55:49] == 30) & ecb2reg[7]) |
((owner_b2reg[13:7] == 30) & eccreg[1]);
    assign e[31] = eca3reg[31] | ((owner_a3reg[55:49] == 31) & ecb2reg[7]) |
((owner_b2reg[13:7] == 31) & eccreg[1]);

// pipeline
always @ (posedge clk) begin
    pixel_areg <= pixel_a;
    owner_areg <= owner_a;
    layer_areg <= layer_a;
    ceareg <= cea;
    careg <= ca;
    ecareg <= eca;
    za_reg <= za;

    owner_a2reg <= owner_areg;
    ca2reg <= careg;
    eca2reg <= ecareg;

    owner_a3reg <= owner_a2reg;
    ca3reg <= ca2reg;
    eca3reg <= eca2reg;

    pixel_breg <= pixel_b;
    owner_breg <= owner_b;
    layer_breg <= layer_b;
    cebreg <= ceb;
    cbreg <= cb;
    ecbreg <= ecb;
    zb_reg <= zb;

    owner_b2reg <= owner_breg;
    cb2reg <= cbreg;
    ecb2reg <= ecbreg;

    owner_creg <= owner_c;
    cecreg <= cec;
    ccreg <= cc;
    eccreg <= ecc;

```

```

    collision_reg <= c;
    ecollision_reg <= e;

    pixel_out <= zc ? bkg_pixel : pixel_c;
end

endmodule

```

pixel_combinator.v

Contains the pixel combinator module, and a module to select the smallest from 4 inputs and point its index.

```

///////////////////////////////
//
// pixel_combinator: Selects the appropriate pixel and sprite info from 4 inputs
//
// pixel1, pixel2, pixel3, pixel4: 4 8-bit pixel values
// z1, z2, z3, z4: whether the pixels should be considered transparent
// owner1, owner2, owner3, owner4: ID of blob responsible for the pixel
// layer1, layer2, lauye3, layer4: pixel layer (2-bit)
// cel, ce2, ce3, ce4: {enemy, collision} bit information
// pixel_out: selected pixel output
// layer_out: selected layer output
// ce_out: combined ce output
// z_out: whether the output is transparent
// conflict1, conflict2, conflict3, conflict4: collision information output for
// each pixel
// econflict1, econflict2, econflict3, econflict4: enemy collision information
// for each pixel
//
///////////////////////////////

module pixel_combinator(clk, pixel1, pixel2, pixel3, pixel4, z1, z2, z3, z4,
                        owner1, owner2, owner3, owner4,
                        layer1, layer2, layer3, layer4,
                        cel, ce2, ce3, ce4,
                        pixel_out, layer_out, owner_out, ce_out, z_out,
                        conflict1, conflict2, conflict3, conflict4,
                        econflict1, econflict2, econflict3, econflict4);

    input clk;
    input[7:0] pixel1, pixel2, pixel3, pixel4;
    input[6:0] owner1, owner2, owner3, owner4;
    input[1:0] layer1, layer2, layer3, layer4;
    input[1:0] cel, ce2, ce3, ce4;
    input z1, z2, z3, z4;

    output[7:0] pixel_out;
    output[1:0] layer_out;
    output[1:0] ce_out;
    output[6:0] owner_out;
    output z_out;
    output conflict1, conflict2, conflict3, conflict4;
    output econflict1, econflict2, econflict3, econflict4;

    wire en1, en2, en3, en4, o1, o2, o3, o4, c1, c2, c3, c4, e1, e2, e3, e4;
    wire[1:0] win_id;
    wire[1:0] alayer1, alayer2, alayer3, alayer4;

    assign en1 = ~z1;

```

```

assign en2 = ~z2;
assign en3 = ~z3;
assign en4 = ~z4;

assign alayer1 = en1 ? layer1 : 3;
assign alayer2 = en2 ? layer2 : 3;
assign alayer3 = en3 ? layer3 : 3;
assign alayer4 = en4 ? layer4 : 3;

min4 layer_selector(alayer1, alayer2, alayer3, alayer4, layer_out, win_id);

assign o1 = (en2 | en3 | en4);
assign o2 = (en1 | en3 | en4);
assign o3 = (en1 | en2 | en4);
assign o4 = (en1 | en2 | en3);

assign c1 = ce2[0] | ce3[0] | ce4[0];
assign c2 = ce1[0] | ce3[0] | ce4[0];
assign c3 = ce1[0] | ce2[0] | ce4[0];
assign c4 = ce1[0] | ce2[0] | ce3[0];

assign e1 = ce2[1] | ce3[1] | ce4[1];
assign e2 = ce1[1] | ce3[1] | ce4[1];
assign e3 = ce1[1] | ce2[1] | ce4[1];
assign e4 = ce1[1] | ce2[1] | ce3[1];

reg pixel_out;
reg owner_out;
reg z_out, ce_out;
reg conflict1, conflict2, conflict3, conflict4;
reg econflict1, econflict2, econflict3, econflict4;

always @ (posedge clk) begin
    pixel_out <= win_id == 3 ? pixel4 : win_id == 2 ? pixel3
                                : win_id == 1 ? pixel2 : pixel1;
    owner_out <= win_id == 3 ? owner4 : win_id == 2 ? owner3
                                : win_id == 1 ? owner2 : owner1;
    z_out <= z1 & z2 & z3 & z4;
    ce_out <= ce1 | ce2 | ce3 | ce4;

    conflict1 <= o1 & ce1[0] ? c1 : 0;
    conflict2 <= o2 & ce2[0] ? c2 : 0;
    conflict3 <= o3 & ce3[0] ? c3 : 0;
    conflict4 <= o4 & ce4[0] ? c4 : 0;

    econflict1 <= o1 & ce1[0] ? e1 : 0;
    econflict2 <= o2 & ce2[0] ? e2 : 0;
    econflict3 <= o3 & ce3[0] ? e3 : 0;
    econflict4 <= o4 & ce4[0] ? e4 : 0;
end

endmodule

///////////////////////////////
// min4: Produces the minimum value and the minimum index from 4 2-bit values.
// /////////////////////////
module min4(c1, c2, c3, c4, win, win_id);

input[1:0] c1, c2, c3, c4;

```

```

output[1:0] win, win_id;

wire[1:0] w1, w2, wid1, wid2;

assign w1 = (c4 < c3 ? c4 : c3);
assign wid1 = (c4 < c3 ? 3 : 2);

assign w2 = (c2 < c1 ? c2 : c1);
assign wid2 = (c2 < c1 ? 1 : 0);

assign win = (w2 < w1? w2 : w1);
assign win_id = (w2 < w1? wid2 : wid1);

endmodule

```

interrupt_generator.v

Contains the interrupt generator module.

```

///////////////////////////////
//
// interrupt_generator: module responsible for sending interrupts to CPU
//
// The beta just ignores interrupts while on supervisor mode (pc31 = 1), so
// we need to watch it and queue the requests as needed. This module contains
// a 16-word FIFO to queue the requests; it sends IRQs to the beta on every
// cycle it is not on supervisor mode, emptying the queue. As such, it is usually
// improbable to have more than 3 or 4 requests at the queue at any time.
// If the queue overflows, the extra requests are ignored.
//
// Since collision between two sprites cannot be inferred from one pixel alone,
// this module collects the current collision information on a register used as a
// buffer, and ORs it with the new input at every clock cycle. After iteration
// through one screen, it then compares with a previous value to determine
// whether the collision status changed for any sprite; if so, it queues up the
// appropriate interrupt.
//
// Note that this mechanism for collision detection implies that no off-screen
// collisions are detected. For most games this is projected for, collisions are
// not a matter out of the screen.
//
///////////////////////////////

module interrupt_generator(clk, reset, collision, ecollision, up, down, left,
                         right, enter, b1, b2, b3, irq, xaddr, hwwe, pc31);

    input clk, reset, pc31;                                // clock, reset and
                                                            // supervisor bit signals
    input[31:0] collision, ecollision;                    // collision inferences for
                                                            // the current pixel
    input up, down, left, right, enter, b1, b2, b3;       // signals determining
                                                            // whether the buttons are
                                                            // pressed

    output irq;                                         // the interrupt request signal itself
    output[4:0] xaddr;                                    // address to jump to, without the 2 last bits (00)
    output hwwe;                                       // whether to record the collision info to the memory

    reg[31:0] c_reg, ec_reg, c_buf, ec_buf;
    reg irq_internal, wr, hwwe, rd;
    reg[4:0] din, xaddr;

```

```

reg up_reg, down_reg, left_reg, right_reg, enter_reg, b1_reg, b2_reg, b3_reg;
reg[18:0] counter;

wire[4:0] dout;
    wire irq, empty;

assign irq = irq_internal & !empty;

fifo irq_fifo (clk, reset, din, wr, full, dout, rd, empty, overflow);
defparam irq_fifo.LOGSIZE = 4;
defparam irq_fifo.WIDTH = 5;

parameter I_CLOCK      = 2;
parameter I_ECOLLISION = 3;
parameter I_COLLISION  = 4;
parameter I_UP_PRESS   = 5;
parameter I_DOWN_PRESS = 6;
parameter I_LEFT_PRESS = 7;
parameter I_RIGHT_PRESS = 8;
parameter I_ENTER_PRESS = 9;
parameter I_B1_PRESS   = 10;
parameter I_B2_PRESS   = 11;
parameter I_B3_PRESS   = 12;
parameter I_UP_RELEASE = 13;
parameter I_DOWN_RELEASE = 14;
parameter I_LEFT_RELEASE = 15;
parameter I_RIGHT_RELEASE = 16;
parameter I_ENTER_RELEASE = 17;
parameter I_B1_RELEASE = 18;
parameter I_B2_RELEASE = 19;
parameter I_B3_RELEASE = 20;

parameter CYCLES = 480000 - 1;

always @(posedge clk) begin

    if (reset) begin
        hwwe <= 0;
        wr <= 0;
        rd <= 0;
        din <= 0;
        c_reg <= 0;
        ec_reg <= 0;
        up_reg <= 0;
        down_reg <= 0;
        left_reg <= 0;
        right_reg <= 0;
        enter_reg <= 0;
        b1_reg <= 0;
        b2_reg <= 0;
        b3_reg <= 0;
        c_buf <= 0;
        ec_buf <= 0;
        irq_internal <= 0;
        counter <= 0;
    end

    if (counter == CYCLES) begin
        counter <= 0;
        din <= I_CLOCK;
        wr <= 1;
    end

```

```

    c_buf <= c_buf | collision;
    ec_buf <= ec_buf | ecollision;
end
else if (counter == CYCLES - 1) begin
    counter <= counter+1;
    c_buf <= c_buf | collision;
    if (ec_buf != ec_reg) begin
        din <= I_ECOLLISION;
        wr <= 1;
        ec_reg <= ec_buf;
        ec_buf <= 0;
    end
end
else if (counter == CYCLES - 2) begin
    counter <= counter+1;
    ec_buf <= ec_buf | ecollision;
    if (c_buf != c_reg) begin
        din <= I_COLLISION;
        wr <= 1;
        c_reg <= collision;
        c_buf <= 0;
    end
end
else begin
    counter <= counter+1;
    c_buf <= c_buf | collision;
    ec_buf <= ec_buf | ecollision;

    if (up != up_reg) begin
        din <= up ? I_UP_PRESS : I_UP_RELEASE;
        wr <= 1;
        up_reg <= up;
    end

    else if (down != down_reg) begin
        din <= down ? I_DOWN_PRESS : I_DOWN_RELEASE;
        wr <= 1;
        down_reg <= down;
    end

    else if (left != left_reg) begin
        din <= left ? I_LEFT_PRESS : I_LEFT_RELEASE;
        wr <= 1;
        left_reg <= left;
    end

    else if (right != right_reg) begin
        din <= right ? I_RIGHT_PRESS : I_RIGHT_RELEASE;
        wr <= 1;
        right_reg <= right;
    end

    else if (enter != enter) begin
        din <= enter ? I_ENTER_PRESS : I_ENTER_RELEASE;
        wr <= 1;
        enter_reg <= enter;
    end

    else if (b1 != b1_reg) begin
        din <= b1 ? I_B1_PRESS : I_B1_RELEASE;
        wr <= 1;
        b1_reg <= b1;
    end

```

```

        else if (b2 != b2_reg) begin
            din <= b2 ? I_B2_PRESS : I_B2_RELEASE;
            wr <= 1;
            b2_reg <= b2;
        end

        else if (b3 != b3_reg) begin
            din <= b3 ? I_B3_PRESS : I_B3_RELEASE;
            wr <= 1;
            b3_reg <= b3;
        end

        else begin
            wr <= 0;
            din <= 0;
        end
    end

    if (!pc31 && !empty) begin
        irq_internal <= 1;
        xaddr <= dout;
        rd <= 1;
        hwwe <= (dout == I_COLLISION) || (dout == I_ECOLLISION);
    end
    else begin
        irq_internal <= 0;
        xaddr <= 0;
        rd <= 0;
    end
end

endmodule

```

fifo.v

Contains the first-in, first-out memory module provided in lecture.

```

// a simple synchronous FIFO (first-in first-out) buffer
// Parameters:
//    LOGSIZE  (parameter) FIFO has 1<<LOGSIZE elements
//    WIDTH    (parameter) each element has WIDTH bits
// Ports:
//    clk      (input) all actions triggered on rising edge
//    reset   (input) synchronously empties fifo
//    din     (input, WIDTH bits) data to be stored
//    wr      (input) when asserted, store new data
//    full    (output) asserted when FIFO is full
//    dout    (output, WIDTH bits) data read from FIFO
//    rd      (input) when asserted, removes first element
//    empty   (output) asserted when fifo is empty
//    overflow (output) asserted when WR but no room, cleared on next RD
module fifo(clk,reset,din,wr,full,dout,rd,empty,overflow);
    parameter LOGSIZE = 2;    // default size is 4 elements
    parameter WIDTH = 4;      // default width is 4 bits

    parameter SIZE = 1 << LOGSIZE; // compute size

    input clk,reset,rd,wr;
    input [WIDTH-1:0] din;

```

```

output [WIDTH-1:0] dout;
output full,empty,overflow;

reg [WIDTH-1:0] fifo[SIZE-1:0];      // fifo data stored here
reg overflow;                      // true if WR but no room, cleared on RD
reg [LOGSIZE-1:0] wptr,rptr;        // fifo write and read pointers

wire [LOGSIZE-1:0] wptr_inc = wptr + 1;

assign empty = (wptr == rptr);
assign full = (wptr_inc == rptr);
assign dout = fifo[rptr];

always @ (posedge clk) begin
    if (reset) begin
        wptr <= 0;
        rptr <= 0;
        overflow <= 0;
    end
    else if (wr) begin
        // store new data into the fifo
        fifo[wptr] <= din;
        wptr <= wptr_inc;
        overflow <= overflow | (wptr_inc == rptr);
    end
    // bump read pointer if we're done with current value.
    // RD also resets the overflow indicator
    if (rd && (!empty || overflow)) begin
        rptr <= rptr + 1;
        overflow <= 0;
    end
end
endmodule

```

Appendix B: Bsim macros

beta.uasm

Macros, abstractions and conventions for the main RAM file.

```
|||||||||||||||||||||||||||||||||||||||||||
||| 6.004 BETA Macro package -           3/10/94 SAW |||
||| This version defines our 32-bit Alpha-like RISC.    |||
|||||||||||||||||||||||||||||||||||


| Global instruction definition conventions:
| * DESTINATION arg is LAST

| Instruction set summary. Notation:
| ra, rb, rc: registers
|     CC: 16-bit signed constant
|     label: statement/location tag (becomes PC-relative offset)

| ADD(RA, RB, RC)          | RC <- <RA> + <RB>
| ADDC(RA, C, RC)         | RC <- <RA> + C
| AND(RA, RB, RC)         | RC <- <RA> & <RB>
| ANDC(RA, C, RC)         | RC <- <RA> & C
| MUL(RA, RB, RC)         | RC <- <RA> * <RB>
| MULC(RA, C, RC)         | RC <- <RA> * C
| DIV(RA, RB, RC)          | RC <- <RA> / <RB>
| DIVC(RA, C, RC)          | RC <- <RA> / C
| OR( RA, RB, RC)          | RC <- <RA> | <RB>
| ORC(RA, C, RC)          | RC <- <RA> | C
| SHL(RA, RB, RC)          | RC <- <RA> << <RB>
| SHLC(RA, C, RC)          | RC <- <RA> << C
| SHR(RA, RB, RC)          | RC <- <RA> >> <RB>
| SHRC(RA, C, RC)          | RC <- <RA> >> C
| SRA(RA, RB, RC)          | RC <- <RA> >> <RB>
| SRAC(RA, C, RC)          | RC <- <RA> >> C
| SUB(RA, RB, RC)          | RC <- <RA> - <RB>
| SUBC(RA, C, RC)          | RC <- <RA> - C
| XOR(RA, RB, RC)          | RC <- <RA> ^ <RB>
| XORC(RA, C, RC)          | RC <- <RA> ^ C

| CMPEQ(RA, RB, RC)        | RC <- <RA> == <RB>
| CMPEQC(RA, C, RC)        | RC <- <RA> == C
| CMPLE(RA, RB, RC)        | RC <- <RA> <= <RB>
| CMPLEC(RA, C, RC)        | RC <- <RA> <= C
| CMPLT(RA, RB, RC)        | RC <- <RA> < <RB>
| CMPLTC(RA, C, RC)        | RC <- <RA> < C

| BR(LABEL,RC)              | RC <- <PC>+4; PC <- LABEL (PC-relative addressing)
| BR(LABEL)                 | PC <- LABEL (PC-relative addressing)
| BEQ(RA, LABEL, RC)        | RC <- <PC>+4; IF <RA>==0 THEN PC <- LABEL
| BEQ(RA, LABEL)             | IF <RA>==0 THEN PC <- LABEL
| BF(RA, LABEL, RC)          | RC <- <PC>+4; IF <RA>==0 THEN PC <- LABEL
| BF(RA, LABEL)              | IF <RA>==0 THEN PC <- LABEL
| BNE(RA, LABEL, RC)         | RC <- <PC>+4; IF <RA>!=0 THEN PC <- LABEL
| BNE(RA, LABEL)             | IF <RA>!=0 THEN PC <- LABEL
| BT(RA, LABEL, RC)          | RC <- <PC>+4; IF <RA>!=0 THEN PC <- LABEL
```

BT(RA, LABEL)	IF <RA>!=0 THEN PC <- LABEL
JMP(RA, RC)	RC <- <PC>+4; PC <- <RA> & 0xFFFF
JMP(RB)	PC <- <RB> & 0xFFFF
LD(RA, CC, RC)	RC <- <<RA>+CC>
LD(CC, RC)	RC <- <CC>
ST(RC, CC, RA)	<RA>+CC <- <RC>
ST(RC, CC)	CC <- <RC>
LDR(CC, RC)	RC <- <CC> (PC-relative addressing)
MOVE(RA, RC)	RC <- <RA>
CMOVE(CC, RC)	RC <- CC
HALT()	STOPS SIMULATOR.
PUSH(RA)	(2) <SP> <- <RA>; SP <- <SP> - 4
POP(RA)	(2) RA <- <<SP>+4>; SP <- <SP> + 4
ALLOCATE(N)	Allocate N longwords from stack
DEALLOCATE(N)	Release N longwords
CALL(label)	Call a subr; save PC in lp.
CALL(label, n)	(2) Call subr at label with n args. Saves return adr in LP. Pops n longword args from stack.
RTN()	Returns to adr in <LP> (Subr return)
XRTN()	Returns to adr in <IP> (Intr return)
WORD(val)	Assemble val as a 16-bit datum
LONG(val)	Assemble val as a 32-bit datum
STORAGE(NWORDS)	Reserve NWORDS 32-bit words of DRAM
GETFRAME(F, RA)	RA <- <<BP>+F>
PUTFRAME(RA, F)	<BP>+F <- <RA>
HW	Makes a hardware call
Calling convention:	
PUSH(argn-1)	
...	
PUSH(arg0)	
CALL(subr, nargs)	
(return here with result in R0, args cleaned)	
Extra register conventions, for procedure linkage:	
LP = 28	Linkage register (holds return adr)
BP = 29	Frame pointer (points to base of frame)
Conventional stack frames look like:	
arg[N-1]	
...	
arg[0]	
<saved lp>	
<saved bp>	
<other saved regs>	
BP-><locals>	
...	
SP->(first unused location)	
Convention: define a symbol for each arg/local giving bp-relative offset.	

| Then use
| getframe(name, r) gets value at offset into register r.
| putframe(r, name) puts value from r into frame at offset name

		End of documentation. Following are the actual definitions...			

| Assemble words, little-endian:
.macro WORD(x) x%0x100 (x>>8)%0x100
.macro LONG(x) WORD(x) WORD(x >> 16) | little-endian for Maybe
.macro STORAGE(NWORDS) . = .+(4*NWORDS)| Reserve NWORDS words of RAM

| register designators
| this allows symbols like r0, etc to be used as
| operands in instructions. Note that there is no real difference
| in this assembler between register operands and small integers.

r0 = 0
r1 = 1
r2 = 2
r3 = 3
r4 = 4
r5 = 5
r6 = 6
r7 = 7
r8 = 8
r9 = 9
r10 = 10
r11 = 11
r12 = 12
r13 = 13
r14 = 14
r15 = 15
r16 = 16
r17 = 17
r18 = 18
r19 = 19
r20 = 20
r21 = 21
r22 = 22
r23 = 23
r24 = 24
r25 = 25
r26 = 26
r27 = 27
r28 = 28
r29 = 29
r30 = 30
r31 = 31

bp = 27 | frame pointer (points to base of frame)
lp = 28 | linkage register (holds return adr)
sp = 29 | stack pointer (points to 1st free locn)
xp = 30 | interrupt return pointer (lp for interrupts)

```

| understand upper case, too.
R0 = r0
R1 = r1
R2 = r2
R3 = r3
R4 = r4
R5 = r5
R6 = r6
R7 = r7
R8 = r8
R9 = r9
R10 = r10
R11 = r11
R12 = r12
R13 = r13
R14 = r14
R15 = r15
R16 = r16
R17 = r17
R18 = r18
R19 = r19
R20 = r20
R21 = r21
R22 = r22
R23 = r23
R24 = r24
R25 = r25
R26 = r26
R27 = r27
R28 = r28
R29 = r29
R30 = r30
R31 = r31
XP = xp
LP = lp
BP = bp
SP = sp

.macro betaop(OP,RA,RB,RC) {
    .align 4
    LONG((OP<<26)+((RC%0x20)<<21)+((RA%0x20)<<16)+((RB%0x20)<<11)) }

.macro betaopc(OP,RA,CC,RC) {
    .align 4
    LONG((OP<<26)+((RC%0x20)<<21)+((RA%0x20)<<16)+(CC%0x10000)) }

.macro ADD(RA, RB, RC)           betaop(0x20,RA,RB,RC)
.macro ADDC(RA, C, RC)          betaopc(0x30,RA,C,RC)

.macro NOP()                   ADD(R31, R31, R31)

.macro HW() {
    | NOP() | <- alternate comment between NOP and the real operation for Bsim tests
    betaop(0x01,0,0,R31)
    NOP()
    NOP()
}

```

.macro AND(RA, RB, RC)	betaop(0x28,RA,RB,RC)
.macro ANDC(RA, C, RC)	betaopc(0x38,RA,C,RC)
.macro MUL(RA, RB, RC)	betaop(0x22,RA,RB,RC)
.macro MULC(RA, C, RC)	betaopc(0x32,RA,C,RC)
.macro DIV(RA, RB, RC)	betaop(0x23,RA,RB,RC)
.macro DIVC(RA, C, RC)	betaopc(0x33,RA,C,RC)
.macro OR(RA, RB, RC)	betaop(0x29,RA,RB,RC)
.macro ORC(RA, C, RC)	betaopc(0x39,RA,C,RC)
.macro SHL(RA, RB, RC)	betaop(0x2C,RA,RB,RC)
.macro SHLC(RA, C, RC)	betaopc(0x3C,RA,C,RC)
.macro SHR(RA, RB, RC)	betaop(0x2D,RA,RB,RC)
.macro SHRC(RA, C, RC)	betaopc(0x3D,RA,C,RC)
.macro SRA(RA, RB, RC)	betaop(0x2E,RA,RB,RC)
.macro SRAC(RA, C, RC)	betaopc(0x3E,RA,C,RC)
.macro SUB(RA, RB, RC)	betaop(0x21,RA,RB,RC)
.macro SUBC(RA, C, RC)	betaopc(0x31,RA,C,RC)
.macro XOR(RA, RB, RC)	betaop(0x2A,RA,RB,RC)
.macro XORC(RA, C, RC)	betaopc(0x3A,RA,C,RC)
.macro CMPEQ(RA, RB, RC)	betaop(0x24,RA,RB,RC)
.macro CMPEQC(RA, C, RC)	betaopc(0x34,RA,C,RC)
.macro CMPLE(RA, RB, RC)	betaop(0x26,RA,RB,RC)
.macro CMPLEC(RA, C, RC)	betaopc(0x36,RA,C,RC)
.macro CMPLT(RA, RB, RC)	betaop(0x25,RA,RB,RC)
.macro CMPLTC(RA, C, RC)	betaopc(0x35,RA,C,RC)
.macro BETABR(OP,RA,RC,LABEL)	betaopc(OP,RA,((LABEL-.)>>2)-1, RC)
.macro BEQ(RA, LABEL, RC)	BETABR(0x1D,RA,RC,LABEL)
.macro BEQ(RA, LABEL)	BETABR(0x1D,RA,r31,LABEL)
.macro BF(RA, LABEL, RC)	BEQ(RA,LABEL,RC)
.macro BF(RA,LABEL)	BEQ(RA,LABEL)
.macro BNE(RA, LABEL, RC)	BETABR(0x1E,RA,RC,LABEL)
.macro BNE(RA, LABEL)	BETABR(0x1E,RA,r31,LABEL)
.macro BT(RA,LABEL,RC)	BNE(RA,LABEL,RC)
.macro BT(RA,LABEL)	BNE(RA,LABEL)
.macro BR(LABEL,RC)	BEQ(r31, LABEL, RC)
.macro BR(LABEL)	BR(LABEL, r31)
.macro JMP(RA, RC)	betaopc(0x1B,RA,0,RC)
.macro JMP(RA)	betaopc(0x1B,RA,0,r31)
.macro LD(RA, CC, RC)	betaopc(0x18,RA,CC,RC)
.macro LD(CC, RC)	betaopc(0x18,R31,CC,RC)
.macro ST(RC, CC, RA)	betaopc(0x19,RA,CC,RC)
.macro ST(RC, CC)	betaopc(0x19,R31,CC,RC)
.macro LDR(CC, RC)	BETABR(0x1F, R31, RC, CC)
.macro MOVE(RA, RC)	ADD(RA, R31, RC)
.macro CMOVE(CC, RC)	ADDC(R31, CC, RC)
.macro PUSH(RA)	ADDC(SP,4,SP) ST(RA,-4,SP)
.macro POP(RA)	LD(SP,-4,RA) ADDC(SP,-4,SP)
.macro CALL(label) BR(label, LP)	
.macro RTN()	JMP(LP)
.macro XRTN()	JMP(XP)

| Controversial Extras
| Calling convention:

```

| PUSH(argn-1)
| ...
| PUSH(arg0)
| CALL(subr, nargs)
| (return here with result in R0, args cleaned)

| Extra register conventions, for procedure linkage:
| LP = 28 | Linkage register (holds return adr)
| BP = 29 | Frame pointer (points to base of frame)

| Conventional stack frames look like:
| arg[N-1]
| ...
| arg[0]
| <saved lp>
| <saved bp>
| <other saved regs>
| BP-><locals>
| ...
| SP->(first unused location)

| Convention: define a symbol for each arg/local giving bp-relative offset.
| Then use
| getframe(name, r) gets value at offset into register r.
| putframe(r, name) puts value from r into frame at offset name

```

```

.macro GETFRAME(OFFSET, REG) LD(bp, OFFSET, REG)
.macro PUTFRAME(REG, OFFSET) ST(REG, OFFSET, bp)
.macro CALL(S,N) BR(S,lp) SUBC(sp, 4*N, sp)

.macro ALLOCATE(N) ADDC(sp, N*4, sp)
.macro DEALLOCATE(N) SUBC(sp, N*4, sp)

```

```

-----
| GPU control macros
-----

```

| Utility macros for controlling the GPU

```

.macro CMOVE32(CC, RC) {
    CMOVE((CC>>16), RC)
    SHLC(RC, 16, RC)
    ADDC(RC, (CC%0x10000), RC)
}

.macro NEW_SPRITE(ID, TYPE, LAYER, COLLIDABLE, ENEMY, X1, Y1) {
    PUSH(R1)
    PUSH(R2)
    PUSH(R3)

    CMOVE32((0x0<<27)+((ENEMY%0x2)<<19)+((COLLIDABLE%0x2)<<18)+((LAYER%0x4)<<1
6)+((ID%0x80)<<10)+(TYPE%0x800), R1)
    CMOVE32(X1, R2)
    CMOVE32(Y1, R3)
    HW()
    POP(R3)
    POP(R2)
}

```

```

    POP(R1)
}

| ID is taken from R0
.macro NEW_SPRITE_ALLOC_ID(TYPE, LAYER, COLLIDABLE, ENEMY, X1, Y1) {
    PUSH(R0)
    PUSH(R1)
    PUSH(R2)
    PUSH(R3)
    ANDC(R0, 0x3F, R0)
    SHLC(R0, 10, R0)

    CMOVE32((0x0<<27)+((ENEMY%0x2)<<19)+((COLLIDABLE%0x2)<<18)+((LAYER%0x4)<<1
6)+(TYPE%0x800), R1)
    ADD(R0, R1, R1)
    CMOVE32(X1, R2)
    CMOVE32(Y1, R3)
    HW()
    POP(R3)
    POP(R2)
    POP(R1)
    POP(R0)
}

.macro NEW_BLOB(ID, LAYER, ENEMY, X1, Y1, X2, Y2) {
    PUSH(R1)
    PUSH(R2)
    PUSH(R3)
    PUSH(R4)
    PUSH(R5)
    CMOVE32((0x1<<27)+((ENEMY%0x2)<<19)+((LAYER%0x4)<<16)+((ID%0x80)<<10), R1)
    CMOVE32(X1, R2)
    CMOVE32(Y1, R3)
    CMOVE32(X2, R4)
    CMOVE32(Y2, R5)
    HW()
    POP(R5)
    POP(R4)
    POP(R3)
    POP(R2)
    POP(R1)
}

| ID is taken from R0
.macro NEW_BLOB_ALLOC_ID(LAYER, ENEMY, X1, Y1, X2, Y2) {
    PUSH(R0)
    PUSH(R1)
    PUSH(R2)
    PUSH(R3)
    PUSH(R4)
    PUSH(R5)
    ANDC(R0, 0x3F, R0)
    SHLC(R0, 10, R0)
    CMOVE32((0x1<<27)+((ENEMY%0x2)<<19)+((LAYER%0x4)<<16), R1)
    ADD(R0, R1, R1)
    CMOVE32(X1, R2)
    CMOVE32(Y1, R3)
    CMOVE32(X2, R4)
    CMOVE32(Y2, R5)
}

```

```

HW()
POP(R5)
POP(R4)
POP(R3)
POP(R2)
POP(R1)
POP(R0)
}

.macro NEW_TILED_SPRITE(ID, TYPE, LAYER, COLLIDABLE, ENEMY, X1, Y1, X2, Y2) {
    PUSH(R1)
    PUSH(R2)
    PUSH(R3)
    PUSH(R4)
    PUSH(R5)

    CMOVE32((0x2<<27)+((ENEMY%0x2)<<19)+((COLLIDABLE%0x2)<<18)+((LAYER%0x4)<<1
6)+((ID%0x80)<<10)+(TYPE%0x800), R1)
        CMOVE32(X1, R2)
        CMOVE32(Y1, R3)
        CMOVE32(X2, R4)
        CMOVE32(Y2, R5)
    HW()
    POP(R5)
    POP(R4)
    POP(R3)
    POP(R2)
    POP(R1)
}

| ID is taken from R0
.macro NEW_TILED_SPRITE_ALLOC_ID(TYPE, LAYER, COLLIDABLE, ENEMY, X1, Y1, X2, Y2) {
    PUSH(R0)
    PUSH(R1)
    PUSH(R2)
    PUSH(R3)
    PUSH(R4)
    PUSH(R5)
    ANDC(R0, 0x3F, R0)
    SHLC(R0, 10, R0)

    CMOVE32((0x2<<27)+((ENEMY%0x2)<<19)+((COLLIDABLE%0x2)<<18)+((LAYER%0x4)<<1
6)+(TYPE%0x800), R1)
        ADD(R0, R1, R1)
        CMOVE32(X1, R2)
        CMOVE32(Y1, R3)
        CMOVE32(X2, R4)
        CMOVE32(Y2, R5)
    HW()
    POP(R5)
    POP(R4)
    POP(R3)
    POP(R2)
    POP(R1)
    POP(R0)
}

| X1, Y1, X2, Y2 in place
.macro NEW_TILED_SPRITE_REG_POS(ID, TYPE, LAYER, COLLIDABLE, ENEMY) {

```

```

PUSH(R1)

CMOVE32((0x2<<27)+((ENEMY%0x2)<<19)+((COLLIDABLE%0x2)<<18)+((LAYER%0x4)<<1
6)+((ID%0x80)<<10)+(TYPE%0x800), R1)
    HW()
    POP(R1)
}

.macro DESTROY_SPRITE(ID) {
    PUSH(R1)
    CMOVE32((0x3<<27)+((ID%0x80)<<10), R1)
    HW()
    POP(R1)
}

.macro SET_TYPE(ID, TYPE) {
    PUSH(R1)
    CMOVE32((0xA<<27)+((ID%0x80)<<10)+(TYPE%0x800), R1)
    HW()
    POP(R1)
}

| ID is taken from R0
.macro SET_TYPE_ALLOC_ID(TYPE) {
    PUSH(R0)
    PUSH(R1)
    ANDC(R0, 0x3F, R0)
    SHLC(R0, 10, R0)
    CMOVE32((0xA<<27)+((ID%0x80)<<10)+(TYPE%0x800), R1)
    ADD(R0, R1, R1)
    HW()
    POP(R1)
    POP(R0)
}

| R2, R3 must contain positions
.macro MOVE_SPRITE(ID) {
    PUSH(R1)
    CMOVE32((0x4<<27) + ((ID%0x80)<<10), R1)
    HW()
    POP(R1)
}

| ID is taken from R0
| R2, R3 must contain positions
.macro MOVE_SPRITE_ALLOC_ID() {
    PUSH(R0)
    PUSH(R1)
    ANDC(R0, 0x3F, R0)
    SHLC(R0, 10, R0)
    CMOVE32((0x4<<27), R1)
    ADD(R0, R1, R1)
    HW()
    POP(R1)
    POP(R0)
}

.macro SET_LCP(ID, LAYER, COLLIDABLE, ENEMY) {
    PUSH(R1)

```

```

CMOVE32((0x5<<27)+((ENEMY%0x2)<<19)+((COLLIDABLE%0x2)<<18)+((LAYER%0x4)<<1
6)+((ID%0x80)<<10), R1)
    HW()
    POP(R1)
}

| ID is taken from R0
| LAYER is taken from R2
| {COLLIDABLE,ENEMY} is taken from R3
.macro SET_LCP_ALLOC_ID() {
    PUSH(R0)
    PUSH(R1)
    PUSH(R2)
    PUSH(R3)
    ANDC(R0, 0x3F, R0)
    ANDC(R2, 0x3, R2)
    ANDC(R3, 0x3, R3)
    SHLC(R0, 10, R0)
    SHLC(R2, 16, R2)
    SHLC(R3, 18, R3)
    CMOVE32((0x5<<26), R1)
    ADD(R0, R1, R1)
    ADD(R2, R3, R3)
    ADD(R3, R1, R1)
    HW()
    POP(R3)
    POP(R2)
    POP(R1)
    POP(R0)
}
.macro SET_FILTER(ID, FILTER) {
    PUSH(R1)
    CMOVE32((0x6<<27)+((ID%0x80)<<10)+(FILTER%0x20), R1)
    HW()
    POP(R1)
}
| ID is taken from R0
.macro SET_FILTER_ALLOC_ID(FILTER) {
    PUSH(R0)
    PUSH(R1)
    ANDC(R0, 0x3F, R0)
    SHLC(R0, 10, R0)
    CMOVE32((0x6<<27)+(FILTER%0x20), R1)
    ADD(R0, R1, R1)
    HW()
    POP(R1)
    POP(R0)
}
.macro SET_MIRROR(ID, MIRROR) {
    PUSH(R1)
    CMOVE32((0x7<<27)+(MIRROR%0x4),R1)
    HW()
    POP(R1)
}

```

```

| ID is taken from R0
.macro SET_MIRROR_ALLOC_ID(MIRROR) {
    PUSH(R0)
    PUSH(R1)
    ANDC(R0, 0x3F, R0)
    SHLC(R0, 10, R0)
    CMOVE32((0x7<<27)+(MIRROR%0x4),R1)
    ADD(R0, R1, R1)
    HW()
    POP(R1)
    POP(R0)
}

.macro SET_CAMERA(X, Y) {
    PUSH(R1)
    PUSH(R2)
    PUSH(R3)
    CMOVE32((0x8<<27), R1)
    CMOVE32(X, R2)
    CMOVE32(Y, R3)
    HW()
    POP(R3)
    POP(R2)
    POP(R1)
}

| X, Y already stored on R2, R3
.macro SET_CAMERA_ALLOC() {
    PUSH(R1)
    CMOVE32((0x8<<27), R1)
    HW()
    POP(R1)
}

.macro SET_BACKGROUND(PIXEL) {
    PUSH(R1)
    CMOVE32((0x9<<27)+(PIXEL%0x100), R1)
    HW()
    POP(R1)
}

| PIXEL is taken from R0
.macro SET_BACKGROUND_ALLOC_PIXEL() {
    PUSH(R0)
    PUSH(R1)
    ANDC(R0, 0xFF, R0)
    CMOVE32((0x9<<27)+(PIXEL%0x100), R1)
    ADD(R0, R1, R1)
    HW()
    POP(R1)
    POP(R0)
}

```

|-----
Privileged mode instructions

| SVC calls; used for OS extensions

- | Note that, conventionally, this uses betaopc(0x01, 0, code, 0).
- | Unfortunately that conflicts with our conventions for the HW() call,
- | and as such Yield() would become nonsensical commands to the beta.
- | This bug was a royal pain to locate.

```
.macro SVC(code)           betaopc (0x03, 0, code, 0)
```

Trap and interrupt vectors		
VEC_RESET	= 0	Reset (powerup)
VEC_II	= 4	Illegal instruction (also SVC call)
VEC_CLK	= 8	Clock interrupt
VEC_ECOLLISION	= 12	HW interrupt
VEC_COLLISION	= 16	HW interrupt
VEC_UP_PRESS	= 20	User input interrupts
VEC_DOWN_PRESS	= 24	
VEC_LEFT_PRESS	= 28	
VEC_RIGHT_PRESS	= 32	
VEC_ENTER_PRESS	= 36	
VEC_B1_PRESS	= 40	
VEC_B2_PRESS	= 44	
VEC_B3_PRESS	= 48	
VEC_UP_RELEASE	= 52	
VEC_DOWN_RELEASE	= 56	
VEC_LEFT_RELEASE	= 60	
VEC_RIGHT_RELEASE	= 64	
VEC_ENTER_RELEASE	= 68	
VEC_B1_RELEASE	= 72	
VEC_B2_RELEASE	= 76	
VEC_B3_RELEASE	= 80	
HW-access memory		
ENEMY_STATE	= 84	
COLLISION_STATE	= 88	
constant for the supervisor bit in the PC		
PC_SUPERVISOR	= 0x80000000	the bit itself
PC_MASK	= 0x7fffffff	a mask for the rest of the PC

ram.uasm

Contains the kernel and user processes for the game logic itself.

```
|||||||||||||||||||||||||||||||||||||||||||||||||
||| Videogame OS demo, based on Simple OS for 6.004 Beta processor by Steve Ward(4/19/94)
||| 
||| This file contains a primitive but complete timesharing kernel
||| sufficient to run three processes, plus handlers for a small
||| selection of supervisor calls (SVCs) to perform OS services.
||| The latter include simple console I/O and semaphores.
||| 
||| All kernel code is executed with the Kernel-mode bit of the
||| program counter -- its high-order bit --- set. This causes
||| new interrupt requests to be deferred until the kernel returns
```

```

||| to user mode.

.include beta.uasm

||| Interrupt vectors:

. = VEC_RESET
    BR(I_Reset)      | on Reset (start-up)
. = VEC_II
    BR(I_IIOp)       | on Illegal Instruction (eg SVC)
. = VEC_CLK
    BR(I_Clk)        | on clock interrupt
. = VEC_ECOLLISION
    BR(I_Ecol)        | on HW interrupt
. = VEC_COLLISION
    BR(I_Col)
. = VEC_UP_PRESS
    BR(I_UP)
. = VEC_DOWN_PRESS
    BR(I_DP)
. = VEC_LEFT_PRESS
    BR(I_LP)
. = VEC_RIGHT_PRESS
    BR(I_RP)
. = VEC_ENTER_PRESS
    BR(I_EP)
. = VEC_B1_PRESS
    BR(I_B1P)
. = VEC_B2_PRESS
    BR(I_B2P)
. = VEC_B3_PRESS
    BR(I_B3P)
. = VEC_UP_RELEASE
    BR(I_UR)
. = VEC_DOWN_RELEASE
    BR(I_DR)
. = VEC_LEFT_RELEASE
    BR(I_LR)
. = VEC_RIGHT_RELEASE
    BR(I_RR)
. - VEC_ENTER_RELEASE
    BR(I_ER)
. = VEC_B1_RELEASE
    BR(I_B1R)
. = VEC_B2_RELEASE
    BR(I_B2R)
. = VEC_B3_RELEASE
    BR(I_B3R)
. = ENEMY_STATE      | Memory areas accessed by hardware
Enemy_State: LONG(0)
. = COLLISION_STATE
Collision_State: LONG(0)

```

||| The following macro is the first instruction to be entered for each
 ||| asynchronous I/O interrupt handler. It adjusts XP (the interrupted
 ||| PC) to account for the instruction skipped due to the pipeline bubble.
`.macro ENTER_INTERRUPT SUBC(XP,4,XP)`

```
||||||||||||||||||||||||||||||||||||||||||||||||||||||||||||||||||||
```

Kernel Interrupt support code
We use a slightly simpler (and less efficient) scheme here from
that in the text. On kernel entry, the ENTIRE state -- 31
registers -- of the interrupted program is saved in a designated
region of kernel memory ("UserMState", below). This entire state
is then restored on return to the interrupted program.

| Here's the SAVED STATE of the interrupted process, while we're
| processing an interrupt.

UserMState:

STORAGE(32) | R0-R31... (PC is in XP!)

| Here are macros to SAVE and RESTORE state -- 31 registers -- from
| the above storage.

| N.B. - The following macro assumes that R0 is a macro for
| the integer 0, R1 is a macro for the integer 1, etc.

.macro SS(R) ST(R, UserMState+(4*R))| (Auxiliary macro)

```
.macro SAVESTATE() {
```

```
SS(0) SS(1) SS(2) SS(3) SS(4) SS(5) SS(6) SS(7)
SS(8) SS(9) SS(10) SS(11) SS(12) SS(13) SS(14) SS(15)
SS(16) SS(17) SS(18) SS(19) SS(20) SS(21) SS(22) SS(23)
SS(24) SS(25) SS(26) SS(27) SS(28) SS(29) SS(30) }
```

| See comment for SS(R), above

.macro RS(R) LD(UserMState+(4*R), R)| (Auxiliary macro)

```
.macro RESTORESTATE() {
```

```
RS(0) RS(1) RS(2) RS(3) RS(4) RS(5) RS(6) RS(7)
RS(8) RS(9) RS(10) RS(11) RS(12) RS(13) RS(14) RS(15)
RS(16) RS(17) RS(18) RS(19) RS(20) RS(21) RS(22) RS(23)
RS(24) RS(25) RS(26) RS(27) RS(28) RS(29) RS(30) }
```

KStack: LONG(.+4)
STORAGE(256) | Pointer to ...
| ... the kernel stack.

Handler for Illegal Instructions
(including SVCs)

I IIIOp:

SAVESTATE() | Save the machine state.
LD(KStack, SP) | Install kernel stack pointer.

LD(XP, -4, r0)	Fetch the illegal instruction
SHRC(r0, 26, r0)	Extract the 6-bit OPCODE
SUBC(r0, 2, r0)	NEW: account for the fact that we modified the

definition of SVC

SHLC(r0, 2, r0)	Make it a WORD (4-byte) index
LD(r0, UUOTBl, r0)	Fetch UUOTBl[OPCODE]
JMP(r0)	and dispatch to the UUO handle

```
.macro UUO(ADR) LONG(ADR+PC_SUPERVISOR) | Auxiliary Macros  
.macro BAD()      UUO(UUOError)
```

UUOTbl:	BAD()	UUO(SVC_UUO)	BAD()	BAD()
	BAD()	BAD()	BAD()	BAD()
	BAD()	BAD()	BAD()	BAD()
	BAD()	BAD()	BAD()	BAD()
	BAD()	BAD()	BAD()	BAD()
	BAD()	BAD()	BAD()	BAD()
	BAD()	BAD()	BAD()	BAD()
	BAD()	BAD()	BAD()	BAD()

||| Here's the handler for truly unused opcodes (not SVCs):
 UUOError: BR(UUOError) | Crash system

||| Here's the common exit sequence from Kernel interrupt handlers:
 ||| Restore registers, and jump back to the interrupted user-mode
 ||| program.

I_Rtn:	RESTORESTATE()	
kexit:	JMP(XP)	Good place for debugging breakpoint!

||| Alternate return from interrupt handler which BACKS UP PC,
 ||| and calls the scheduler prior to returning. This causes
 ||| the trapped SVC to be re-executed when the process is
 ||| eventually rescheduled...

I_Wait:	LD(UserMState+(4*30), r0)	Grab XP from saved MState,
	SUBC(r0, 4, r0)	back it up to point to
	ST(r0, UserMState+(4*30))	SVC instruction
	CALL(Scheduler)	Switch current process,
	BR(I_Rtn)	and return to (some) user.

||| Sub-handler for SVCs, called from I_IIOp on SVC opcode:

SVC_UUO:		
	LD(XP, -4, r0)	The faulting instruction.
	ANDC(r0, 0x7, r0)	Pick out low bits,
	SHLC(r0, 2, r0)	make a word index,
	LD(r0, SVCTbl, r0)	and fetch the table entry.
	JMP(r0)	

SVCTbl:	UUO(HaltH)	SVC(0): User-mode HALT instruction
	UUO(WaitH)	SVC(1): Wait(S) ,,, S in R3
	UUO(SignalH)	SVC(2): Signal(S), S in R3
	UUO(YieldH)	SVC(3): Yield()
	UUO(GetECollision)	SVC(4): Get enemy collision info, when it changes, into R0
	UUO(GetCollision)	SVC(5): Get collision info, when it changes, into R0
	BAD()	SVC(6): unused
	BAD()	SVC(7): unused

||||||||||||||||||||||||||||||||||||||||||||||||||||||||
 ||| Enemy collision and collision handling
 |||
 ||| Interrupts set flags informing there is a new value, which was
 ||| stored by hardware. Functions block until flag is clean, then
 ||| clean the flag and return the new requested value.
 |||
 |||

| Enemy_State defined on fixed position

```

Enemy_Flag: LONG(0)
Collision_Flag: LONG(0)

GetECollision:           | return new enemy collision info in r0
    LD(Enemy_Flag, r0)
    BEQ(r0, I_Wait)      | If there is no new value, wait
| new enemy collision, return it
    LD(Enemy_State, r0)   | Fetch value to return
    ST(r31, Enemy_Flag)  | clear flag, value is not new anymore
    BR(I_Rtn)            | and return to user

GetCollision:           | return new collision info in r0 when available
    LD(Collision_Flag, r0)
    BEQ(r0, I_Wait)      | If there is no new value, wait
| new collision info, return it
    LD(Collision_State, r0) | Fetch value to return
    ST(r31,Collision_Flag) | clear flag, value is not new anymore
    BR(I_Rtn)            | and return to user

I_Ecol: ENTER_INTERRUPT() | adjust PC
    ST(r0, UserMState)    | save R0
    CMOVE(1, r0)
    ST(r1, Enemy_Flag)    | set flag
    LD(UserMState, r0)    | restore R0
    BR(I_Rtn)            | and return to user

I_Col: ENTER_INTERRUPT() | adjust PC
    ST(r0, UserMState)    | save R0
    CMOVE(1, r0)
    ST(r1, Collision_Flag) | set flag
    LD(UserMState, r0)    | restore R0
    BR(I_Rtn)            | and return to user

```

```

||||||| User input handling
|||||
|||| Whenever there is a key change, save it to Button_Flags.
|||||||

```

```

| Flags positions:
| UP: 0
| DOWN: 1
| LEFT: 2
| RIGHT: 3
| ENTER: 4
| B1: 5
| B2: 6
| B3: 7
Button_Flags: LONG(0)

| Key press interrupts

```

```

I_UP: ENTER_INTERRUPT()          | Adjust PC
    SET_BACKGROUND(0b11100000)
    ST(r0, UserMState)          | Save R0
    LD(Button_Flags, r0)        | load flags

```

ORC(r0, 0x1, r0)	set position 0 to 1
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
I_DP: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b11100000)	
ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ORC(r0, 0x2, r0)	set position 1 to 1
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
I_LP: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b11100000)	
ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ORC(r0, 0x4, r0)	set position 2 to 1
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
I_RP: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b11100000)	
ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ORC(r0, 0x8, r0)	set position 3 to 1
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
I_EP: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b11100000)	
ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ORC(r0, 0x10, r0)	set position 4 to 1
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
I_B1P: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b11100000)	
ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ORC(r0, 0x20, r0)	set position 5 to 1
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
I_B2P: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b11100000)	
ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ORC(r0, 0x40, r0)	set position 6 to 1
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user

I_B3P: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b11100000)	
ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ORC(r0, 0x80, r0)	set position 7 to 1
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
 Key release interrupts	
I_UR: ENTER_INTERRUPT()	Adjust PC
ST(r0, UserMState)	Save R0
SET_BACKGROUND(0b00011000)	
LD(Button_Flags, r0)	load flags
ANDC(r0, 0xFFFFE, r0)	set position 0 to 0
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
I_DR: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b00011000)	
ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ANDC(r0, 0xFFFFD, r0)	set position 1 to 0
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
I_LR: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b00011000)	
ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ANDC(r0, 0xFFFFB, r0)	set position 2 to 0
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
I_RR: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b00011000)	
ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ANDC(r0, 0xFFFF7, r0)	set position 3 to 0
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
I_ER: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b00011000)	
ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ANDC(r0, 0xFFEF, r0)	set position 4 to 0
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
I_B1R: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b00011000)	

ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ANDC(r0, 0xFFDF, r0)	set position 5 to 0
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
I_B2R: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b00011000)	
ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ANDC(r0, 0xFFBF, r0)	set position 6 to 0
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user
I_B3R: ENTER_INTERRUPT()	Adjust PC
SET_BACKGROUND(0b00011000)	
ST(r0, UserMState)	Save R0
LD(Button_Flags, r0)	load flags
ANDC(r0, 0xFF7F, r0)	set position 7 to 0
ST(r0, Button_Flags)	store flags
LD(UserMState, r0)	restore r0
BR(I_Rtn)	return to user

|||||
 ||| Timesharing: N-process round-robin scheduler
 |||||

||| ProcTbl contains a 31-word data structure for each process,
 ||| including R0-R30. R31, which always contains 0, is omitted.
 ||| The XP (R30) value stored for each process is the PC,
 ||| and points to the next instruction to be executed.

||| The kernel variable CurProc always points to the ProcTbl entry
 ||| corresponding to the "swapped in" process.

ProcTbl:

STORAGE(29)	Process 0: R0-R28
LONG(P0Stack)	Process 0: SP
LONG(P0Start)	Process 0: XP (= PC)
STORAGE(29)	Process 1: R0-R28
LONG(P1Stack)	Process 1: SP
LONG(P1Start)	Process 1: XP (= PC)

CurProc: LONG(ProcTbl)

||| Schedule a new process.
 ||| Swaps current process out of UserMState, swaps in a new one.

Scheduler:

PUSH(LP)	
CMOVE(UserMState, r0)	
LD(CurProc, r1)	
CALL(CopyMState)	Copy UserMState -> CurProc
LD(CurProc, r0)	

	ADD(r0, 4*31, r0)	Increment to next process..
	CMPLTC(r0,CurProc, r1)	End of ProcTbl?
	BT(r1, Sched1)	Nope, its OK.
	CMOVE(ProcTbl, r0)	yup, back to Process 0.
Sched1:	ST(r0, CurProc)	Here's the new process;
	ADD(r31, UserMState, r1)	Swap new process in.
	CALL(CopyMState)	
	LD(Tics, r0)	Reset TicsLeft counter
	ST(r0, TicsLeft)	to Tics.
	POP(LP)	
	JMP(LP)	and return to caller.
Copy a 31-word MState structure from the address in <r0> to that in <r1>		
Trashes r2, leaves r0-r1 unchanged.		
.macro CM(N) LD(r0, N*4, r2) ST(r2, N*4, r1) Auxiliary macro		
CopyMState:		
	CM(0) CM(1) CM(2) CM(3) CM(4) CM(5) CM(6) CM(7)	
	CM(8) CM(9) CM(10) CM(11) CM(12) CM(13) CM(14) CM(15)	
	CM(16) CM(17) CM(18) CM(19) CM(20) CM(21) CM(22) CM(23)	
	CM(24) CM(25) CM(26) CM(27) CM(28) CM(29) CM(30)	
	JMP(LP)	

||||||
||| Clock interrupt handler: Invoke the scheduler.
||||||

||| Here's the deal:
 ||| Each compute-bound process gets a quantum consisting of TICS clock
 ||| interrupts, where TICS is the number stored in the variable Tics
 ||| below. To avoid overhead, we do a full state save only when the
 ||| clock interrupt will cause a process swap, using the TicsLeft
 ||| variable as a counter.
 ||| We do a LIMITED state save (r0 only) in order to free up a register,
 ||| then count down TicsLeft stored below. When it becomes negative,
 ||| we do a FULL state save and call the scheduler; otherwise we just
 ||| return, having burned only a few clock cycles on the interrupt.
 ||| RECALL that the call to Scheduler sets TicsLeft to Tics, giving
 ||| the newly-swapped-in process a full quantum.

Tics:	LONG(2)	Number of clock interrupts/quantum.
TicsLeft:	LONG(0)	Number of tics left in this quantum
I_Clk:	ENTER_INTERRUPT() ST(r0, UserMState) LD(TicsLeft, r0) SUBC(r0,1,r0) ST(r0, TicsLeft) CMPLTC(r0, 0, r0) BT(r0, DoSwap) LD(UserMState, r0) JMP(XP)	Adjust the PC! Save R0 ONLY, for now. Count down TicsLeft Now there's one left. If new value is negative, then swap processes. Else restore r0, and return to same user.
DoSwap:	LD(UserMState, r0) SAVESTATE() LD(KStack, SP) CALL(Scheduler) BR(I_Rtn)	Restore r0, so we can do a FULL State save. Install kernel stack pointer. Swap it out! and return to next process.

```
|||||||  
||| yield() SVC: voluntarily give up rest of time quantum.  
|||||||
```

YieldH:

CALL(Scheduler)	Schedule next process, and
BR(I_Rtn)	and return to user.

```
|||||||  
||| Here on start-up (reset): Begin executing process 0.  
|||||||
```

I_Reset:

CMOVE(P0Stack, SP)
CMOVE(P0Start, XP)
ST(R31, Button_Flags)
JMP(XP)

```
|||||||  
||| SVC Sub-handler for user-mode HALTs  
|||||||
```

HaltH: BR(I_Wait) | SVC(0): User-mode HALT SVC

```
|||||||  
||| Kernel support for User-mode Semaphores  
|||||||
```

||| User-mode access: macrodefinitions. Semaphore adr passed in r3,
||| which is saved & restored appropriately by macros:
||| NB: Wait() and Signal() SVCs each pass the address of a semaphore
||| in R3. Since the Illegal Opcode handler code doesn't change any
||| registers except R0, the R3 semaphore address is still intact
||| when we enter these handlers:

||| Kernel handler: wait(s):
||| ADDRESS of semaphore s in r3.

WaitH: LD(r3,0,r0) | Fetch semaphore value.
 BEQ(r0,I_Wait) | If zero, block..

 SUBC(r0,1,r0) | else, decrement and return.
 ST(r0,0,r3) | Store back into semaphore
 BR(I_Rtn) | and return to user.

||| Kernel handler: signal(s):
||| ADDRESS of semaphore s in r3.

SignalH: LD(r3,0,r0) | Fetch semaphore value.
 ADDC(r0,1,r0) | increment it,
 ST(r0,0,r3) | Store new semaphore value.
 BR(I_Rtn) | and return to user.

```

|||| User-mode processes
||||

.macro Halt()    SVC(0)      | Stop a process
.macro Yield()   SVC(3)      | Give up remaining quantum
.macro Enemy()   SVC(4)      | Wait until enemy collision changes, get info on R0
.macro Collision() SVC(5)   | Wait until collision changes, get info on R1

||| Semaphore macros.
||| Wait(S) waits on semaphore S; Signal(S) signals on S.
||| Both preserve all registers, by pushing & popping R3.

.macro Wait(S) {
    PUSH(r3)          | Save old <r3>,
    LDR(S,r3)         | put semaphore address into r3
    SVC(2)            | Wait on semaphore whose adr is in R3
    POP(r3) }         | and restore former <r3>

.macro Signal(S) {
    PUSH(r3)          | Save old <r3>,
    LDR(S,r3)         | put semaphore address into r3
    SVC(3)            | Signal on semaphore whose adr is in R3
    POP(r3) }         | and restore former <r3>

||| Allocate a semaphore: used like
|||   name: semaphore(size)
.macro semaphore(N) {
    LONG(.+4)          | Allocate a semaphore, and build a ptr
    LONG(N) }           | Pointer to semaphore
                           | Semaphore itself, init value N.

| Sprite types:
| 0-9: digits
| 10: :
| 11-15: hearts 0/4-4/4
| 16: bm 1
| 17: bm 2
| 18: bm casting
| 19: bm hurt
| 20: bm dead
| 21: box
| 22: brick
| 23: red rock
| 24: fire 1
| 25: fire 2
| 26: hadouken start
| 27: hadouken loop
| 28: arrow
| 29: archer
| 30: archer firing
| 31: paladin 1
| 32: paladin 2

|||| Process zero: setup and clock
|||
||| Create the level, initialize the variables, use timer

```

||||||||||||||||||||||||||||||||||||||||

```
P0Start: SET_CAMERA(0, 5000)
    CMOVE(0, R0)
    ST(R0, CameraX)
        CMOVE(5000, R1)
    ST(R1, CameraY)
    SET_BACKGROUND(0b11111000)
    NEW_SPRITE(0, 16, 2, 1, 0, 100, 5214)
    SET_MIRROR(0, 1)
    CMOVE(100, R0)
    ST(R0, PlayerX)
    CMOVE(5214, R0)
    ST(R0, PlayerY)
    NEW_TILED_SPRITE(1, 23, 2, 1, 0, 0, 5240, 5000, 10000)
    NEW_TILED_SPRITE(2, 22, 2, 1, 0, 300, 5180, 364, 5196)
    CMOVE(0, R0)
    BR(P0Cycle)
```

CycleSize: LONG(0xFFFF2C8)

```
P0Cycle: Yield()
    ADDC(R0, 1, R0)
    LD(CycleSize, R1)
    CMPEQC(R0, R1, R1)
    BT(R1, P0Cycle)
    CALL(UpdatePlayer)
    CMOVE(0, R0)
    BR(P0Cycle)
```

UpdatePlayer:
 LD(Button_Flags, R9)

```
    | Up/down
    ANDC(R9, 0x1, R1)
    ANDC(R9, 0x2, R2)

    BT(R1, B_Up)
    BT(R2, B_Down)
    BR(B_VZero)
```

B_Up:
 LD(PlayerUp, R3)
 BT(R3, B_VZero)
 CMOVE(1, R3)
 ST(R3, PlayerUp)
 CMOVE(10, R4)
 ST(R4, PlayerV)
 BR(B_VDone)

B_Down:
 LD(PlayerUp, R3)
 BT(R3, B_VZero)
 CALL(MakeHurt)
 BR(B_VDone)

B_VZero:
 CALL(MakeNotHurt)
 BR(B_VDone)

MakeHurt:
 CMOVE(3, R0)
 ST(R0, PlayerStatus)
 SET_TYPE(0, 19)
 RTN()

MakeNotHurt:
 LD(PlayerStatus, R1)
 CMPEQC(R1, 3, R0)
 BT(R0, MakeZero)
 RTN()

MakeWalk:
 LD(PlayerStatus, R1)
 CMPEQC(R1, 0, R0)
 BT(R0, MakeOne)
 CMPEQC(R1, 1, R0)
 BT(R0, MakeZero)
 RTN()

MakeOne:
 CMOVE(1, R1)
 ST(R1, PlayerStatus)
 SET_TYPE(0, 17)
 RTN()

MakeZero:
 ST(R31, PlayerStatus)
 SET_TYPE(0, 16)
 RTN()

MakeCasting:
 CMOVE(2, R1)
 ST(R1, PlayerStatus)
 SET_TYPE(0, 18)
 RTN()

B_VDone:
 ANDC(R9, 0x4, R3)
 ANDC(R9, 0x8, R4)
 BT(R3, B_Left)
 BT(R4, B_Right)
 BR(B_HDone)

B_Left:
 SET_MIRROR(0, 0)
 ST(R31, PlayerMirror)
 CALL(MakeWalk)
 LD(PlayerX, R0)
 LD(CameraX, R2)
 ADDC(R2, 5, R2)
 CMPLEC(R0, R2, R1)
 BT(R1, B_HDone)
 CALL(MoveLeft)
 BR(B_HDone)

B_Right:
 SET_MIRROR(0, 1)

```

CMOVE(1, R0)
ST(R0, PlayerMirror)
CALL(MakeWalk)
LD(PlayerX, R0)
LD(CameraX, R2)
ADD(CR2, 449, R2)
CMPLEC(R0, R2, R1)
BF(R1, B_HDone)
CALL(MoveRight)
BR(B_HDone)

```

MoveLeft:

```

LD(PlayerX, R0)
SUBC(R0, 1, R0)
ST(R0, PlayerX)
LD(PlayerX, R2)
LD(PlayerY, R3)
| MOVE_SPRITE(0)
RTN()

```

MoveRight:

```

LD(PlayerX, R0)
ADD(CR0, 1, R0)
ST(R0, PlayerX)
LD(PlayerX, R2)
LD(PlayerY, R3)
| MOVE_SPRITE(0)
RTN()

```

B_HDone:

```

ANDC(R9, 0x10, R5)
BF(R5, B_CastingDone)

```

B_Casting:

```

CALL(MakeCasting)

```

B_CastingDone:

```

BR(P0Cycle)

```

P0Stack: STORAGE(256)

```

||||||| Variables
|||||||

```

CameraX: LONG(0)
 CameraY: LONG(0)

PlayerX:	LONG(0)
PlayerY:	LONG(0)
PlayerUp:	LONG(0) 0 = floor, 1 = up, 2 = down
PlayerV:	LONG(0) vertical speed
PlayerStatus:	LONG(0) 0 = step1, 1 = step2, 2 = casting, 3 = hurt/down, 4 = dead
PlayerMirror:	LONG(1) 1 = right, 0 = left
Gravity:	LONG(0xFFFF2C8) how many cycles for each iteration

```

|||||||

```

||| Process one: gravity

P1Start: CMOVE(0, R0)

P1Cycle: Yield()
 ADDC(R0, 1, R0)
 LD(Gravity, R1)
 CMPEQC(R0, R1, R1)
 BT(R1, GStart)

GStart: ADDC(R0, 1, R0)
 LD(PlayerUp, R6)
 BF(R6, GFloor)
 CMPEQC(R6, 1, R0)
 BT(R0, GUp)
 BR(GDown)

GFloor: LD(Collision_Flag, R0)
 ANDC(R0, 1, R0)
 BT(R0, GDone)
 CMOVE(2, R0)
 ST(R0, PlayerUp)
 ST(R31, PlayerV)
 BR(GDone)

GUp: LD(PlayerV, R6)
 BF(R6, GTurn)
 SUBC(R6, 1, R6)
 ST(R6, PlayerV)
 LD(PlayerY, R2)
 SUB(R2, R6, R2)
 ST(R2, PlayerY)
 LD(PlayerX, R2)
 LD(PlayerY, R3)
 | MOVE_SPRITE(0)
 BR(GDone)

GTurn: CMOVE(2, R0)
 ST(R0, PlayerUp)
 BR(GDone)

GDown: LD(PlayerY, R0)
 CMPLEC(R0, 5240, R1)
 BF(R1, GCollided)
 CMPLEC(R0, 5180, R1)
 BT(R1, GNotCollided)
 LD(PlayerX, R1)
 CMPLEC(R1, 281, R2)
 BT(R2, GNotCollided)
 CMPLEC(R1, 364, R2)
 BF(R2, GNotCollided)
 BR(GCollided)

GNotCollided:
 LD(PlayerV, R6)
 ADDC(R6, 1, R6)
 ST(R6, PlayerV)
 LD(PlayerY, R2)

```
ADD(R2, R6, R2)
ST(R2, PlayerY)
LD(PlayerX, R2)
LD(PlayerY, R3)
| MOVE_SPRITE(0)
BR(GDone)
```

GCollided:
ST(R31, PlayerUp)

GDone: BR(GStart)

P1Stack: STORAGE(256)

Appendix C: Other scripts

ImageConverter.java

Used to convert bulks of images into the data part of .coe files.

```
import java.awt.image.*;
import java.awt.*;
import javax.imageio.ImageIO;
import java.io.*;

/**
 * Small java utility for converting any number of image files into a fragment
 * of .cue format
 */
public class ImageConverter {

    /** Main method (starts execution) */
    public static void main(String[] args) {
        try {
            Image img = null;
            for (String x : args) {
                img = ImageIO.read(new File(x));
                handlepixels(img, 0, 0, img.getWidth(null), img.getHeight(null));
            }
        } catch (Exception e) {
            e.printStackTrace();
        }
    }

    /** Transforms 8 bits of color into 2 */
    public static String convert2(int info) {
        double w = 255/6;
        if (info < w) return "00";
        if (info < 3*w) return "01";
        if (info < 5*w) return "10";
        return "11";
    }

    /** Transforms 8 bits of color into 3 */
    public static String convert3(int info) {
        double w = 255/14;
        if (info < w) return "000";
        if (info < 3*w) return "001";
        if (info < 5*w) return "010";
        if (info < 7*w) return "011";
        if (info < 9*w) return "100";
        if (info < 11*w) return "101";
        if (info < 13*w) return "110";
        return "111";
    }

    /** Prints info about a single pixel */
    public static void handlesinglepixel(int x, int y, int pixel) {
        int alpha = (pixel >> 24) & 0xff;
        int red   = (pixel >> 16) & 0xff;
        int green = (pixel >> 8) & 0xff;
        int blue  = (pixel       ) & 0xff;
        System.out.println(convert3(red) + convert2(green) + convert3(blue)+",");
    }
}
```

```

}

/** Prints info about all pixels, then pads it with zeros */
public static void handlepixels(Image img, int x, int y, int w, int h) {
    int[] pixels = new int[w * h];
    PixelGrabber pg = new PixelGrabber(img, x, y, w, h, pixels, 0, w);
    try {
        pg.grabPixels();
    } catch (InterruptedException e) {
        System.err.println("interrupted waiting for pixels!");
        return;
    }
    if ((pg.getStatus() & ImageObserver.ABORT) != 0) {
        System.err.println("image fetch aborted or errored");
        return;
    }
    for (int j = 0; j < h; j++) {
        for (int i = 0; i < w; i++) {
            handlesinglepixel(x+i, y+j, pixels[j * w + i]);
        }
    }
}
}

```

betamem.py

Used to quickly build small BRAMs .v files based on coe files (as opposed to built-in utility on Xilinx, which is fairly slow). Code provided by Chris Terman.

```

#!/usr/bin/env python
import sys,os,os.path,traceback

# get name of code/module
if (len(sys.argv) != 2):
    print "Usage: betamem <modulename>"
    sys.exit(0)

mname = sys.argv[1]

# read in memory contents
coename = mname + ".coe"
if not os.path.exists(coename):
    print "Oops: can't find %s" % coename
    sys.exit(0)
try:
    f = open(coename)
    contents = f.read() # read in entire file
    f.close()
except Exception,e:
    print "Oops:",e
    sys.exit(0)

# make a list, one entry per location. Skip past
# any coe header lines.
contents = contents.replace(',', '').split('\n')

# convert each hex string to an integer
locations = []
for line in contents:

```

```

if len(line) == 0: continue
elif line[0] == 'm': continue
try:
    line = line.replace(';', '')
    locations.append(int(line,16))
except Exception,e:
    print "Oops: error reading location",(len(locations)+1),": ",e
    sys.exit(0)
nlocs = len(locations)

# helper function returns binary string with WIDTH
# digits from BITOFFSET within location LOCN
def bits(width,bitoffset,locn):
    if locn >= nlocs: v = 0
    else: v = locations[locn]
    v >>= bitoffset;
    result = []
    for i in xrange(width):
        if v % 2 == 0: result.append('0')
        else: result.append('1')
        v >>= 1
    result.reverse()
    return ''.join(result)

# see what BRAM organization to use
if (nlocs <= 512):
    nmems = 1           # use a single 512 x 36 BRAM
    bram = "RAMB16_S36"
    naddr = 9
    width = 32
    pwidth = 4
elif (nlocs <= 1024):
    nmems = 2           # use two 1024 x 16 BRAMs
    bram = "RAMB16_S18"
    naddr = 10
    width = 16
    pwidth = 2
elif (nlocs <= 2048):
    nmems = 4           # use four 2048 x 8 BRAMs
    bram = "RAMB16_S9"
    naddr = 11
    width = 8
    pwidth = 1
elif (nlocs <= 4096):
    nmems = 8           # use eight 4096 x 4 BRAMs
    bram = "RAMB16_S4"
    naddr = 12
    width = 4
    pwidth = 0
elif (nlocs <= 8192):
    nmems = 16          # use sixteen 8192 x 2 BRAMs
    bram = "RAMB16_S2"
    naddr = 13
    width = 2
    pwidth = 0
elif (nlocs <= 16384):
    nmems = 32          # use thirty-two 16384 x 1 BRAMs
    bram = "RAMB16_S1"
    naddr = 14
    width = 1
    pwidth = 0
else:
    print "Oops: %d is too big, can only support up to 16k locations" % nlocs

```

```

    sys.exit(0)

# ready to create appropriate Verilog module
try:
    vname = mname + ".v"
    v = open(vname,'w')

    # output standard module prologue
    v.write("// single-port read/write memory initialized with %s code\n"
module %s(addr,clk,din,dout,we);
    input [13:0] addr;      // up to 16K locations
    input clk;             // memory has internal address regs
    input [31:0] din;      // appears after rising clock edge
    output [31:0] dout;    // written at rising clock edge
    input we;              // enables write port

    // we're using %d out of %d locations
    """ % (mname,mname,nlocs,1 << naddr))

    # output appropriate number of BRAM instances
    for i in xrange(nmems):
        lo = i * width
        hi = lo + width - 1
        if pwidth > 0:
            parity = ".DIP(%d'h0)," % pwidth
        else:
            parity = ""
        v.write(" %s\n"
m%d(.CLK(clk),.ADDR(addr[%d:0]),.DI(din[%d:%d]),%s.DO(dout[%d:%d]),.WE(we),.EN(1'
b1),.SSR(1'b0));\n" % (bram,i,naddr-1,hi,lo,parity,hi,lo))
        # output defparams to initialize this BRAM block
        nwords = 256/width
        for init in xrange(64):
            v.write(" defparam m%d.INIT_%02X = 256'b" % (i,init))
            start = init * nwords
            first = True
            for locn in xrange(start+nwords,start,-1):
                if first: first = False
                else: v.write('_')
                v.write(bits(width,lo,locn-1))
            v.write(';\n')

    v.write("\nendmodule")
    v.close()
except Exception,e:
    print "Oops:",e
    sys.exit(0)

# finished!

```

Appendix D: ROM Sprites

ID	Sprite	ID	Sprite
0	0	1	1
2	2	3	3
4	4	5	5
6	6	7	7
8	8	9	9
10	:	11	♥
12	♥	13	♥
14	♥	15	♥
16		17	
18		19	
20		21	
22		23	
24		25	
26		27	
28		29	
30		31	
32			